



Exemples de stimulateurs tactiles basés sur le confinement d'ondes

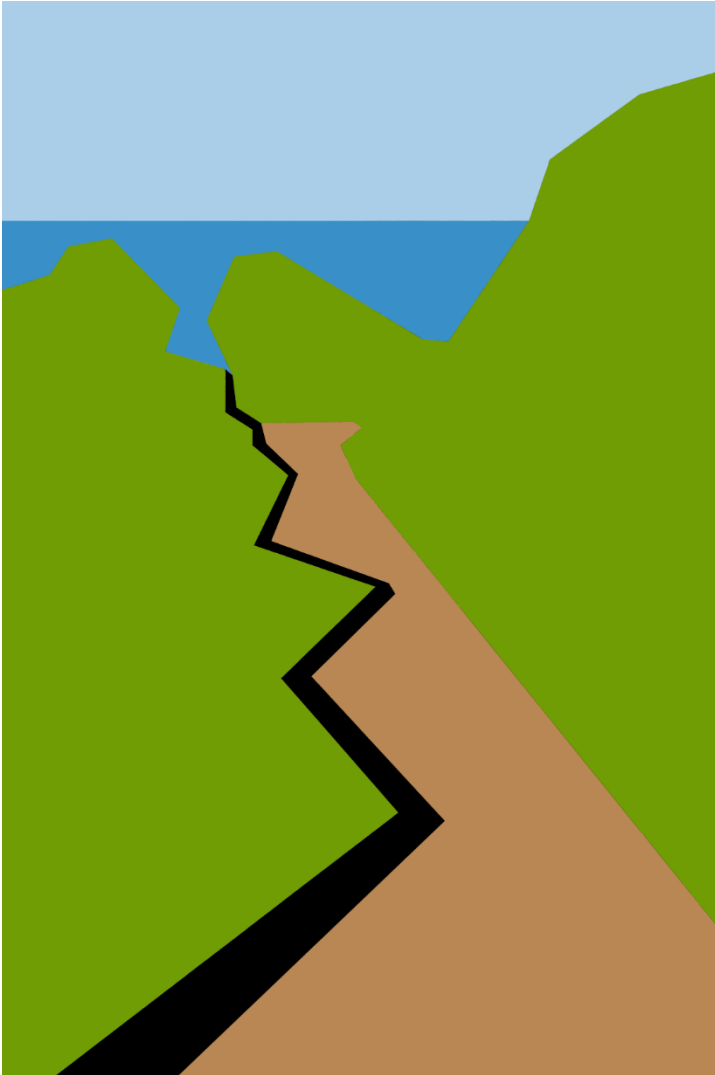
Ayoub Ben Dhiab

6 avril 2021

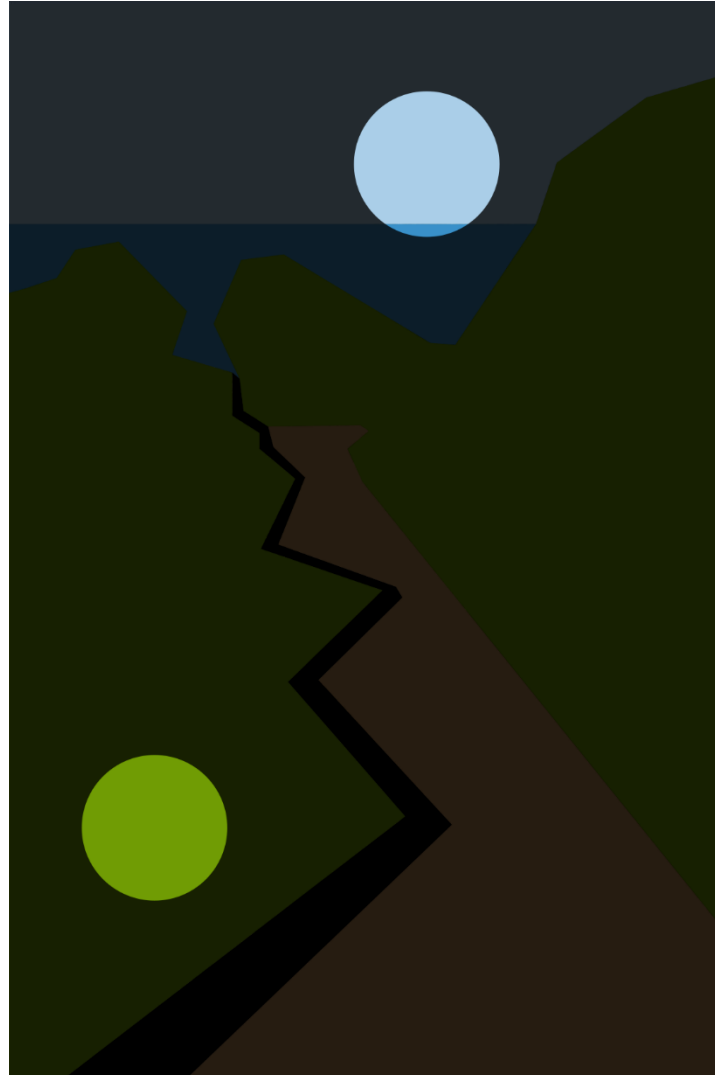
DE LA RECHERCHE À L'INDUSTRIE



Image Vibratoire



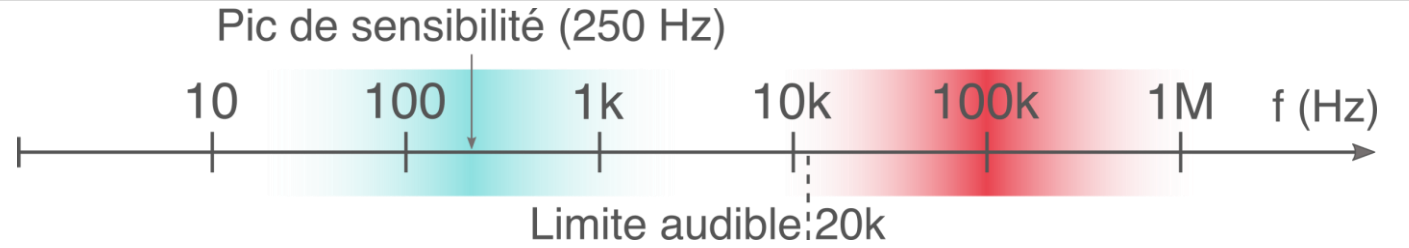
Vue Tactile



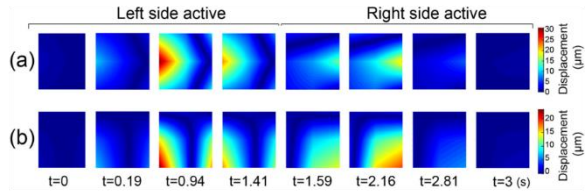
Répartition énergie



Approches par Contrôle

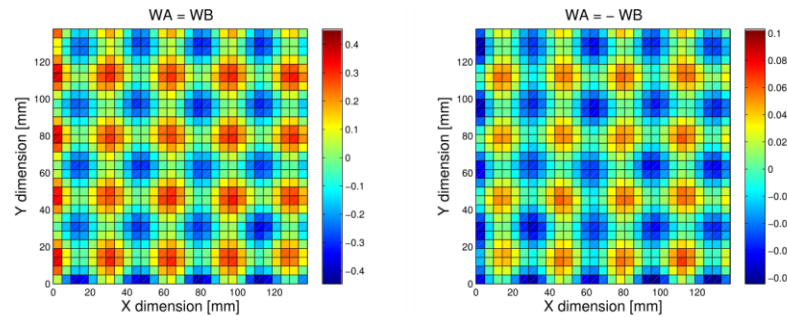


Optimisation fréquence/amplitude



Evolution of vibration maps for vibrotactile flow under the hand
[Emgin & al. 2019]

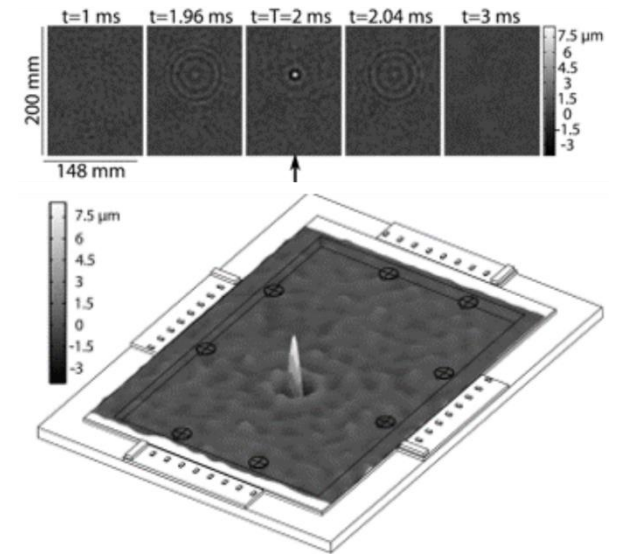
Superposition modale



Plate's deformation for several combinations modes

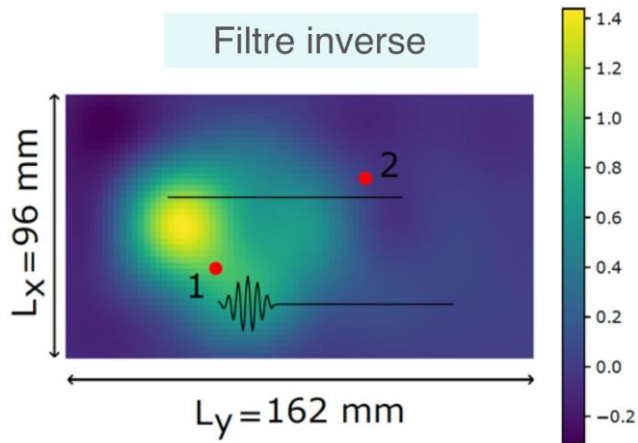
[Ghenna & al. 2016]

Retournement temporel

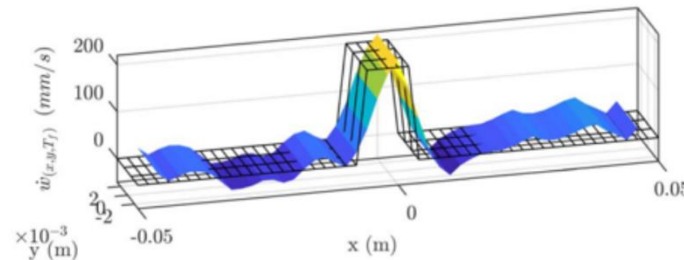


[Hudin & al. 2015]

Filtre inverse

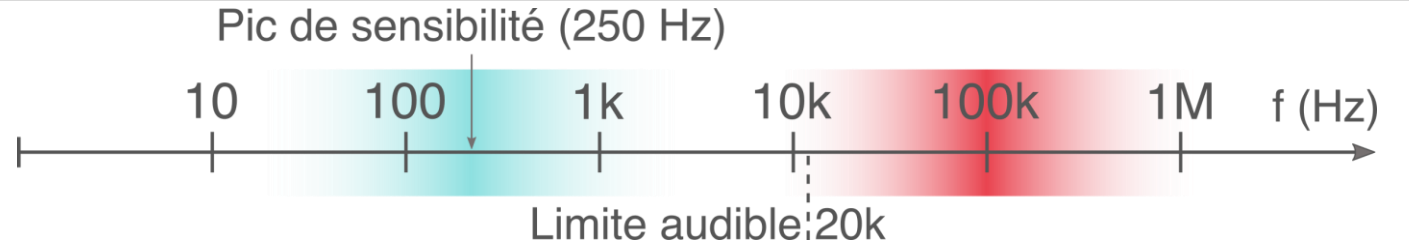


[Pantera & al. 2019]

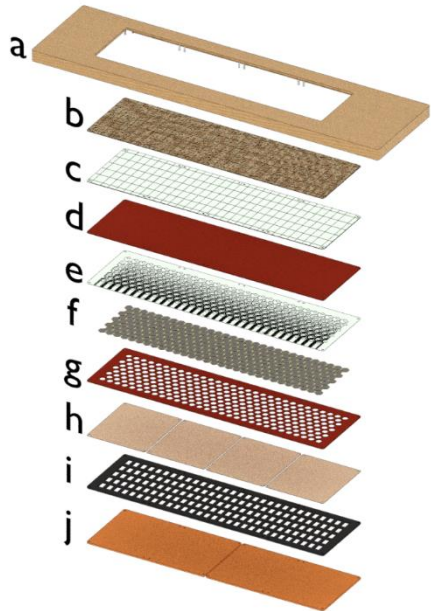


[Enferad & al. 2018]

Approches par Confinement



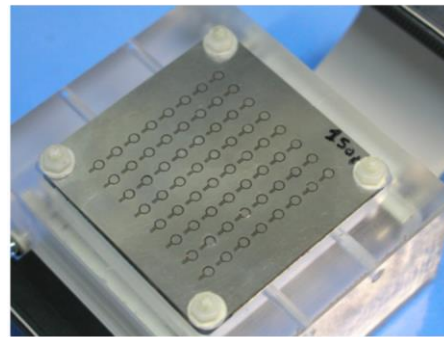
Attenuation



Multi-layered construction of the HSoundplane

[Papetti & al. 2019]

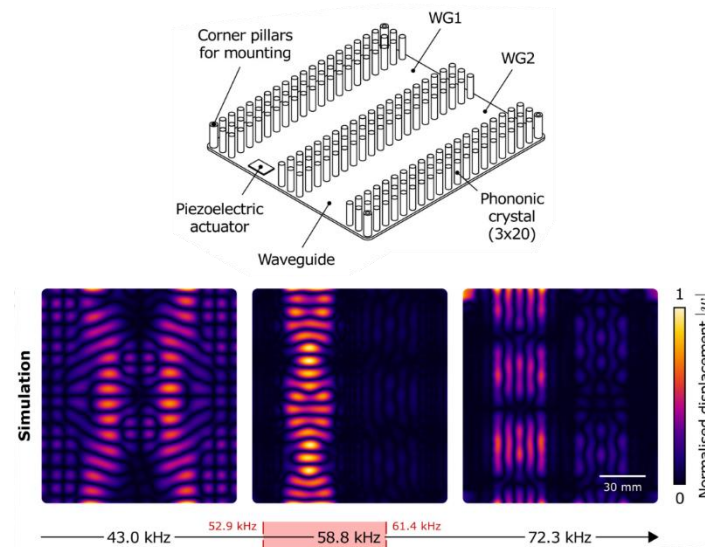
Isolation



VITAL 8 × 8 integrated laser-cut flexible membrane vibrotactile display

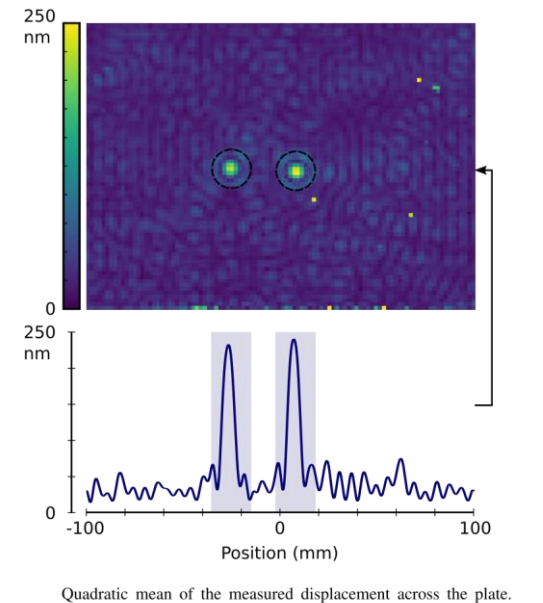
[Benali-Khoudja & al. 2006]

Méta-matériaux

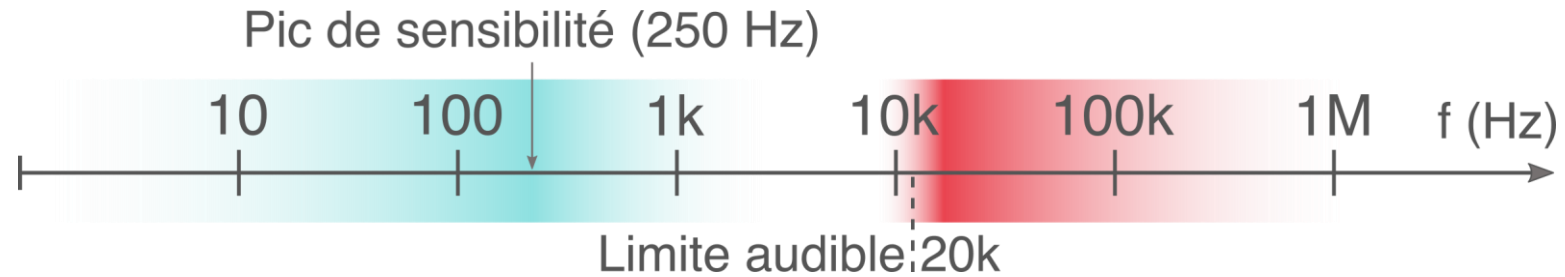


[Daunizeau & al. 2021]

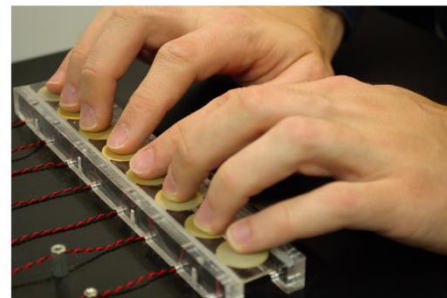
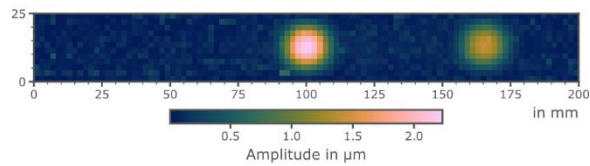
Fréquences non-rayonnantes



[Hudin & al. 2017]

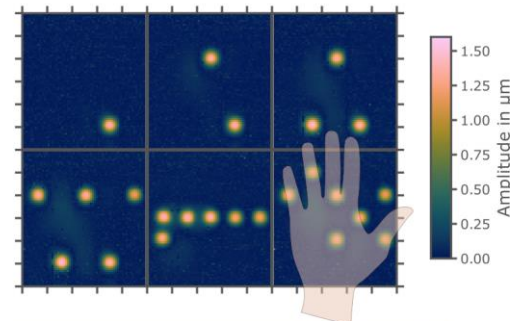


Guide d'onde



[Ben Dhiab & al., 2019]

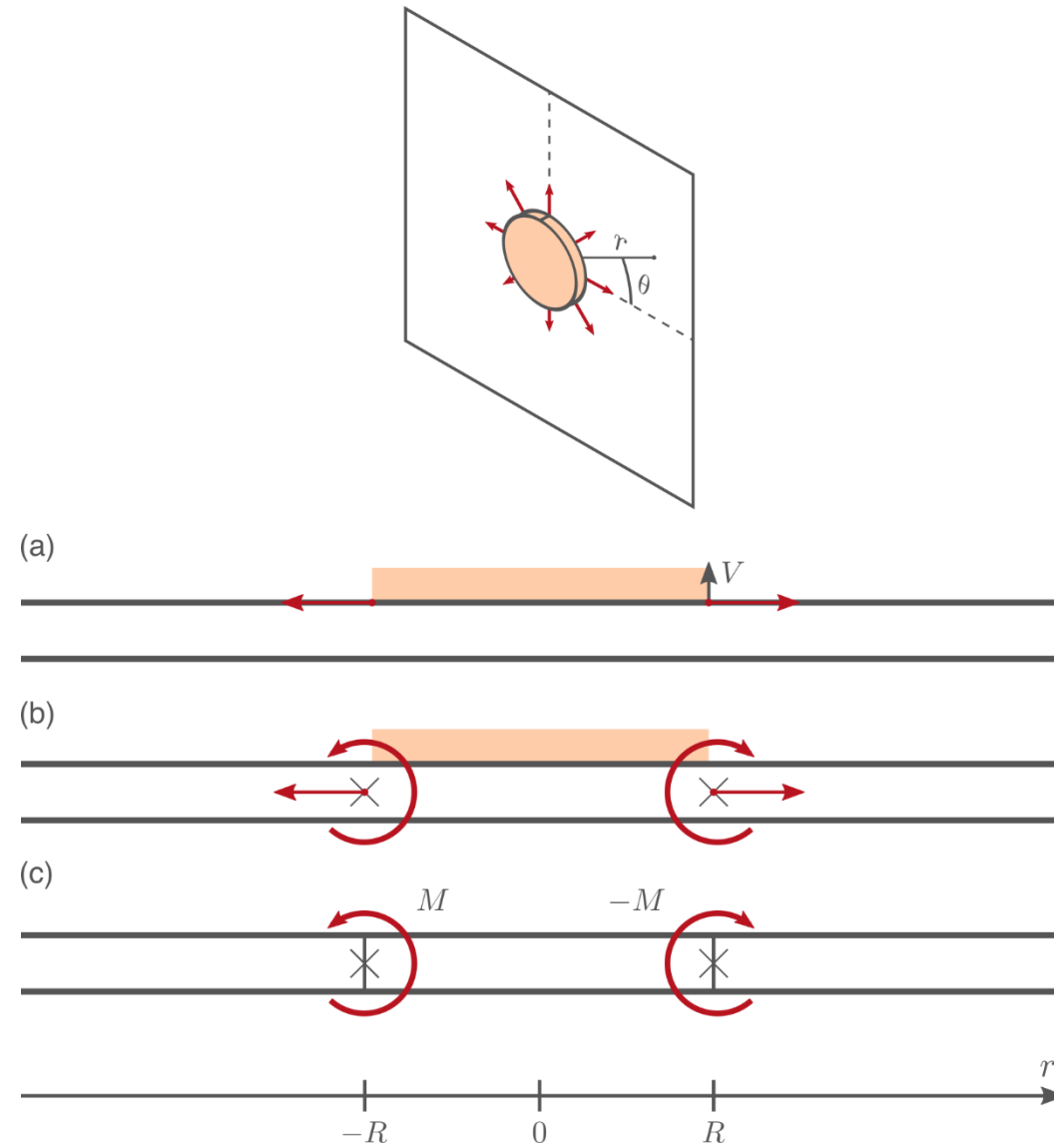
Supports périodiques



[Ben Dhiab & al., 2020]

Fréquences non-rayonnantes

Propagation dans les Milieux et Evanescence



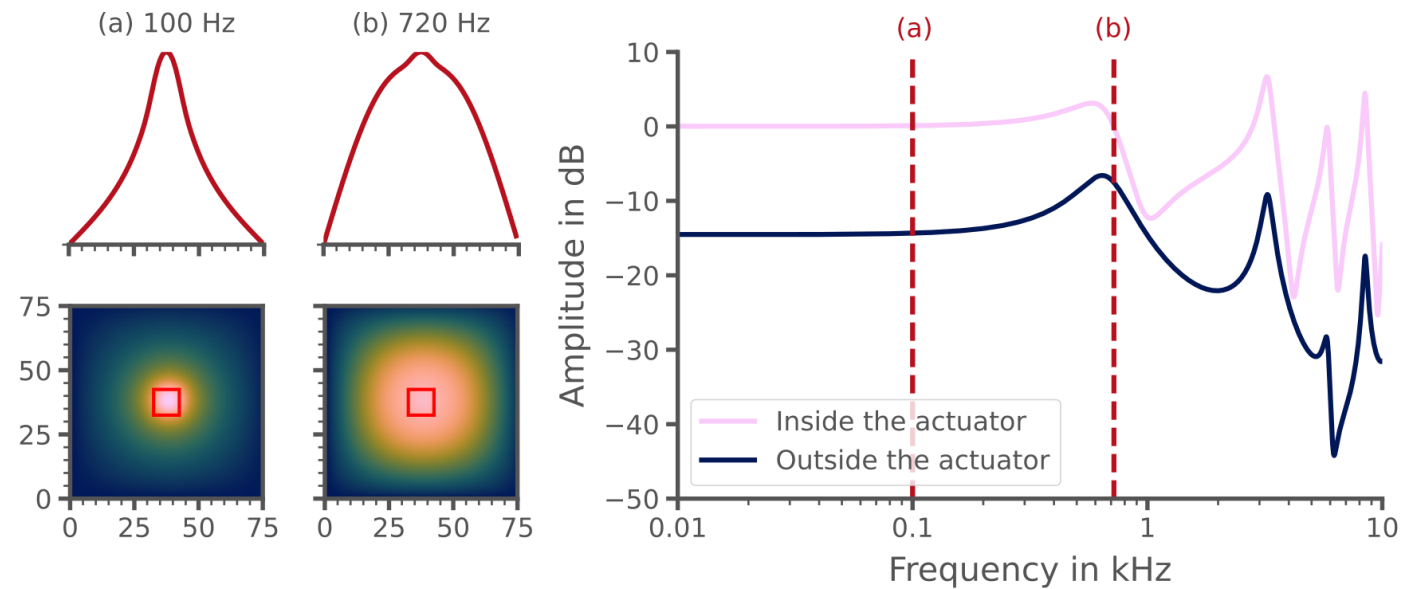


Figure 4.1: Simulation of a $75 \times 75 \times 0.7 \text{ mm}^3$ glass plate excited with a square piezoelectric actuator in its center. The first resonance is around 580 Hz. (a) Before the first resonance, we have an evanescent behavior. (b) After the first mode, propagation occurs and we have a uniform distribution of vibration energy across the surface.

$$\omega_1 = 2 \sqrt{\frac{D}{\rho h}} \left(\frac{\pi^2}{a^2} \right)$$

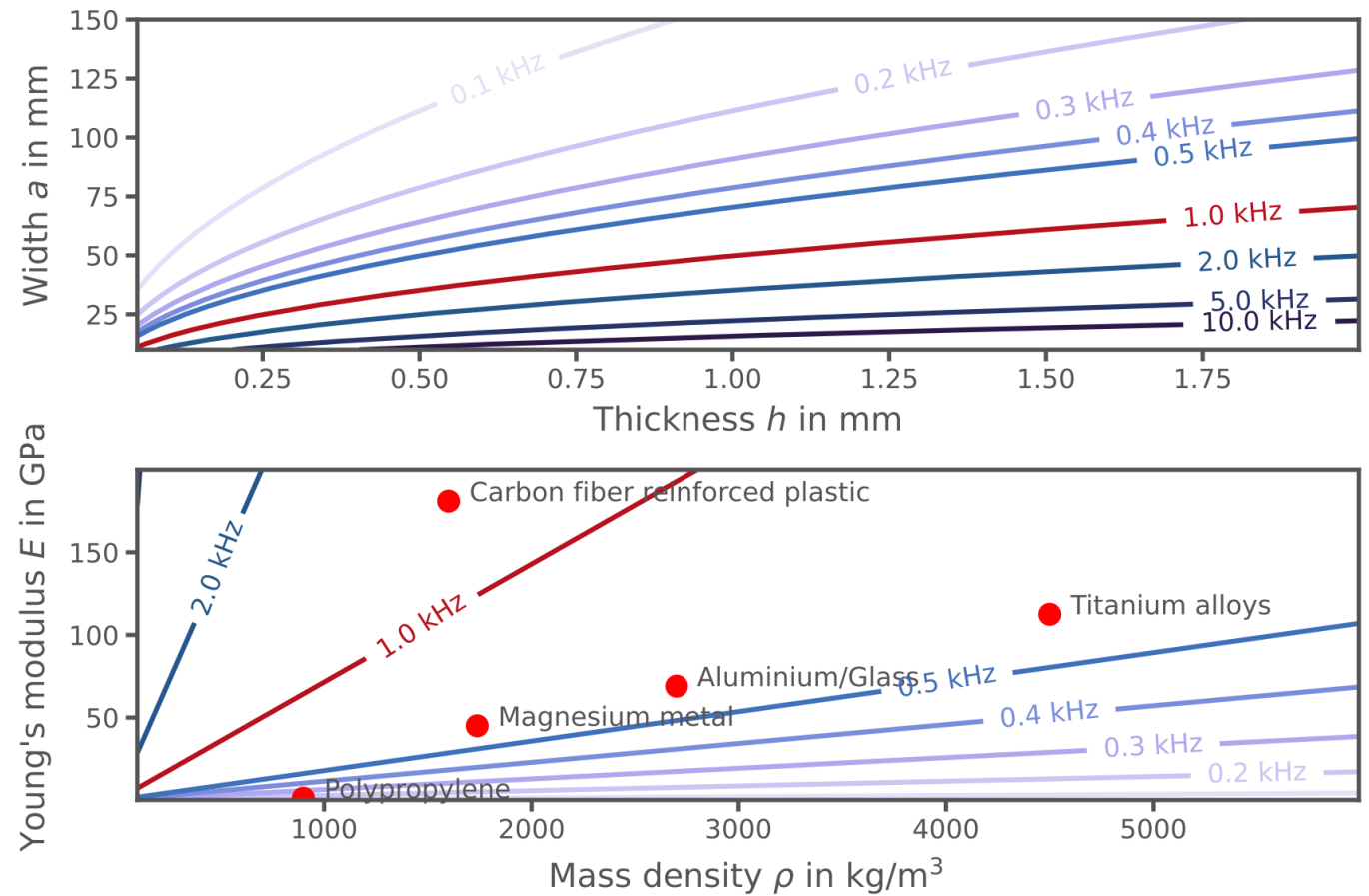


Figure 4.2: Abacus. Upper: First mode frequency abacus of a glass plate depending on its geometrical properties. Lower: First mode frequency abacus of a $75 \times 75 \times 0.7 \text{ mm}^3$ plate depending on its material properties ($\nu = 0.3$).

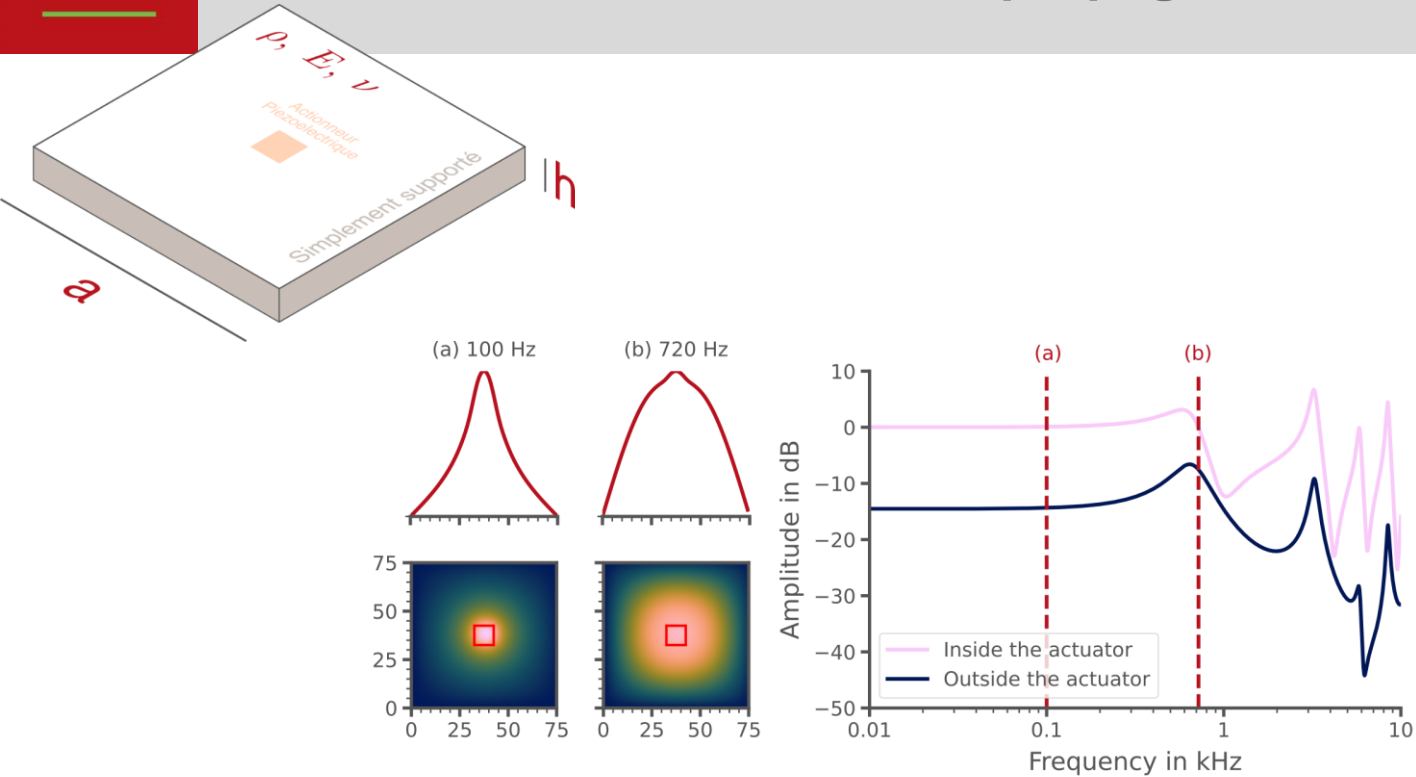


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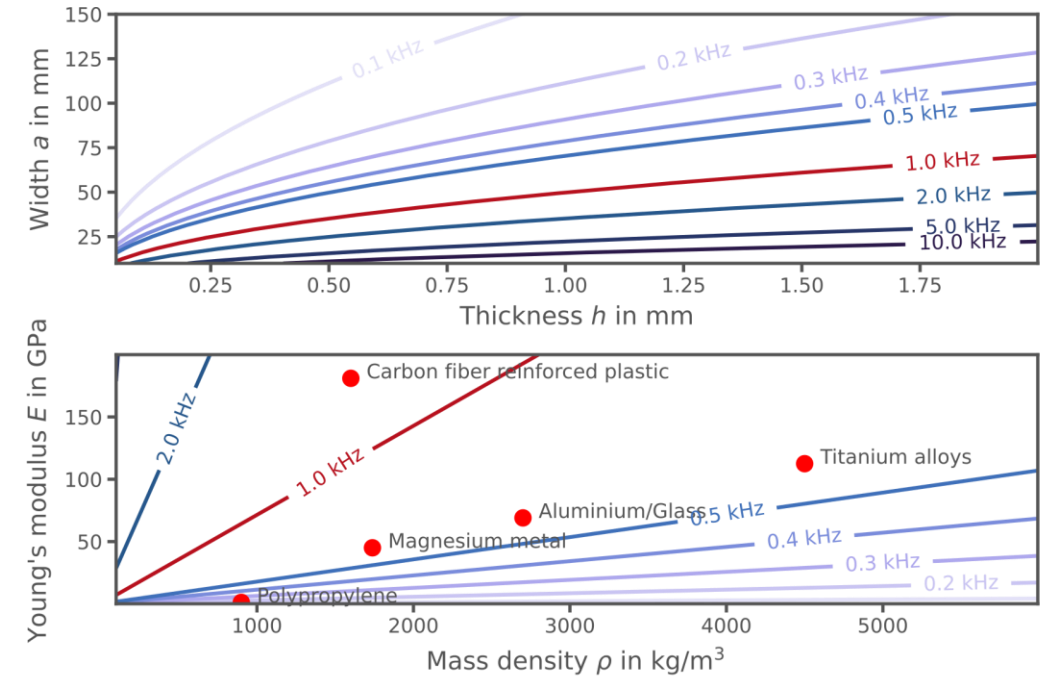


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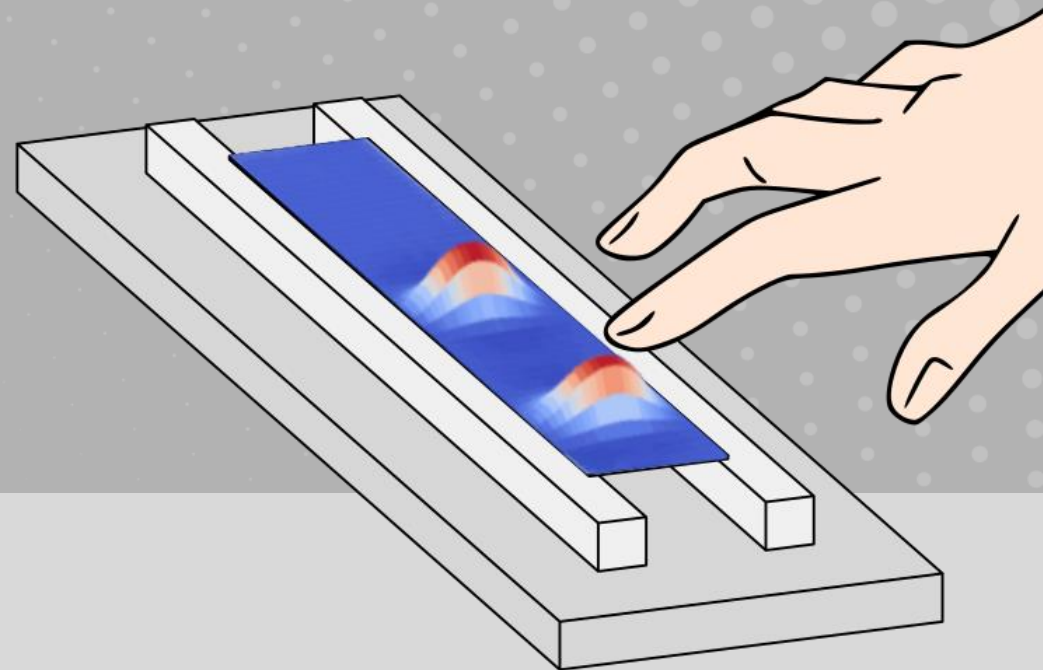
$$\omega_1 = 2 \sqrt{\frac{D}{\rho h}} \left(\frac{\pi^2}{a^2} \right)$$

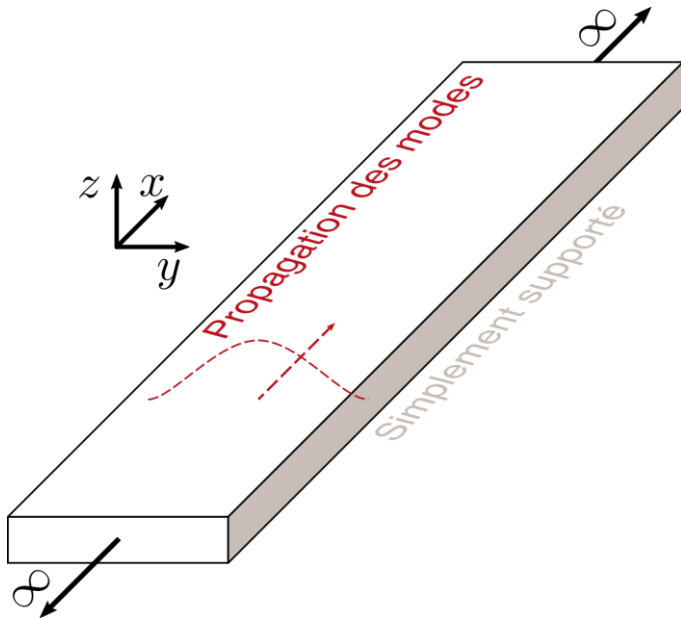
- $\omega_1 \nearrow$
- *taille* \searrow
 - *masse* \searrow
 - *rigidité* \nearrow

Réduire la taille $a \searrow \rightarrow$ Guide d'onde

Augmenter la rigidité \rightarrow Raidisseurs
+ Conditions aux limites
 \rightarrow Supports périodiques

Confinement des Vibrations dans les *Guides d'Ondes*





$$f_n = \frac{\omega_n}{2\pi} = \frac{\pi}{4\sqrt{3}} \frac{h}{W^2} \sqrt{\frac{E}{\rho(1-\nu^2)}} n^2$$

Paramètres Géométriques

Paramètres Matériaux

h : épaisseur

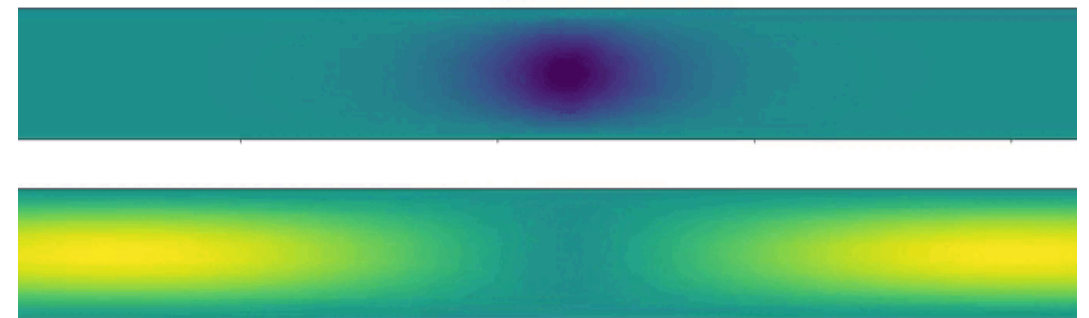
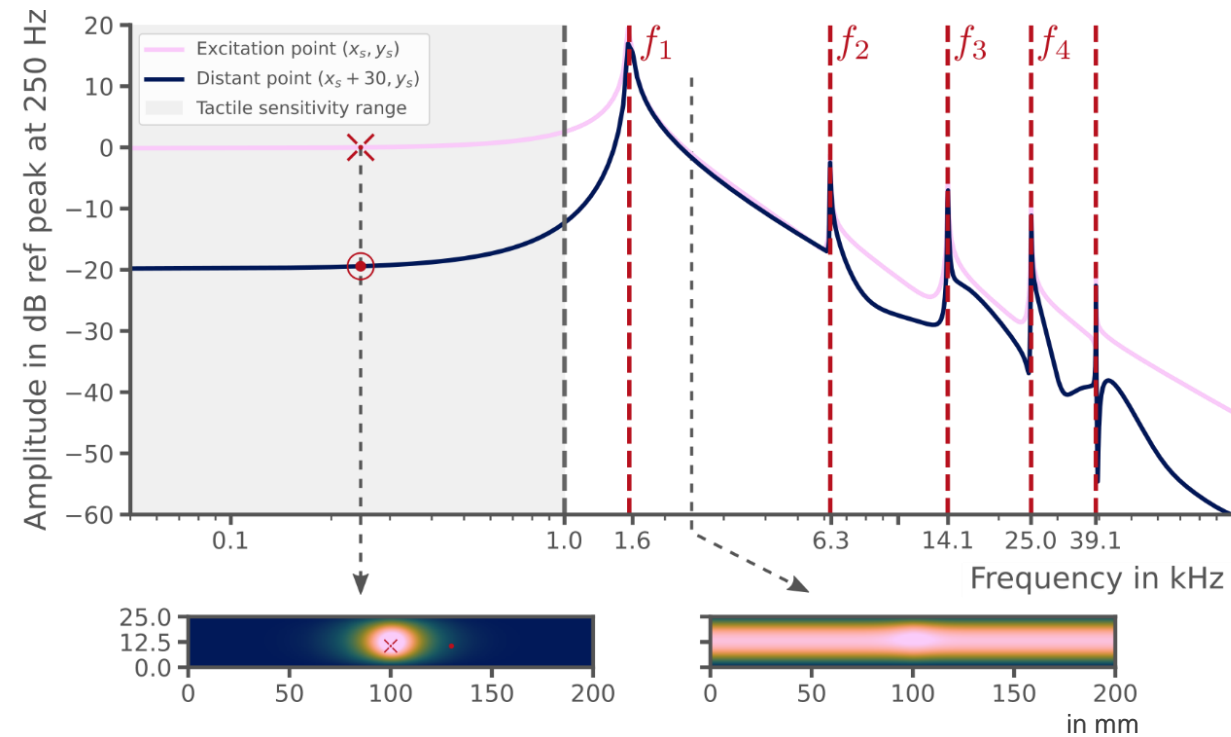
W : largeur

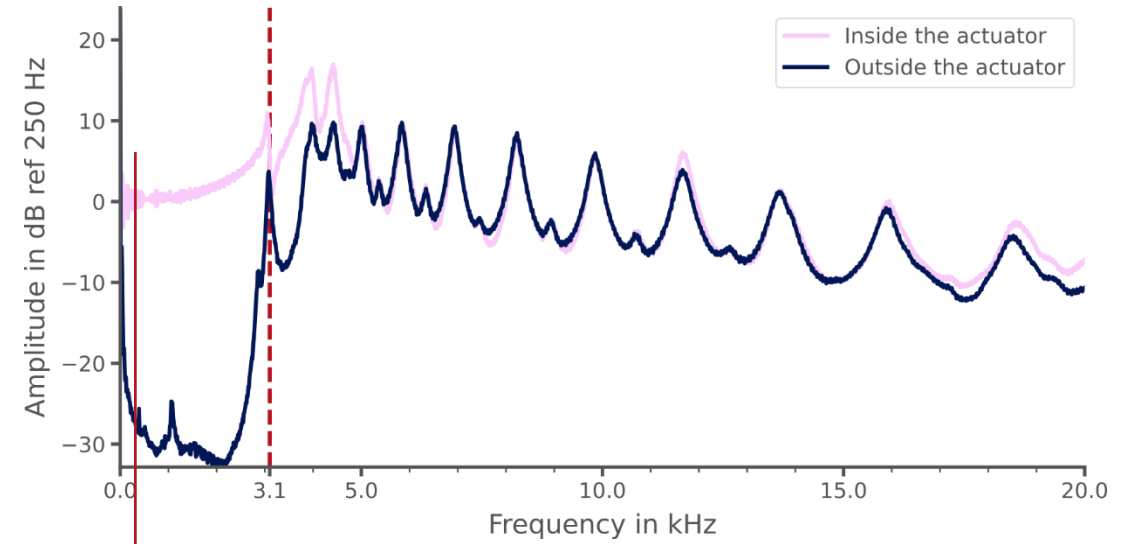
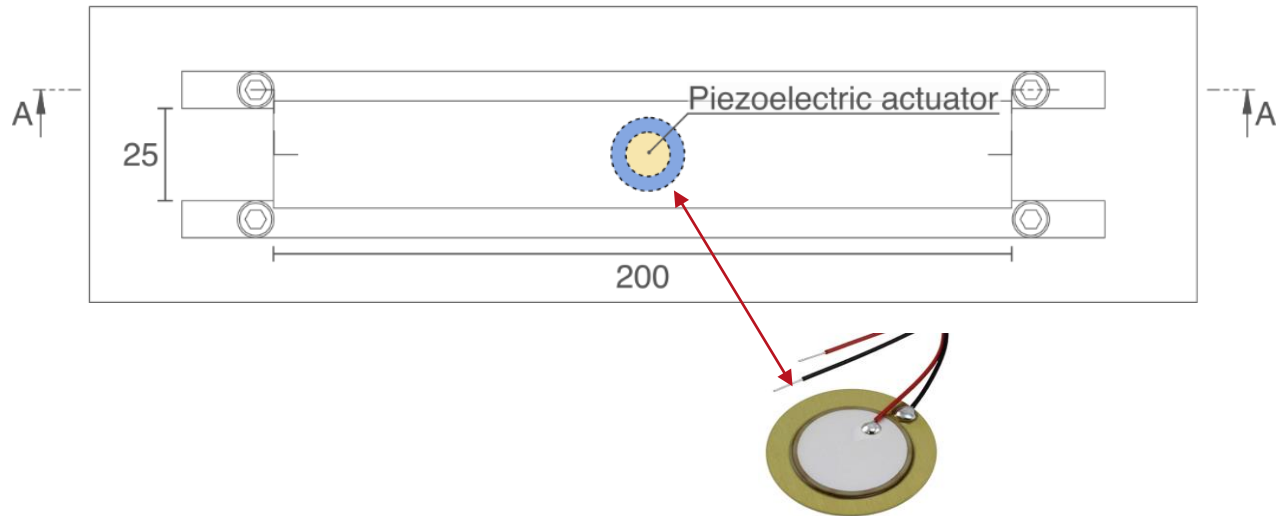
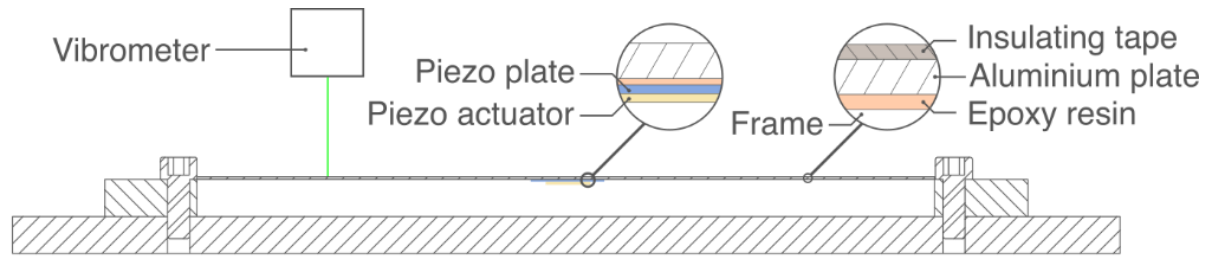
E : Module d'Young

ρ : masse volumique

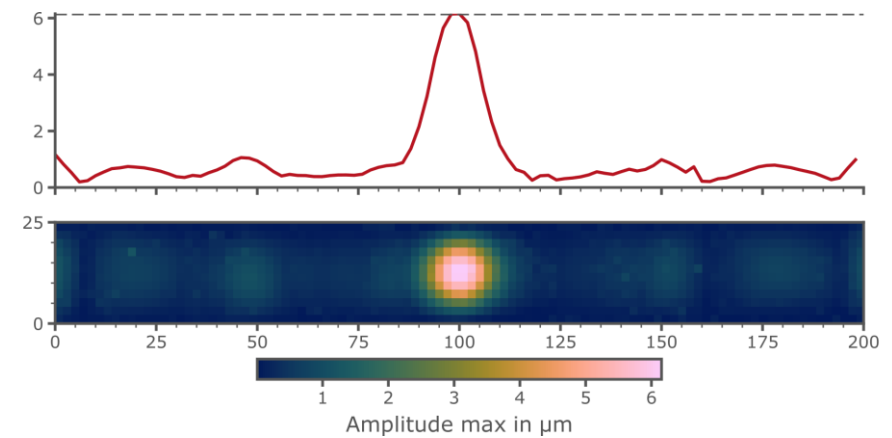
ν : coefficient de Poisson

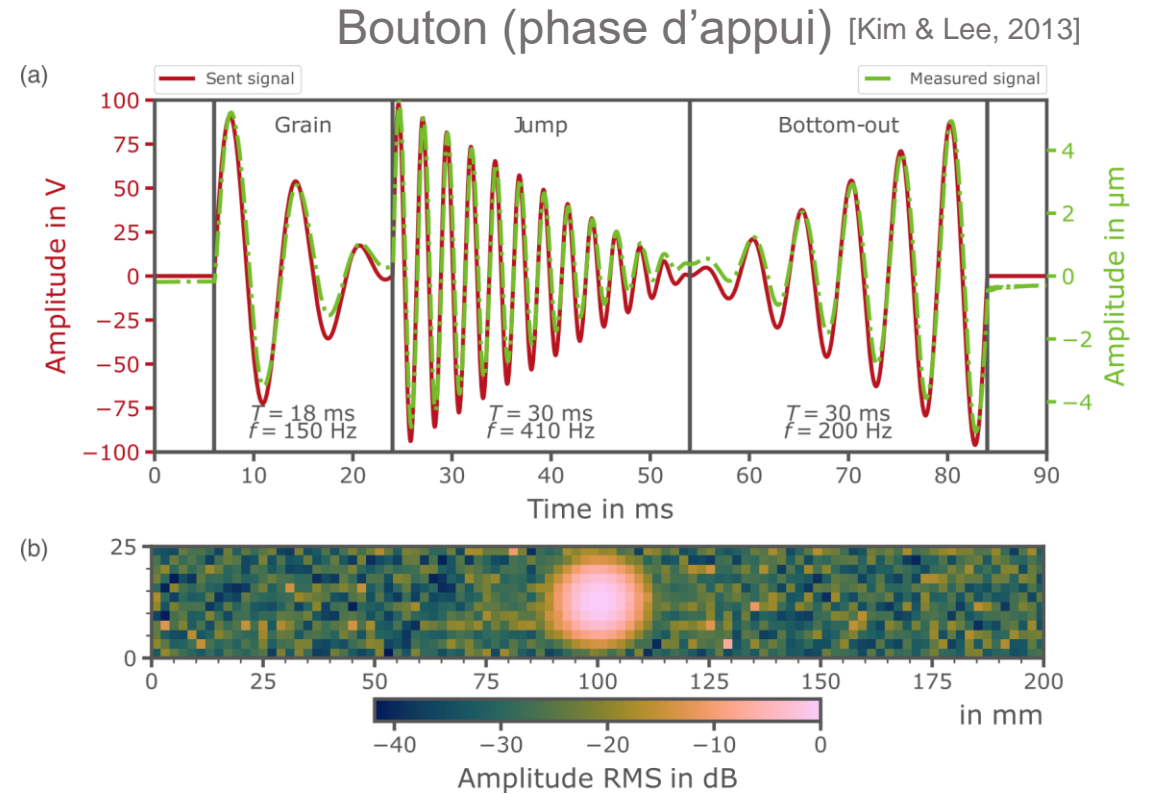
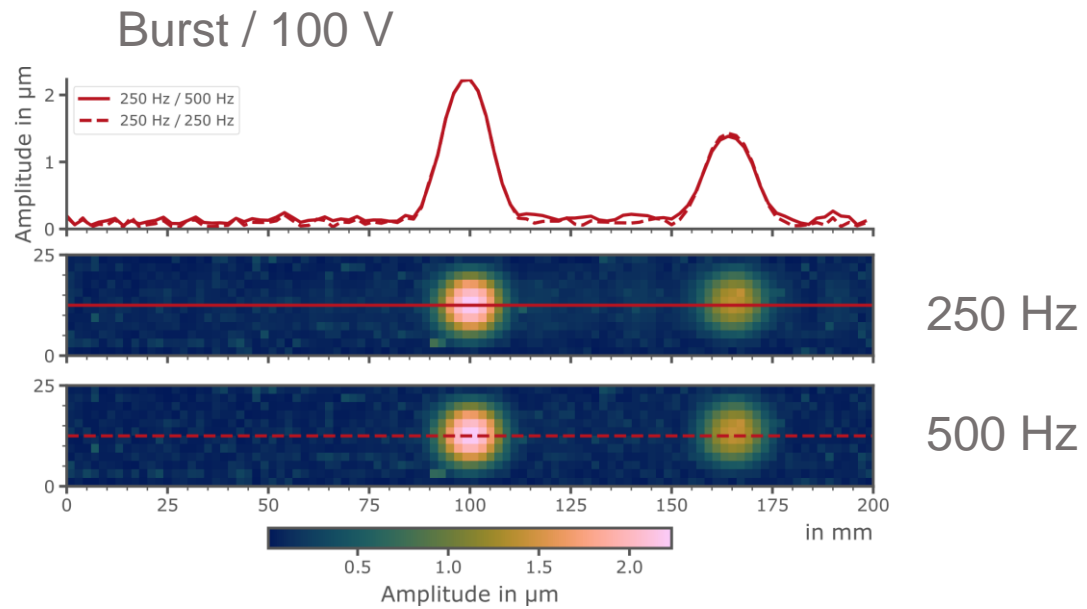
n : numéro du mode

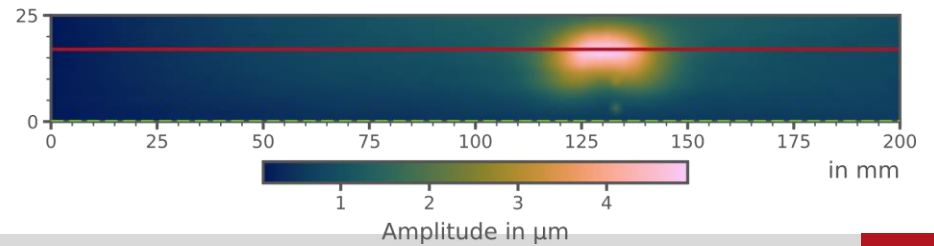
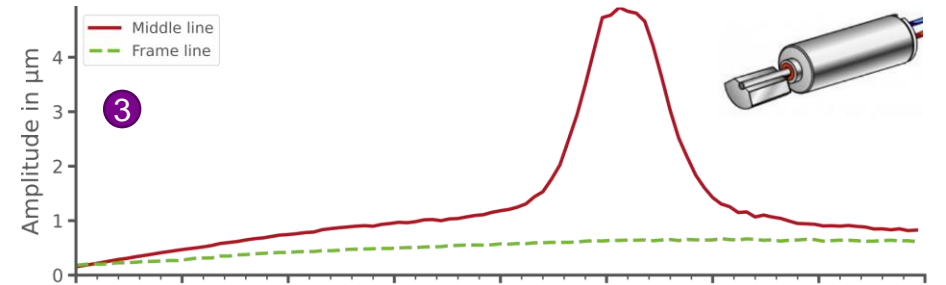
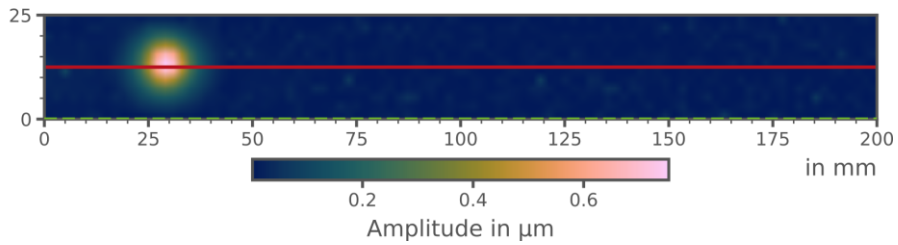
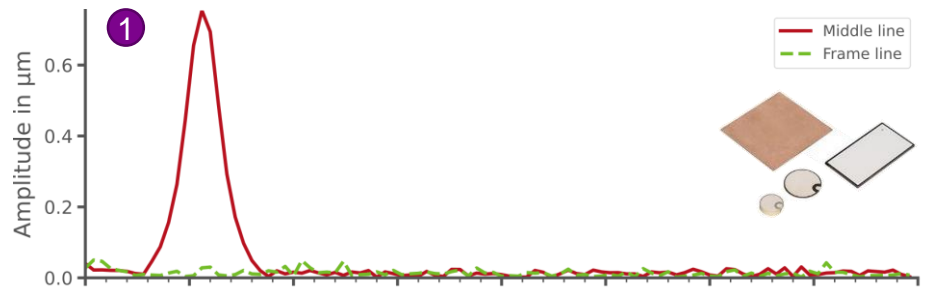
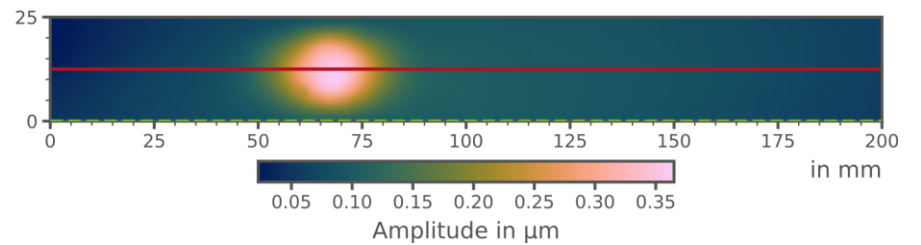
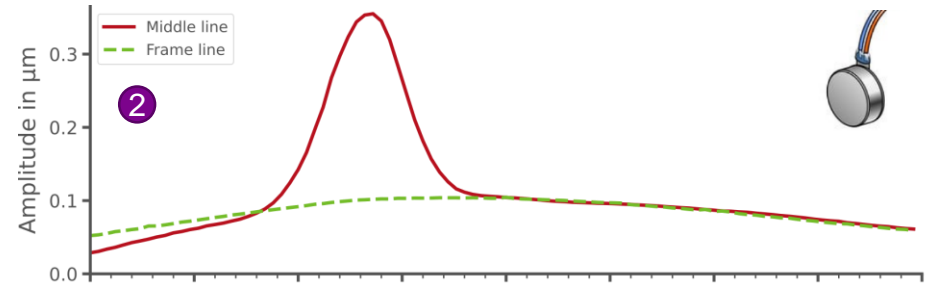
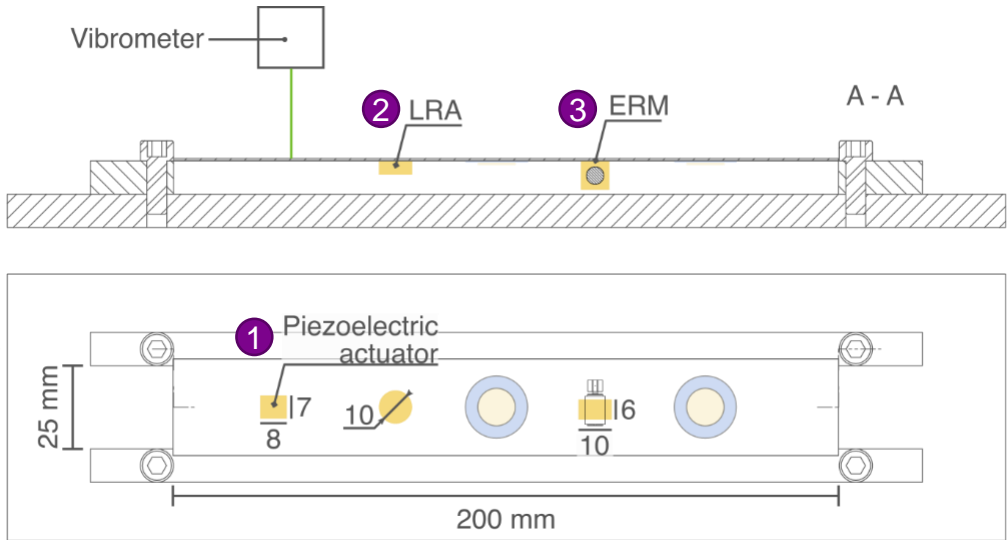




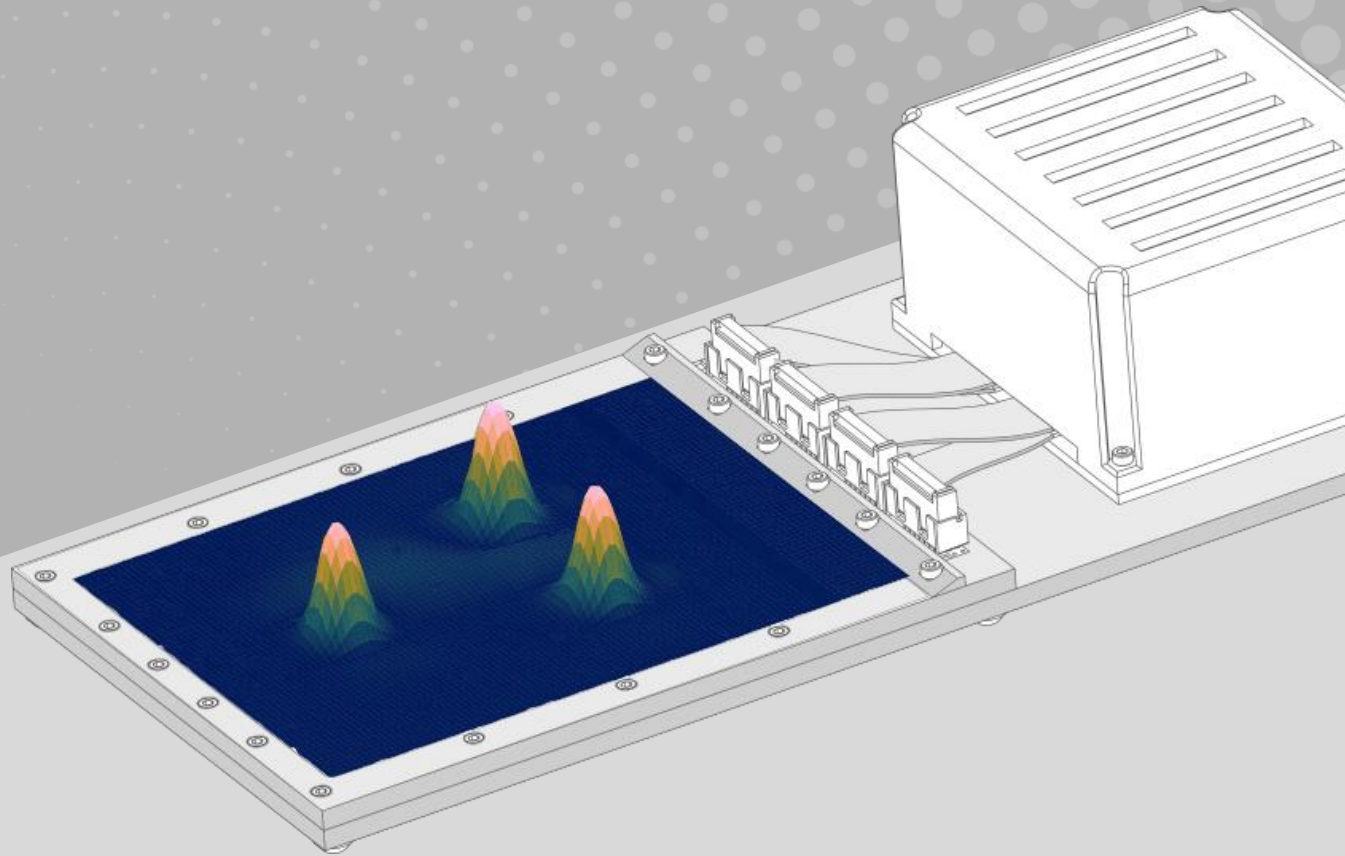
Sin / 250 Hz / 100 V

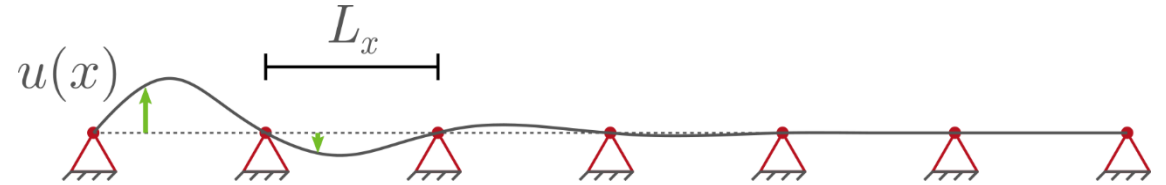
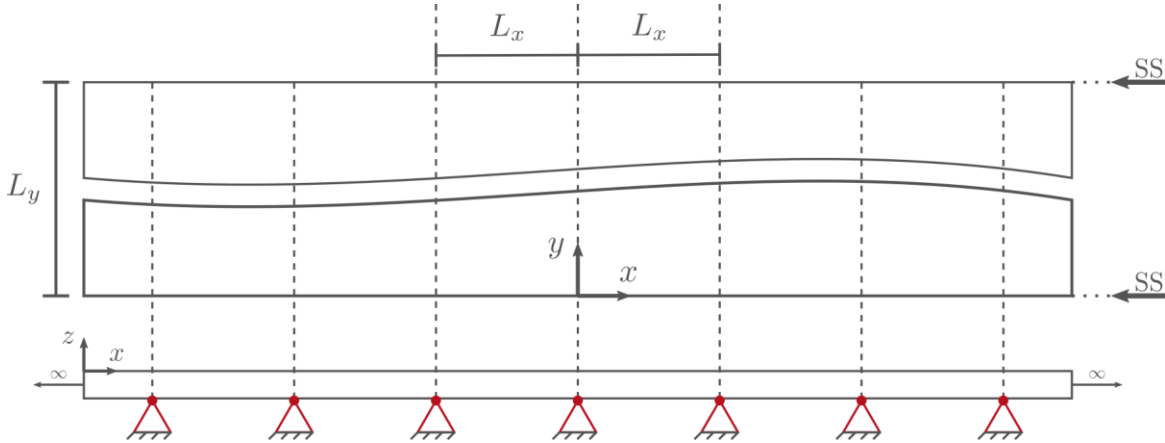






Confinement des Vibrations sur *Surfaces Etendues*





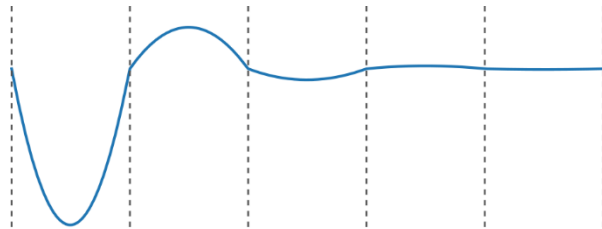
$$u(x + L_x) = u(x)e^{\mu}$$

$$\mu = \mu_r + j\mu_i$$

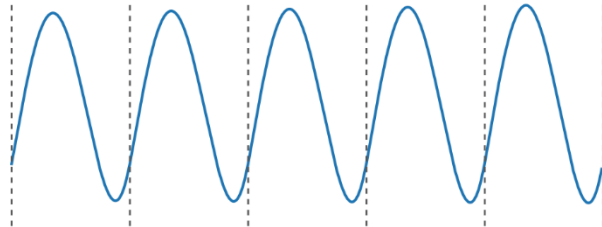
Constante de propagation
d'une section à une autre.

[Mead, 1986]

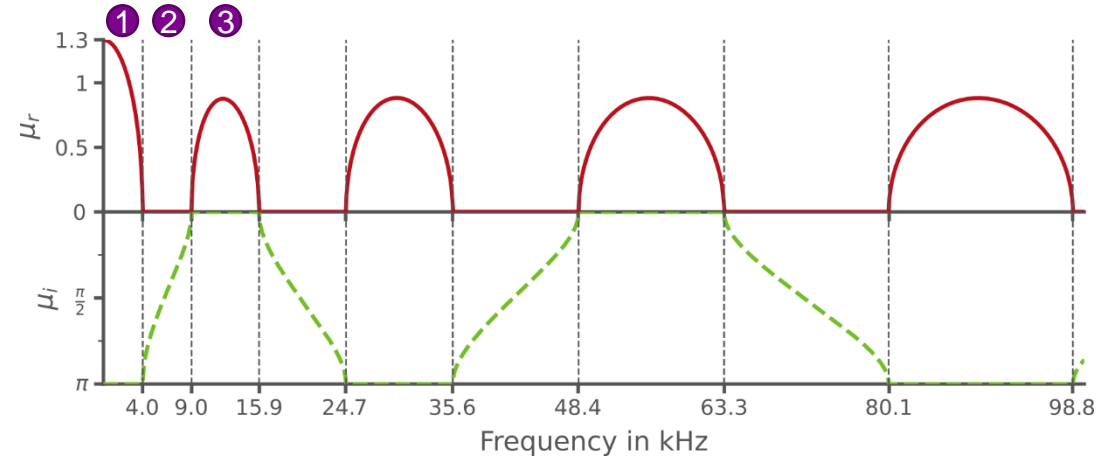
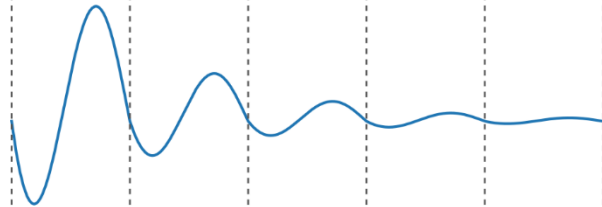
1

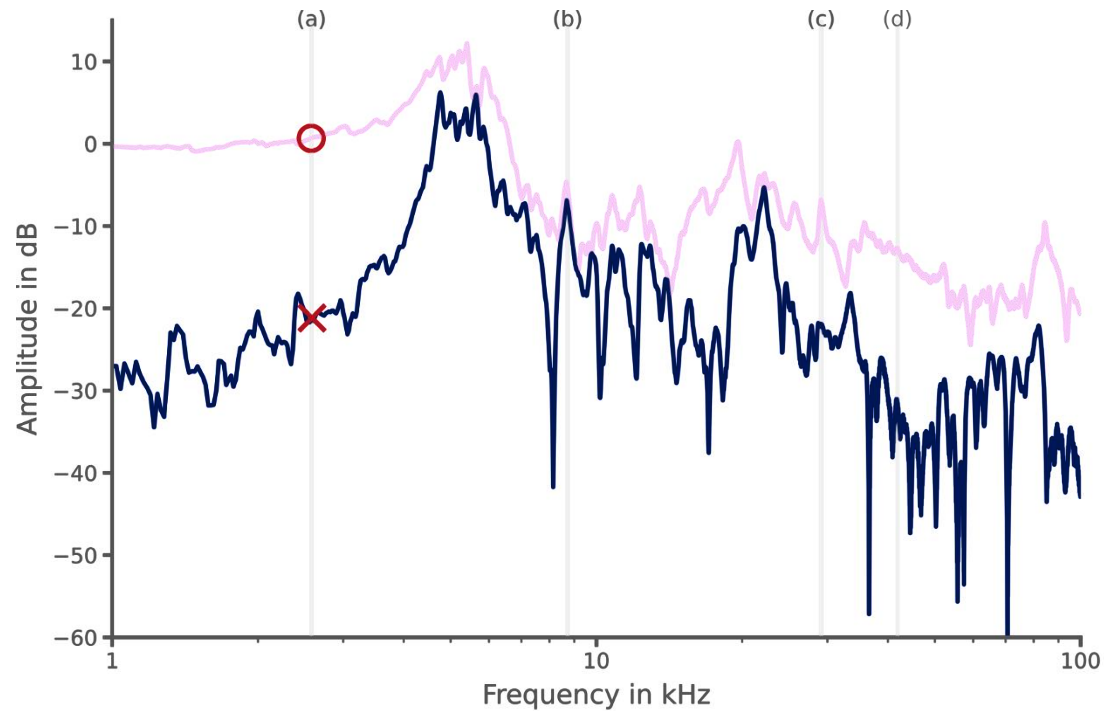


2



3



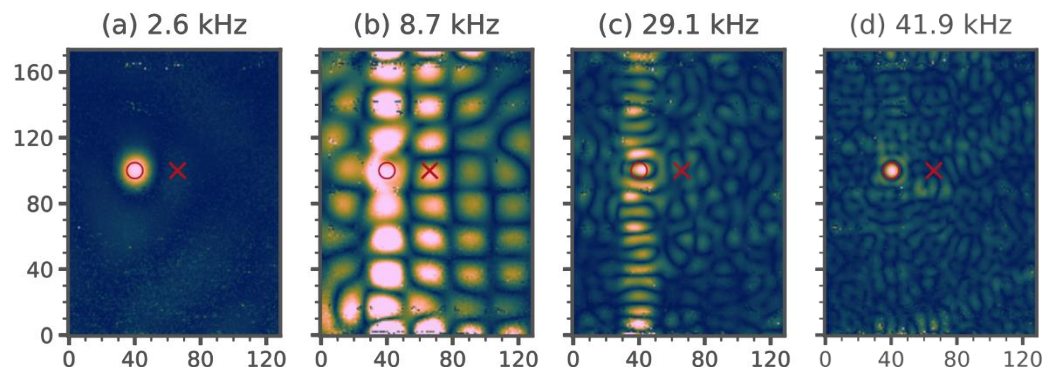


(a) Non propagation

(b) Propagation

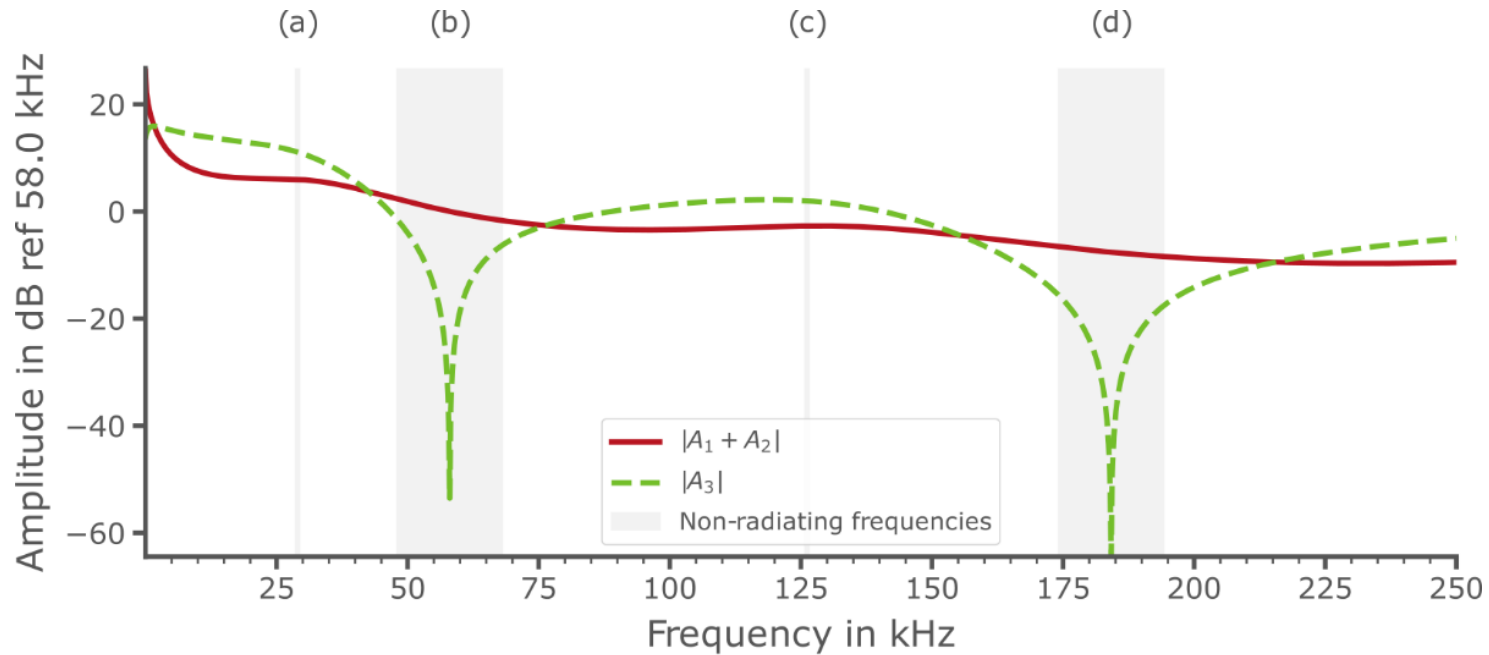
(c) Attenuation

(d) Non-rayonnement



Fréquences Non-Rayonnantes et Modulation de Friction Localisée



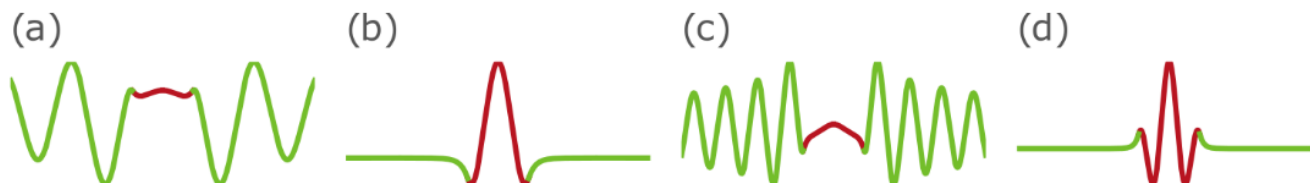


$$f_n = \frac{1}{2\pi} \sqrt{\frac{D}{\rho h}} \left(\frac{\alpha_n}{R}\right)^2$$

avec : $J_1(\alpha_n) = 0$

soit : $\alpha_n = 3.83, 7.02, 10.17, \dots$

- Si $R \searrow \rightarrow f_n \nearrow$





CONCEPTION



RECHERCHE



AUDIO



ASSEMBLAGE



SUPPORT



USAGES



MULTI-TOUCH



COLLAGE



PIEZOELECTRIQUE



MATERIAU MOU



COQUE



ELECTRONIQUE



SOUDAGE



CODEC



ACCESSIBILITE



MATRICE



PSYCHOPHYSIQUE



API