

Interaction through shape-changing surfaces

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Interaction through shape-changing surfaces



Octopus: no bone but remarkable shape-changing ability



**Latest devices
manually change
between limited shapes**

Latest devices
manually change
between limited shapes



Limitations

Limitations

Rigid



Unsuitable to wear on the body

Not actuated



Limited applications

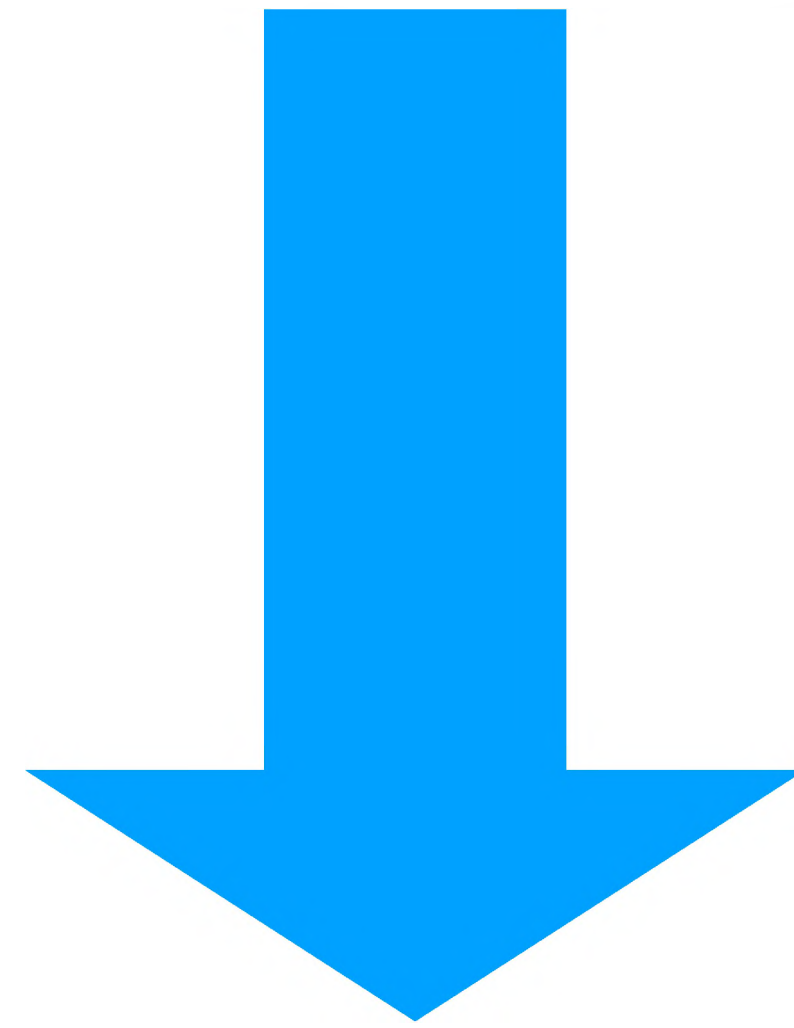
Limited shapes



Limited functions

Soft, actuated, and more shape-changes

**Soft, actuated, and more
shape-changes**



Novel user interaction experience

programmable soft materials

programmable soft materials?

soft

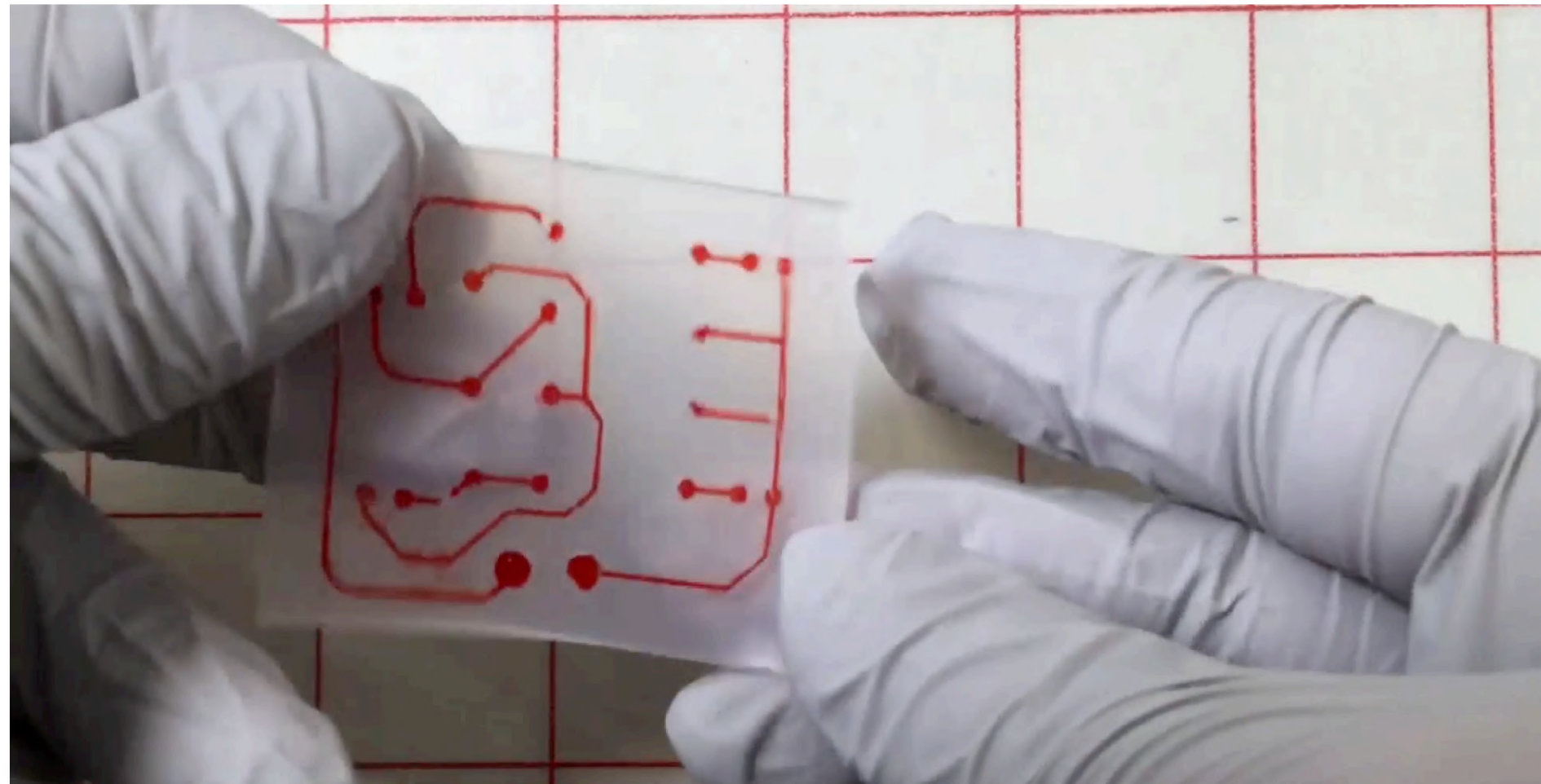
Soft materials

Elastomer



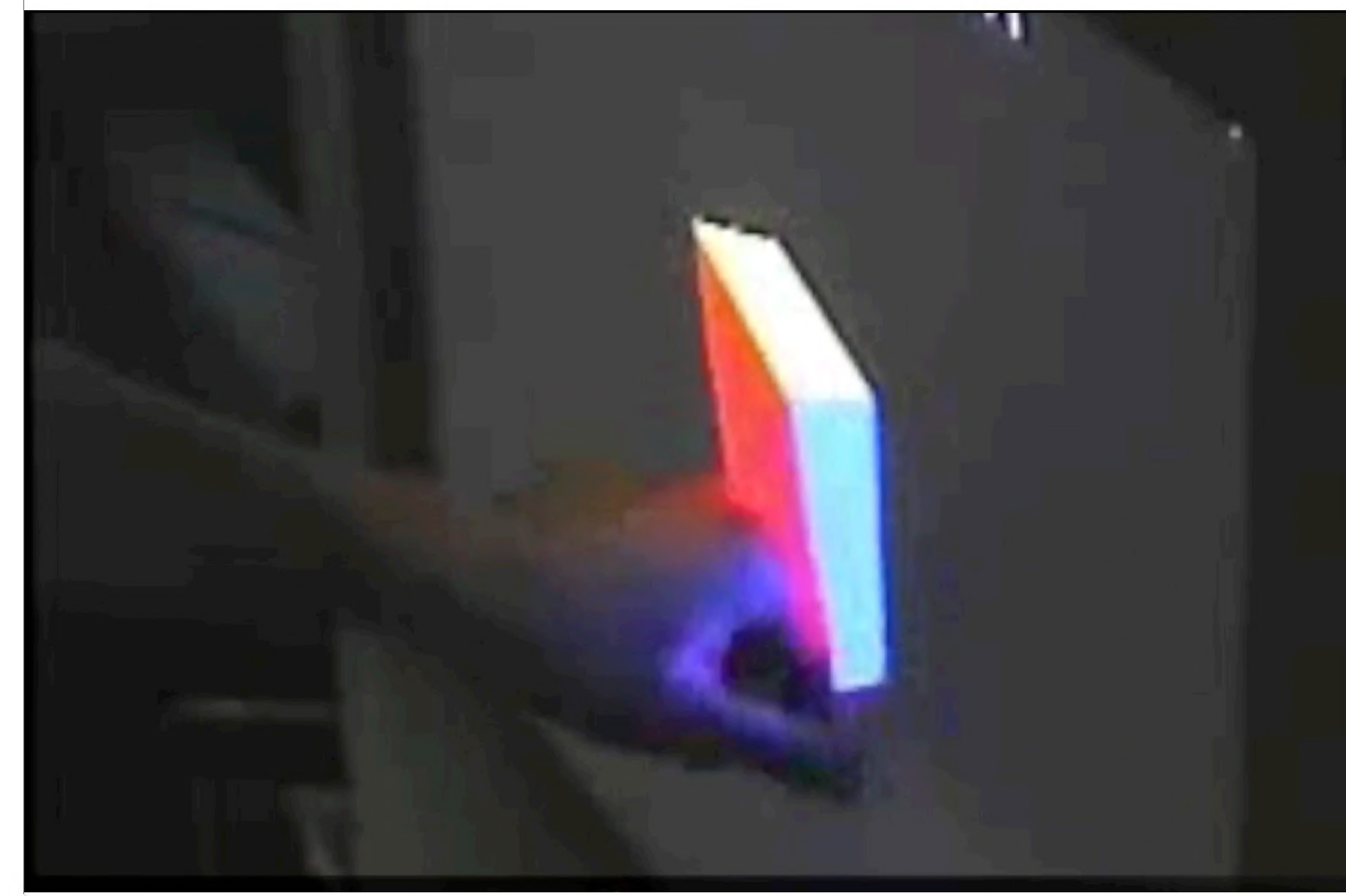
[Teyssier et al, UIST'19]

Hydrogel



[Yuk et al, Nature
Communications 2016]

Fabric



[Troiano et al, AVI' 14]

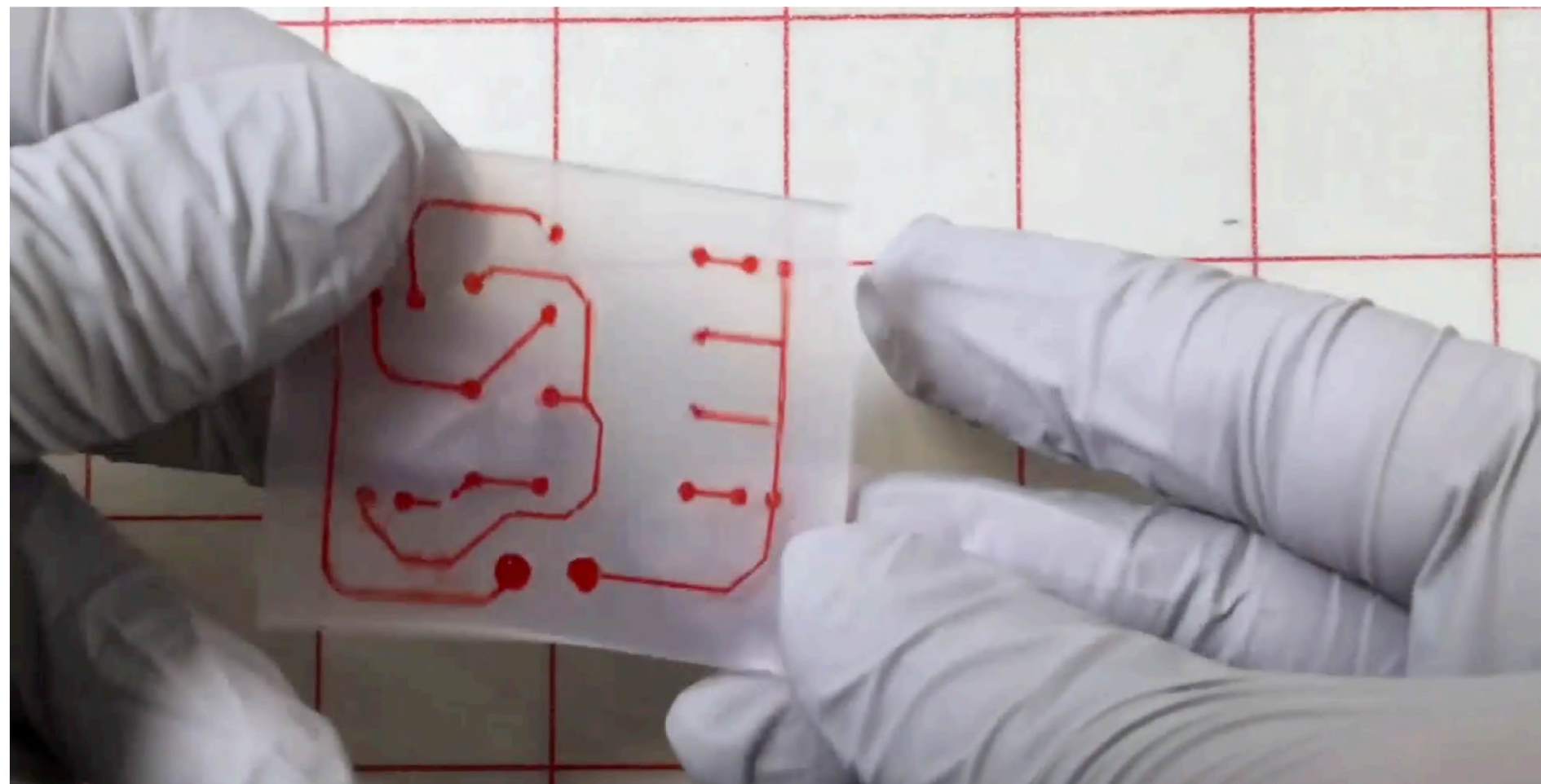
Soft materials

Elastomer



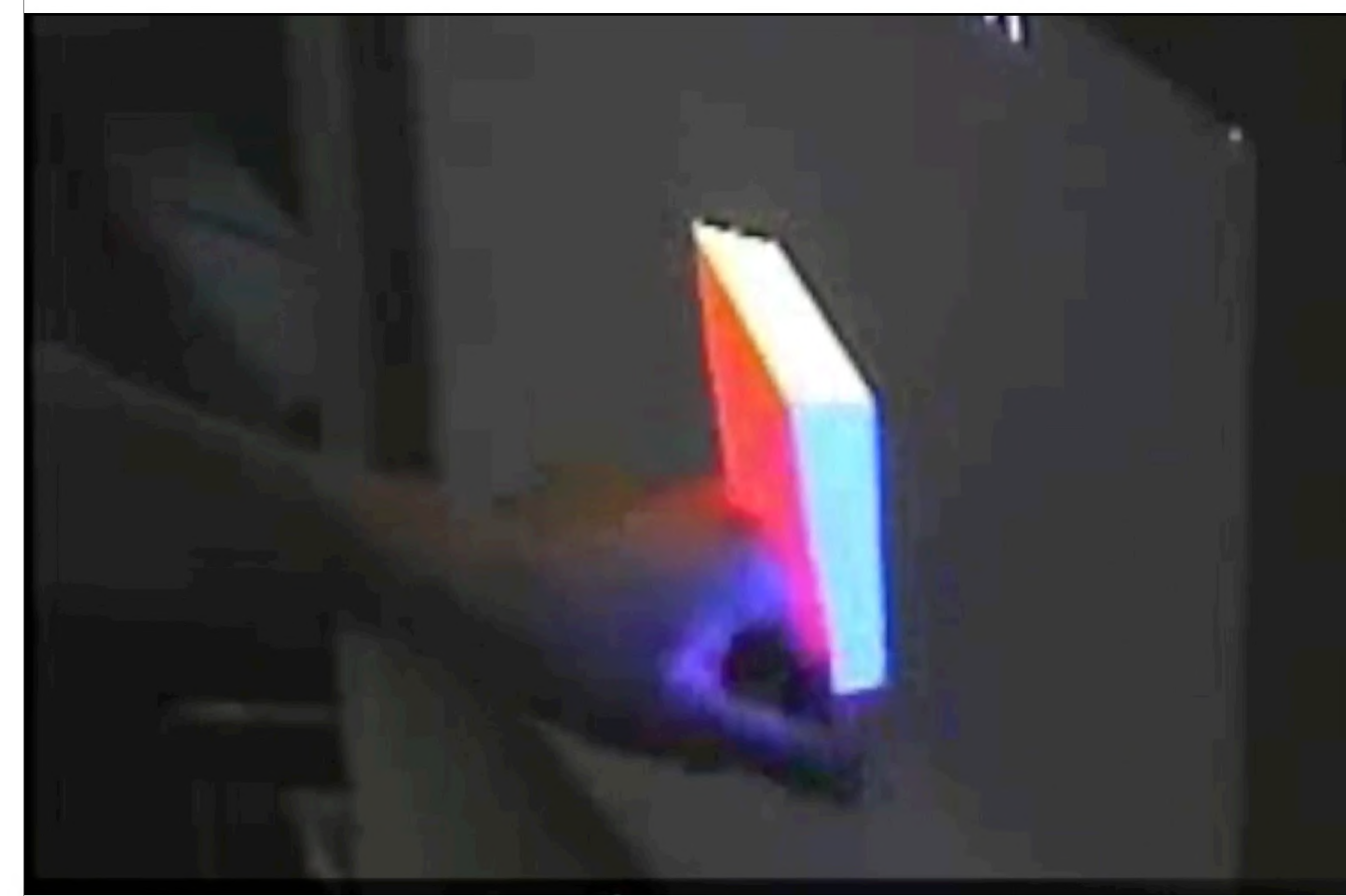
[Teyssier et al, UIST'19]

Hydrogel



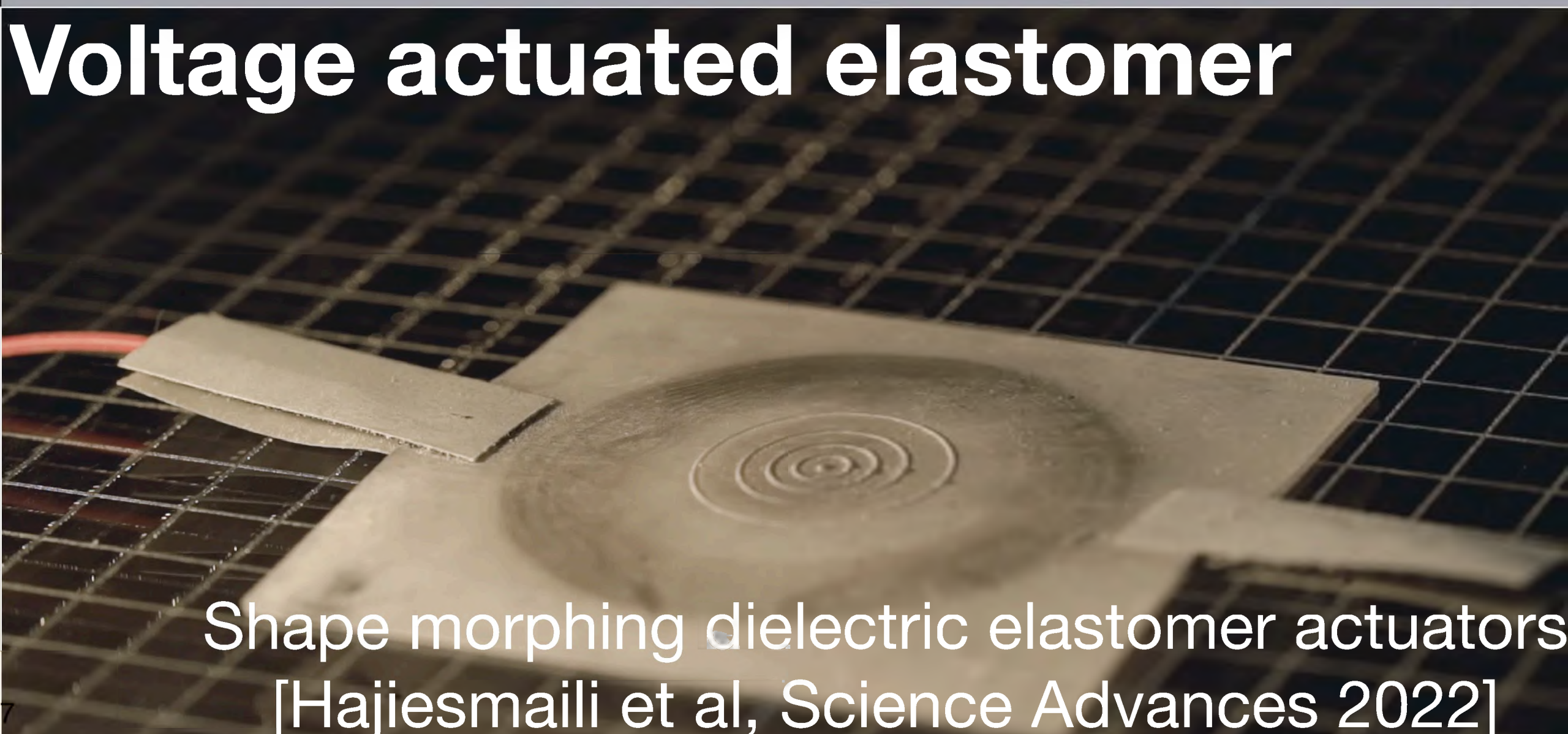
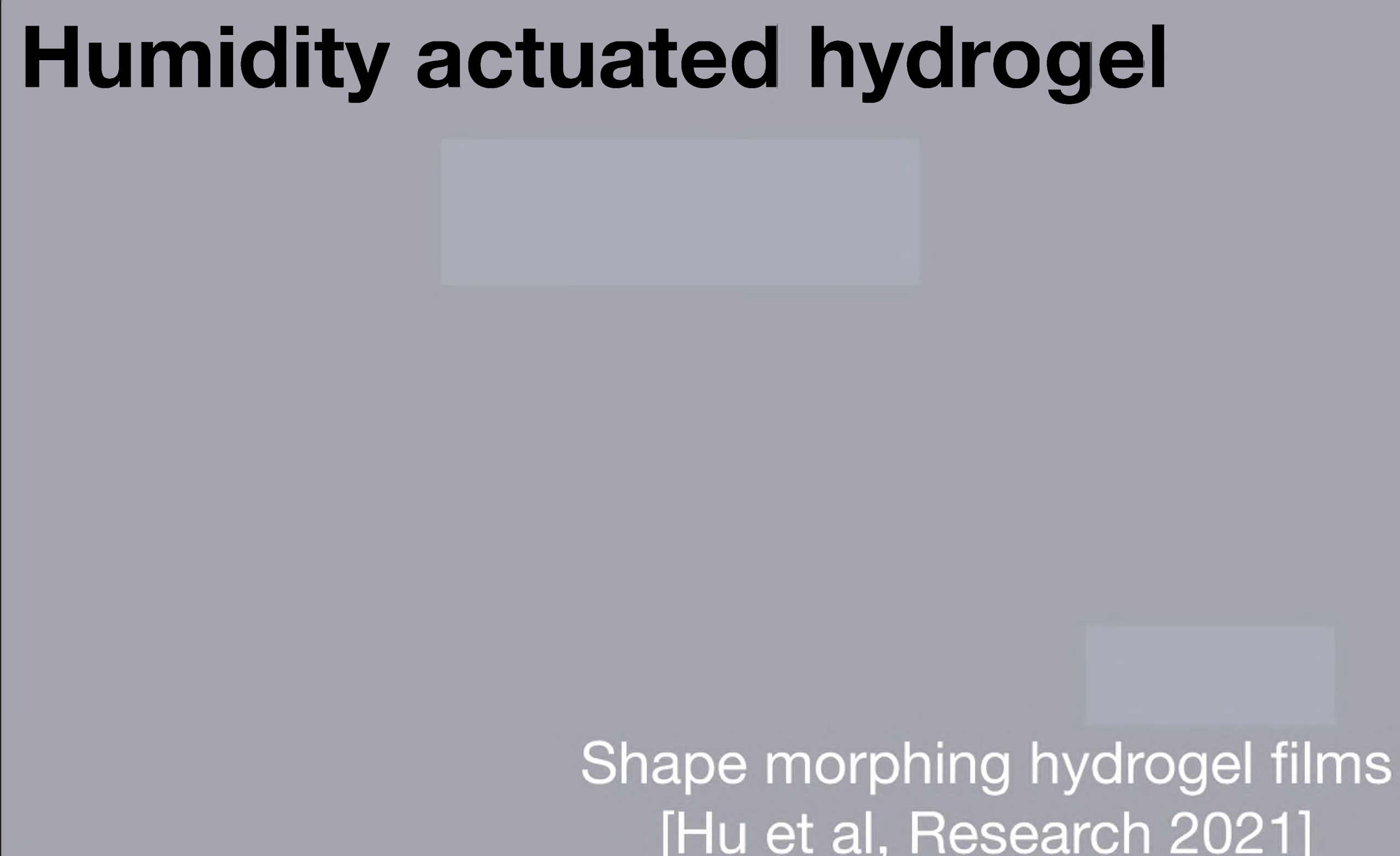
[Yuk et al, Nature
Communications 2016]

Fabric



[Troiano et al, AVI' 14]

programmable



Air pressure actuated elastomer

Baromorph
[Siéfert et al, Nature Materials 2019]

Heat actuated fabric



Humidity actuated hydrogel

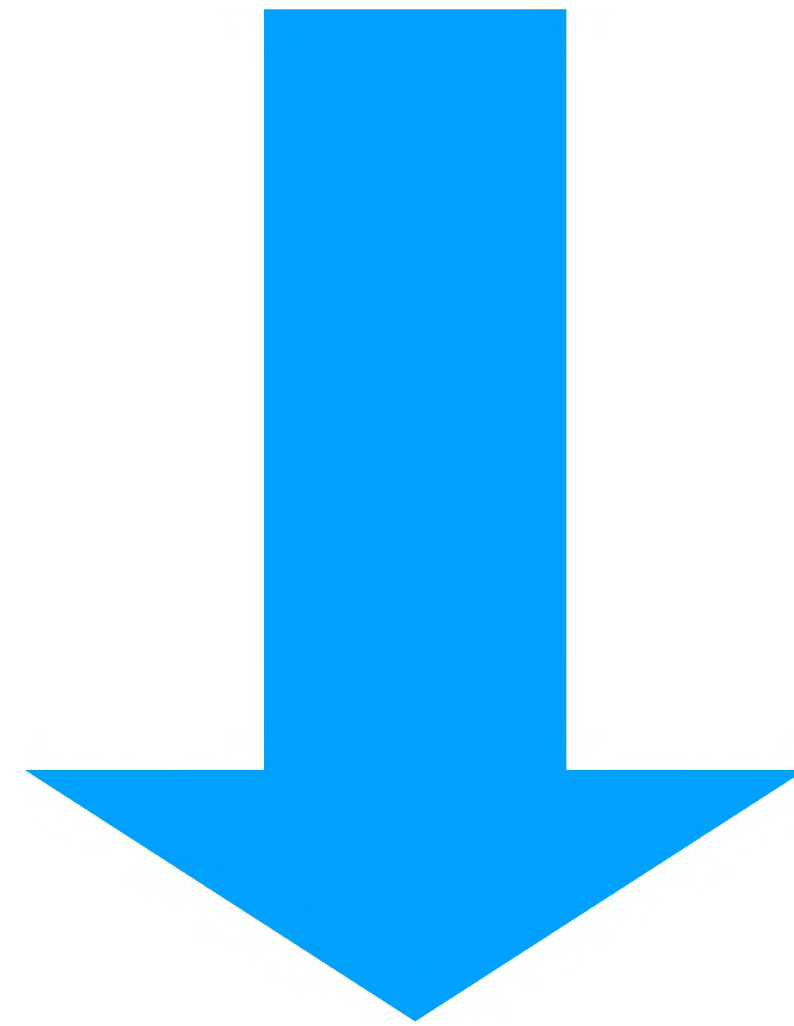


Voltage actuated elastomer



Programmable soft materials

Programmable soft materials



Shape-changing UIs

Adapt to users



ambienBeat
[Choi et al, TEI' 20]

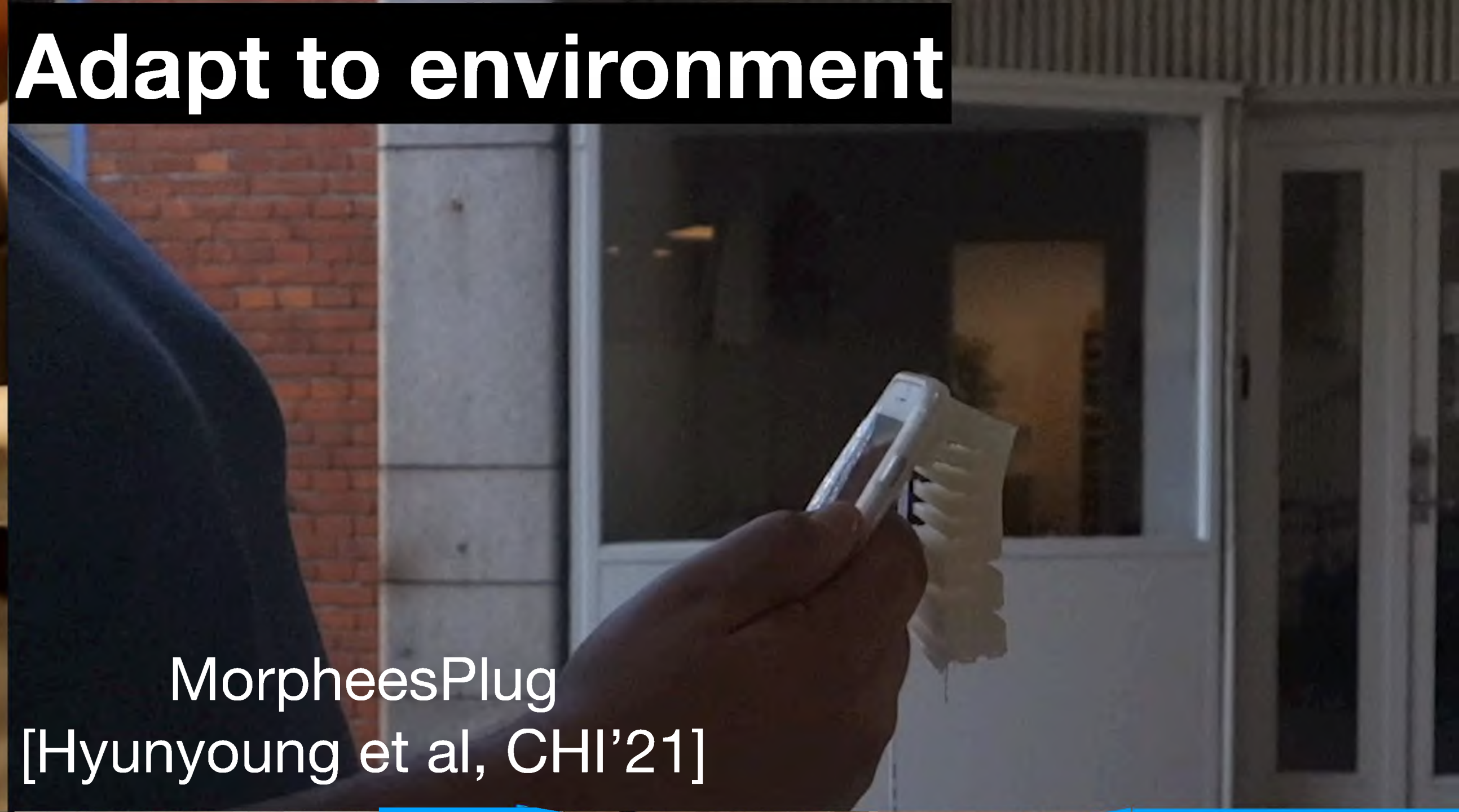
Adapt to task



Transformable tablet cases

PneUI
[Yao et al, UIST'13]

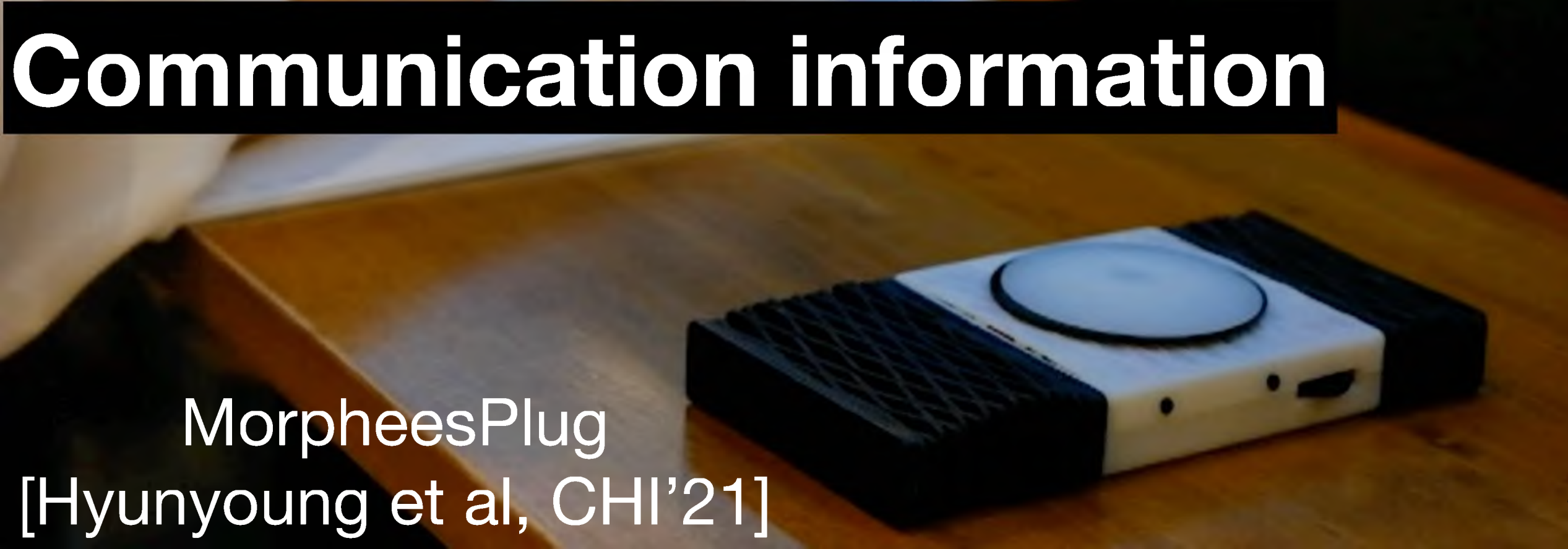
Adapt to environment



MorpheesPlug
[Hyunyoung et al, CHI'21]



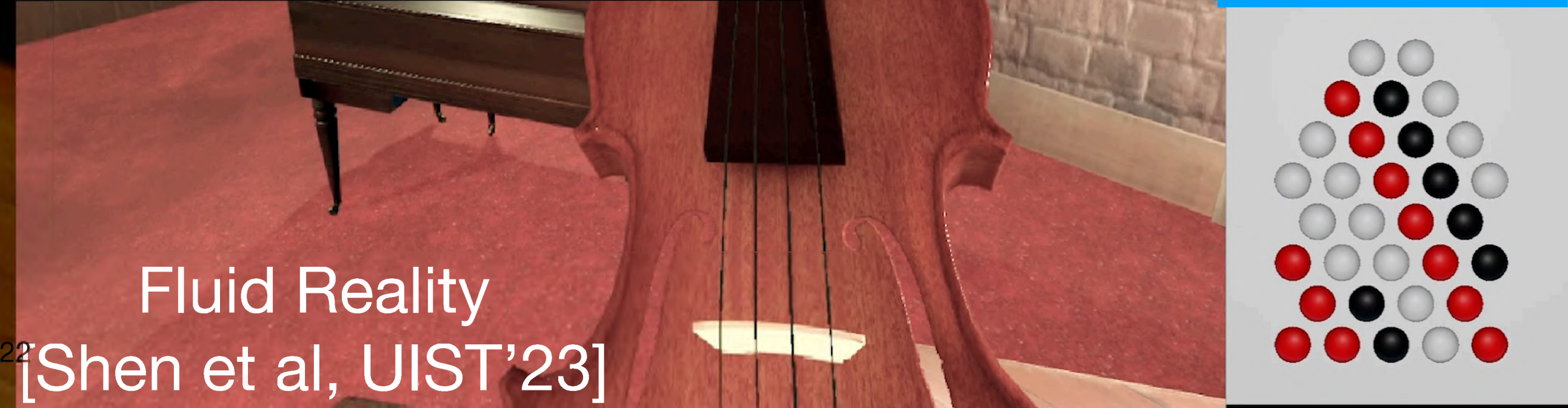
Communication information



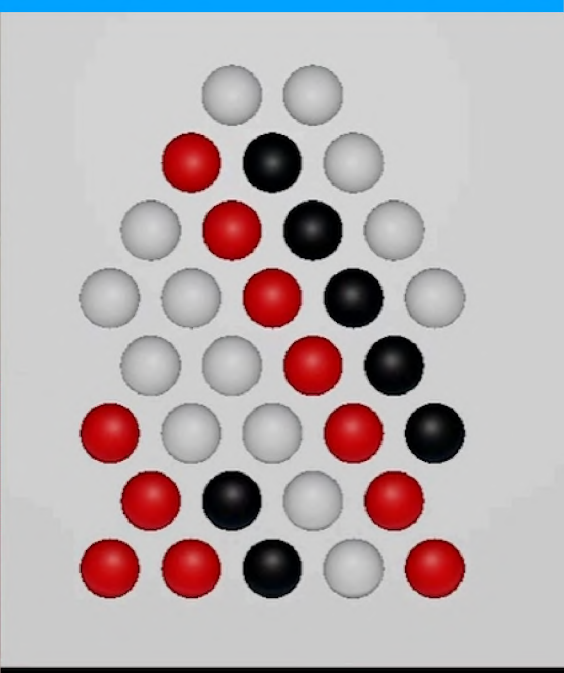
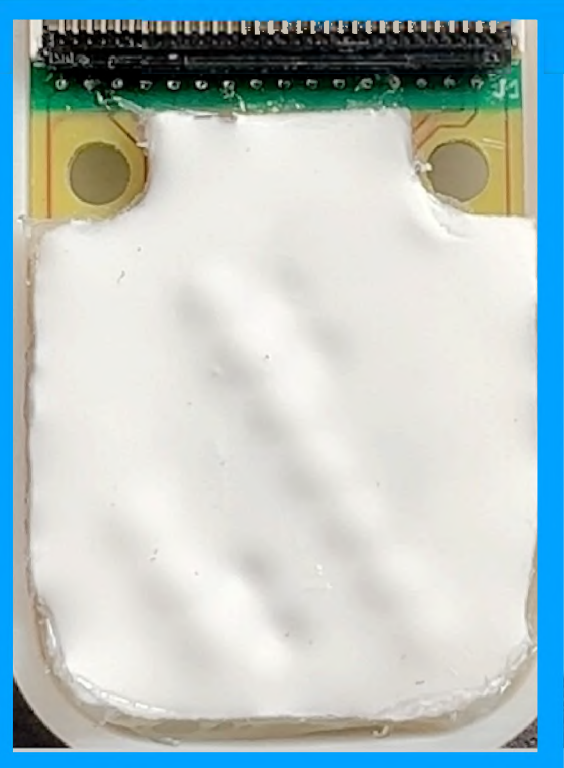
MorpheesPlug
[Hyunyoung et al, CHI'21]



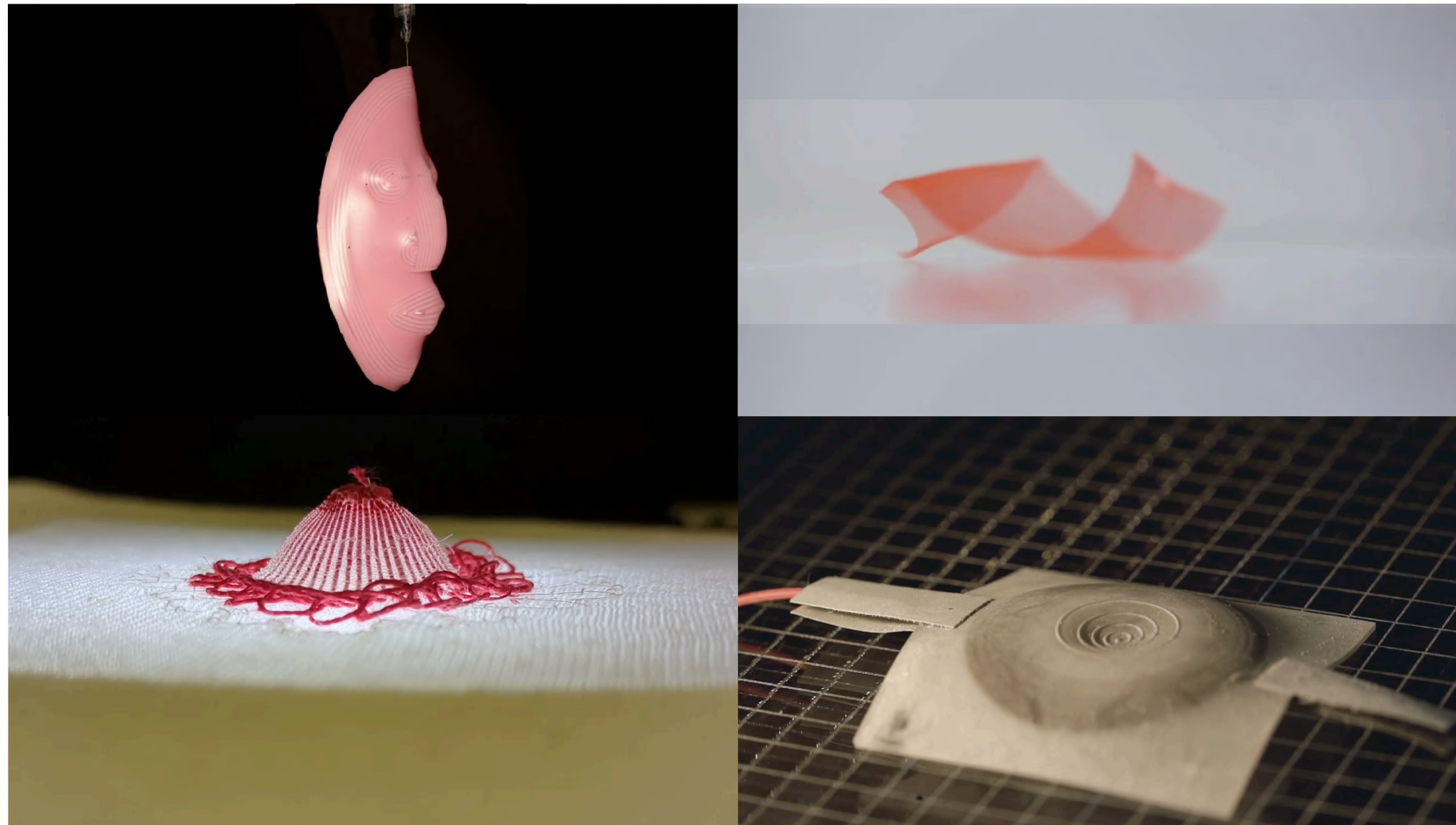
Simulate objects



Fluid Reality
[Shen et al, UIST'23]



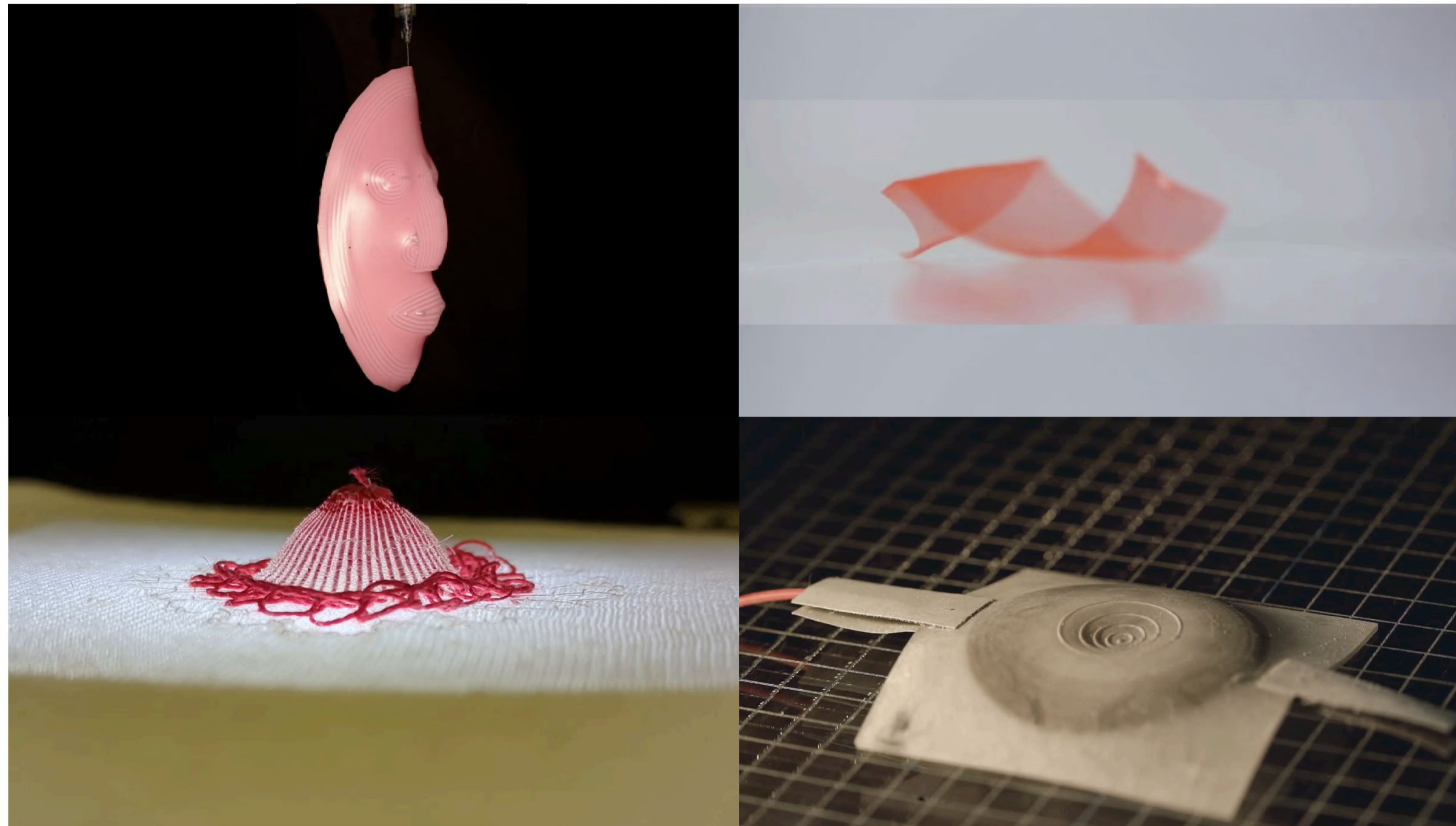
Programmable soft materials



Shape-changing UIs



Programmable soft materials



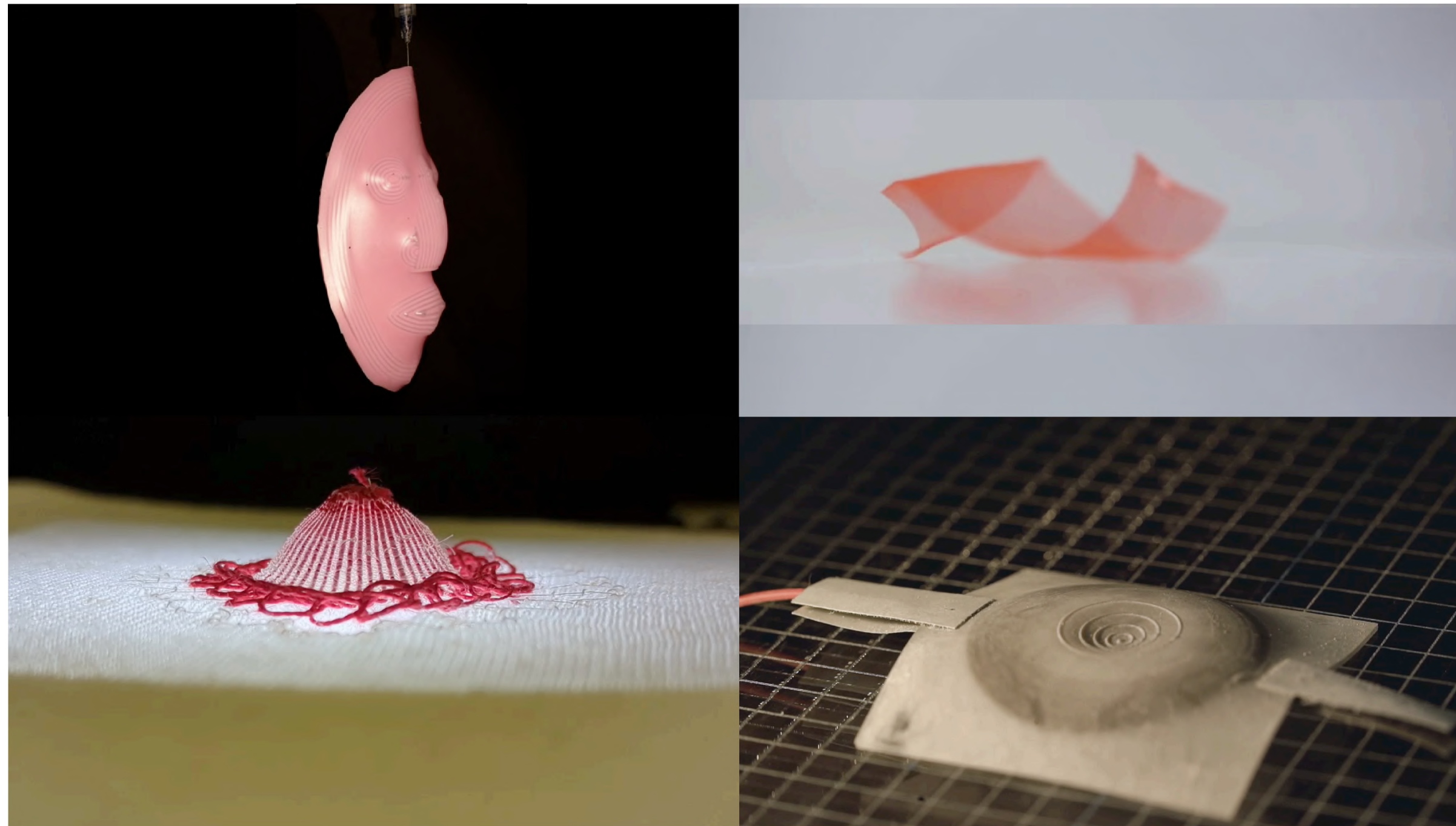
Shape-changing UIs

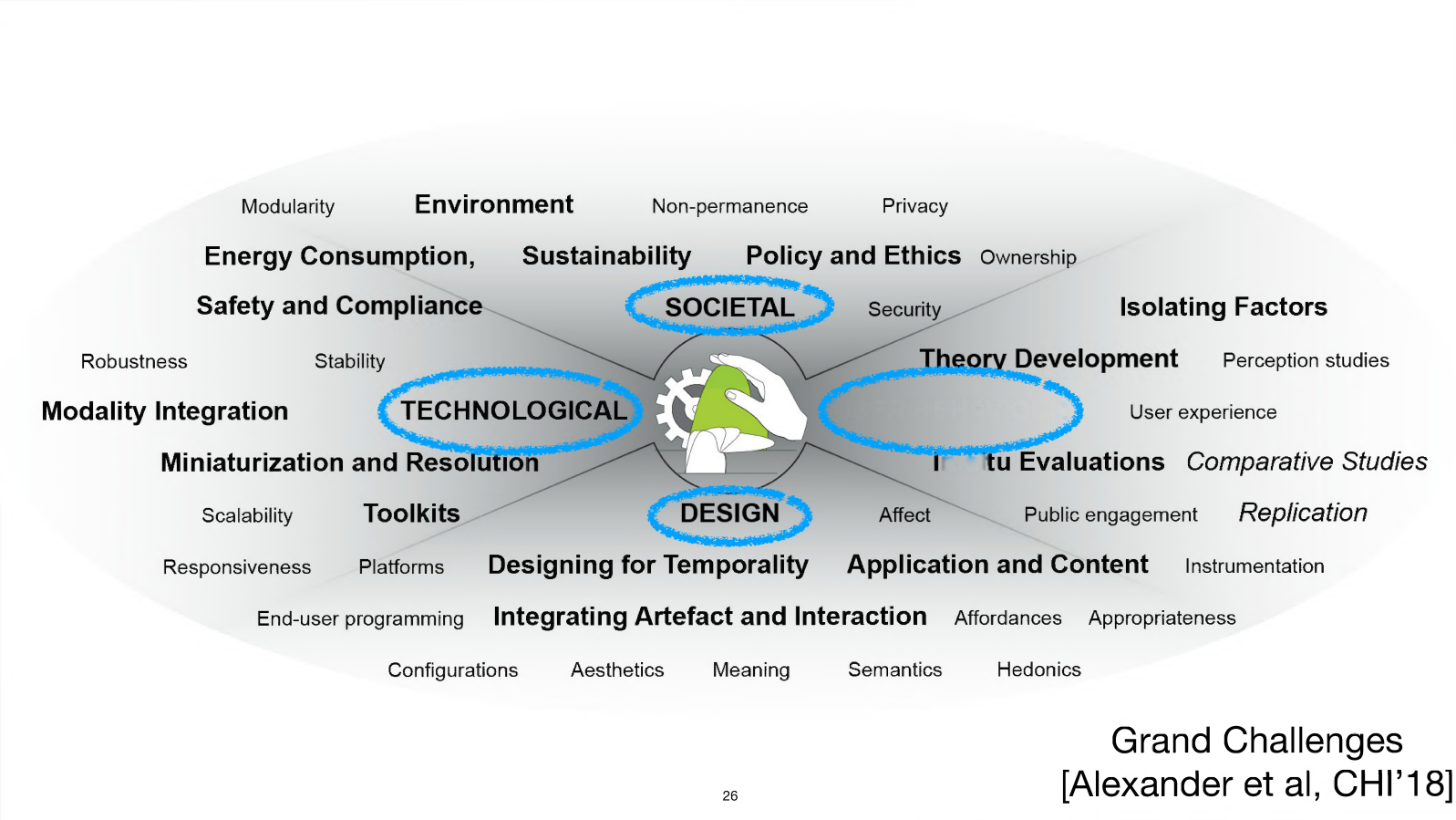


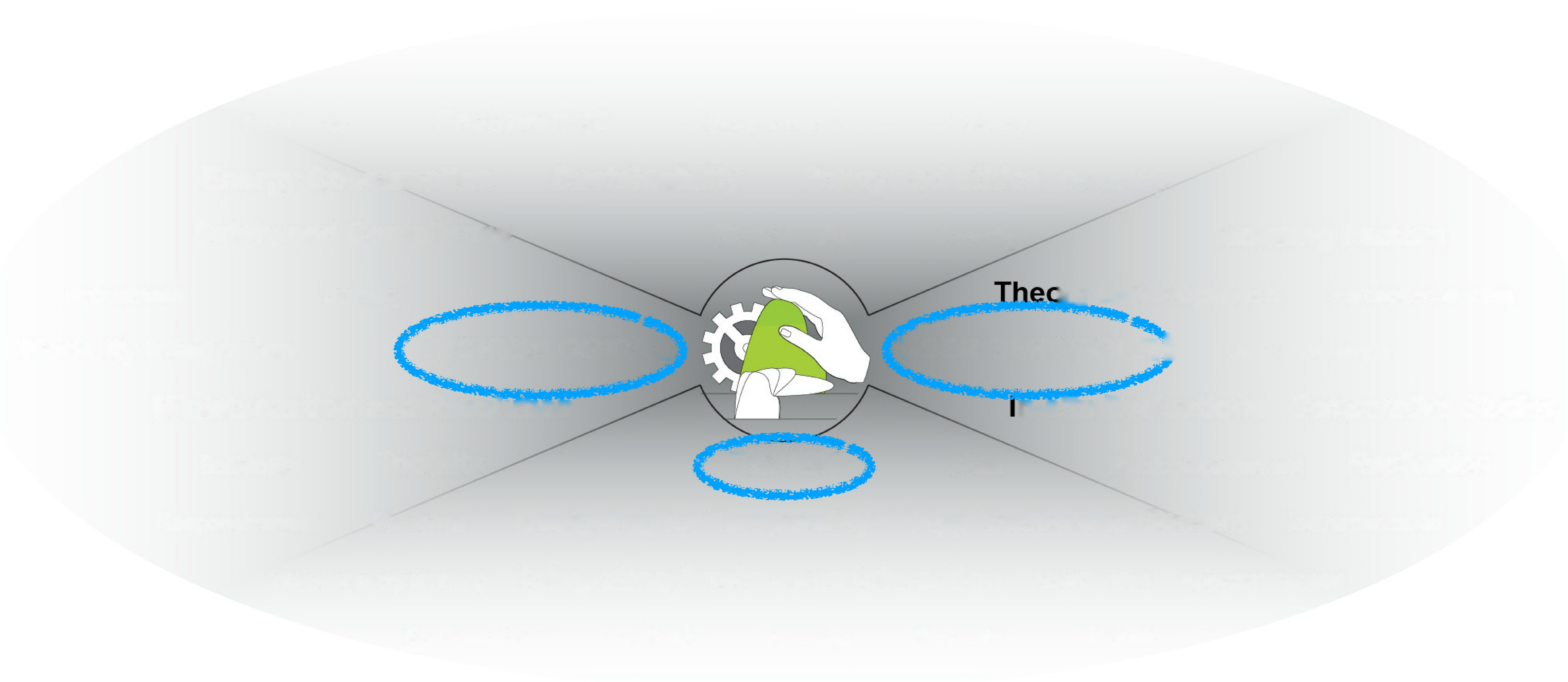
Challenges

Programmable soft materials

Shape-changing UIs



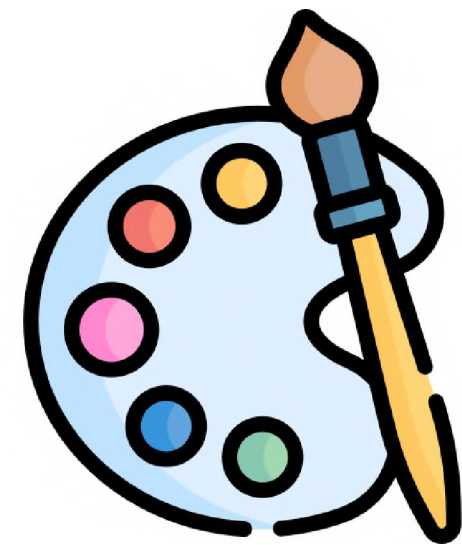




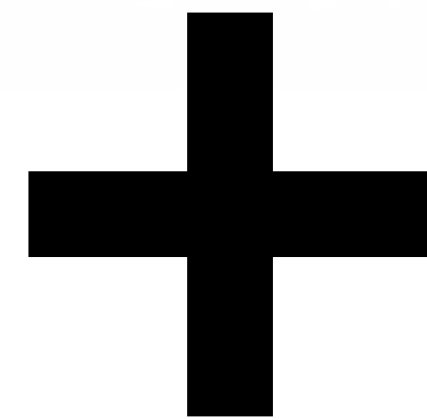


Developing shape-changing surfaces

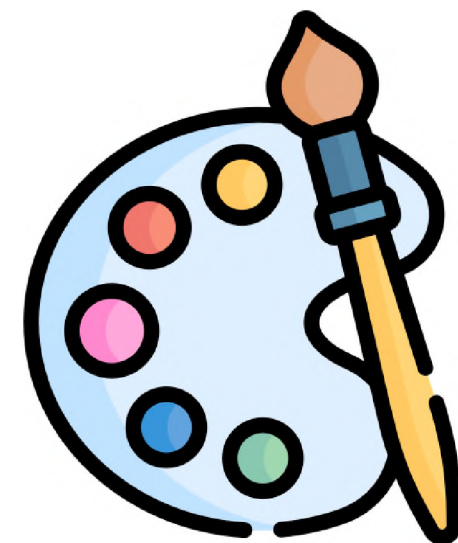
Other interaction information beyond shapes?

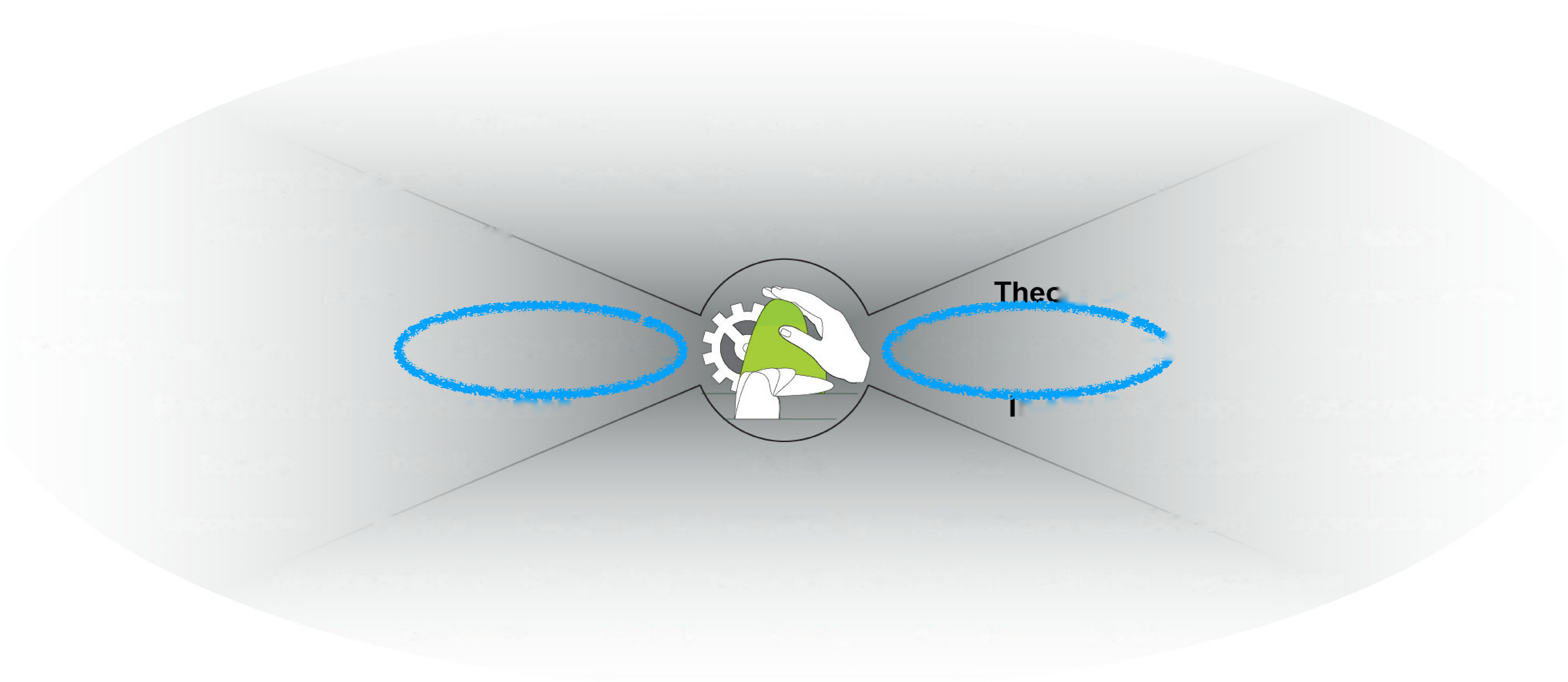


Developping shape-changing surfaces



Other interaction information beyond shapes?





Introduction

Technological explorations

User perception study

New device design

Interaction beyond shapes

Challenges and future work



Technological explorations

User perception study

New device design

Interaction beyond shapes

Challenges and future work

Technological explorations



User perception study

New device design

Interaction beyond shapes

Challenges and future work

Technological explorations

Programmable soft **materials**
for **different shape-changing** UIs

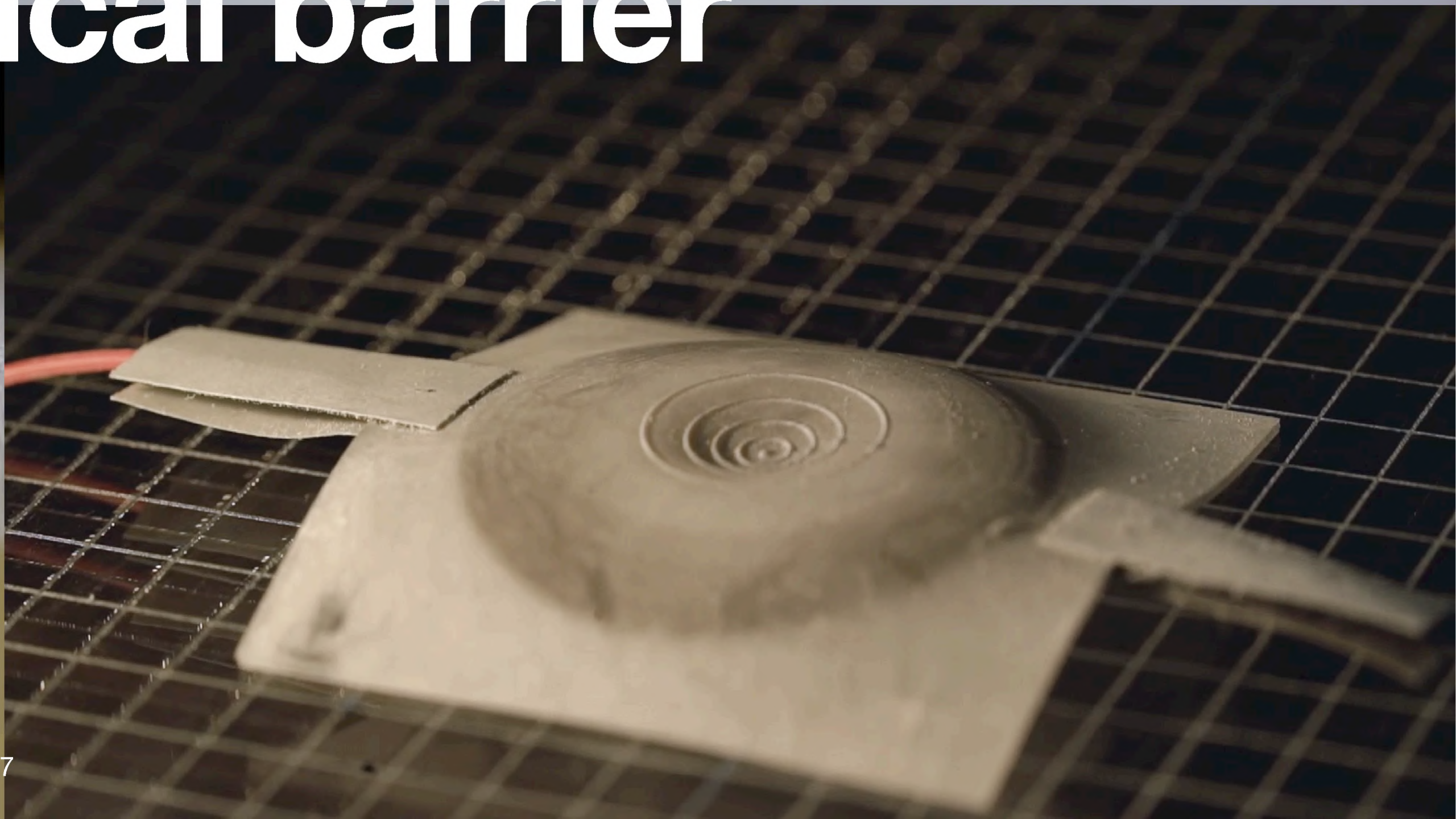
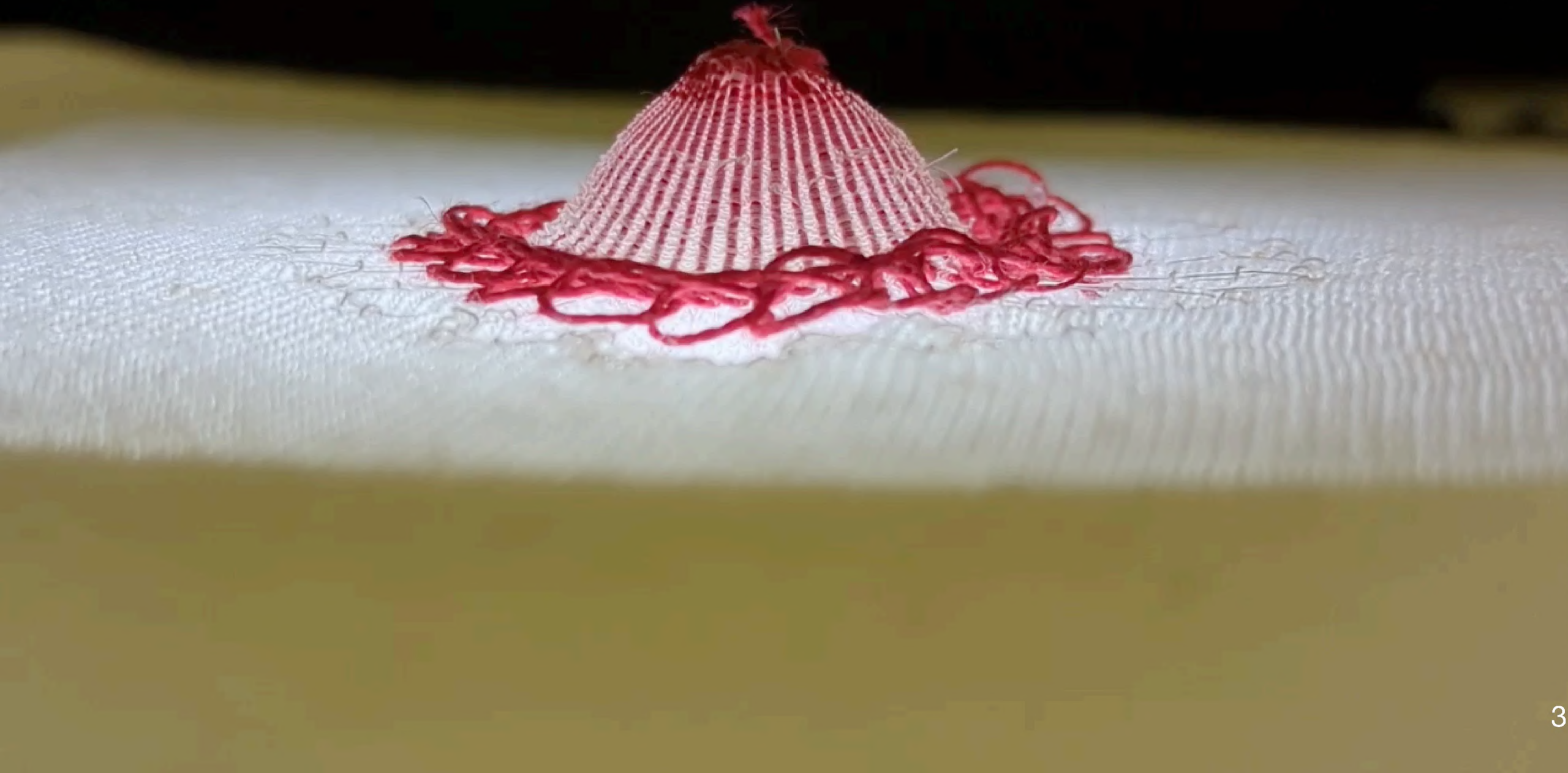
Novel technology **addressing limits** of
current programmable soft **materials**

Proof of concept prototypes

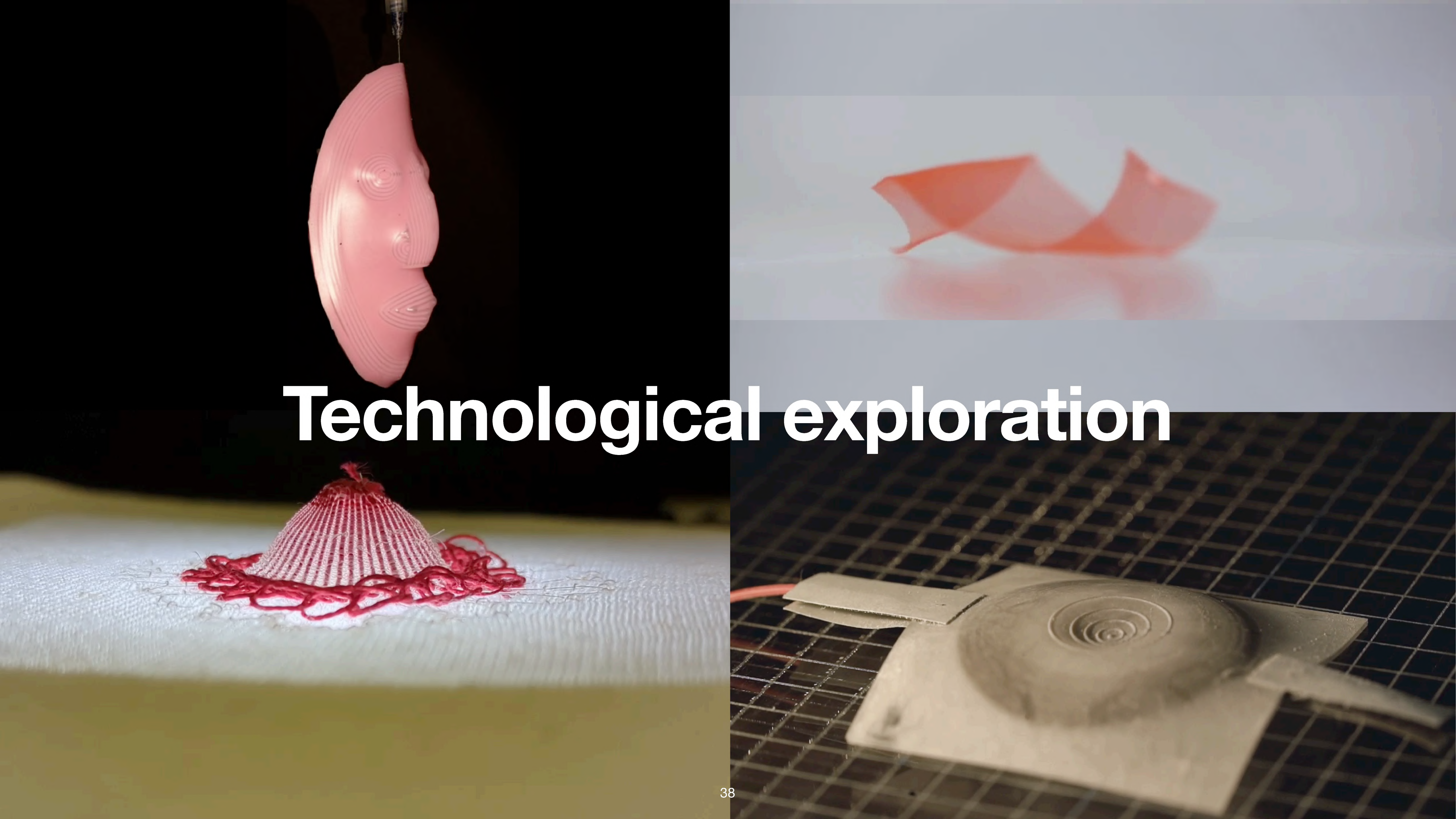




Technological barrier



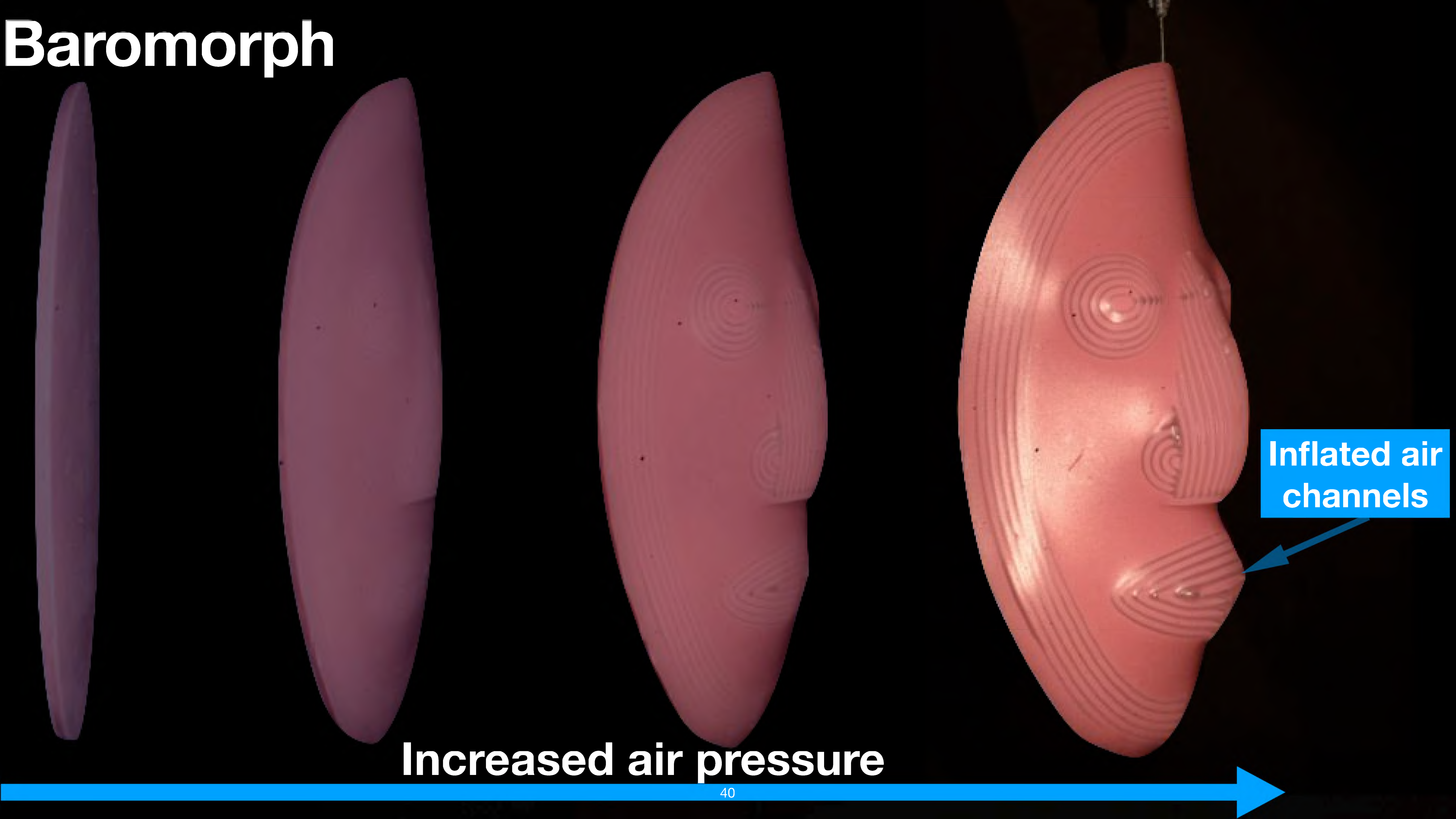
Technological exploration





Baromorph
[Siéfert et al, Nature Materials 2019]

Baromorph



Increased air pressure

Inflated air
channels

Advantages

Soft

Safe

Rapid actuation

High shape-changing potential

Advantages

Soft

Safe

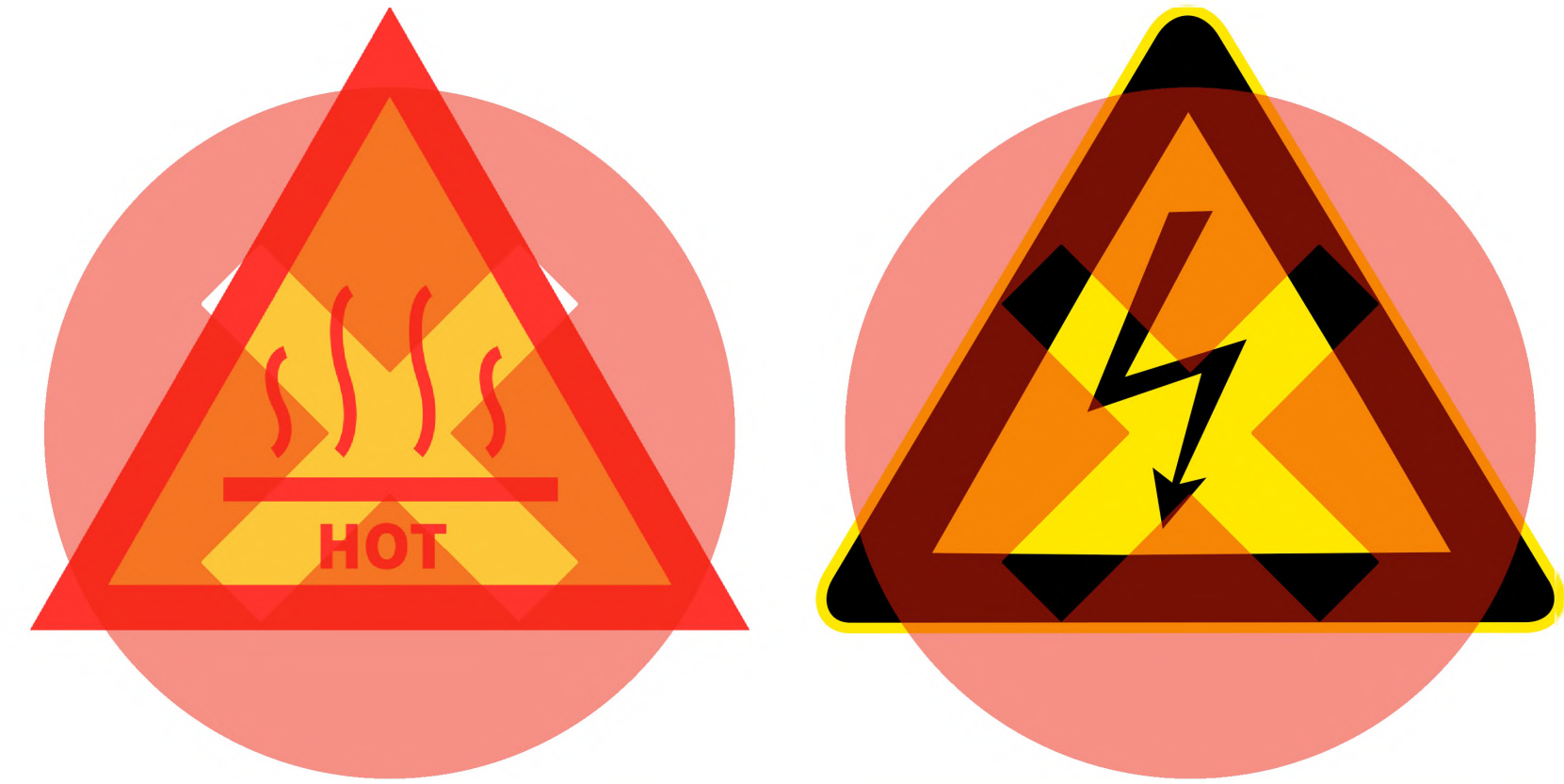
Rapid actuation

High shape-changing potential



Advantages

Soft



Rapid actuation

High shape-changing potential

Advantages

Soft

Safe



Rapid actuation

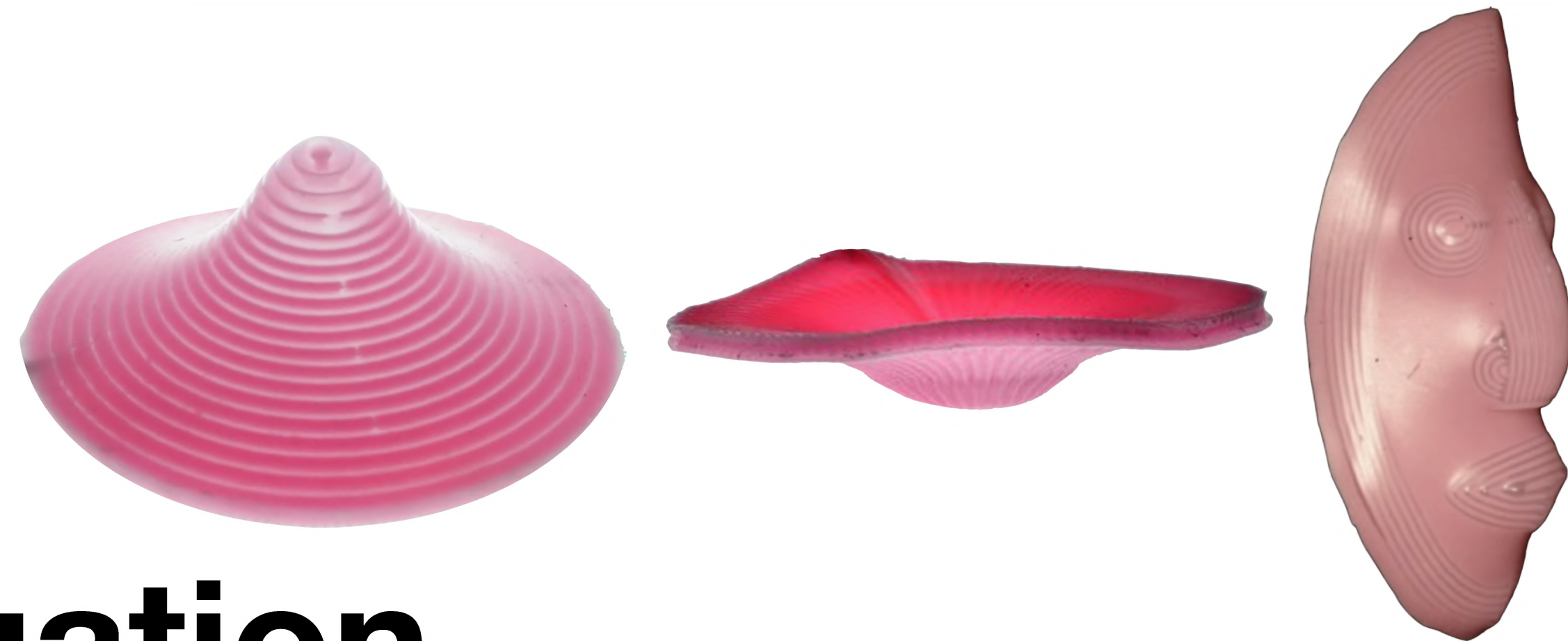
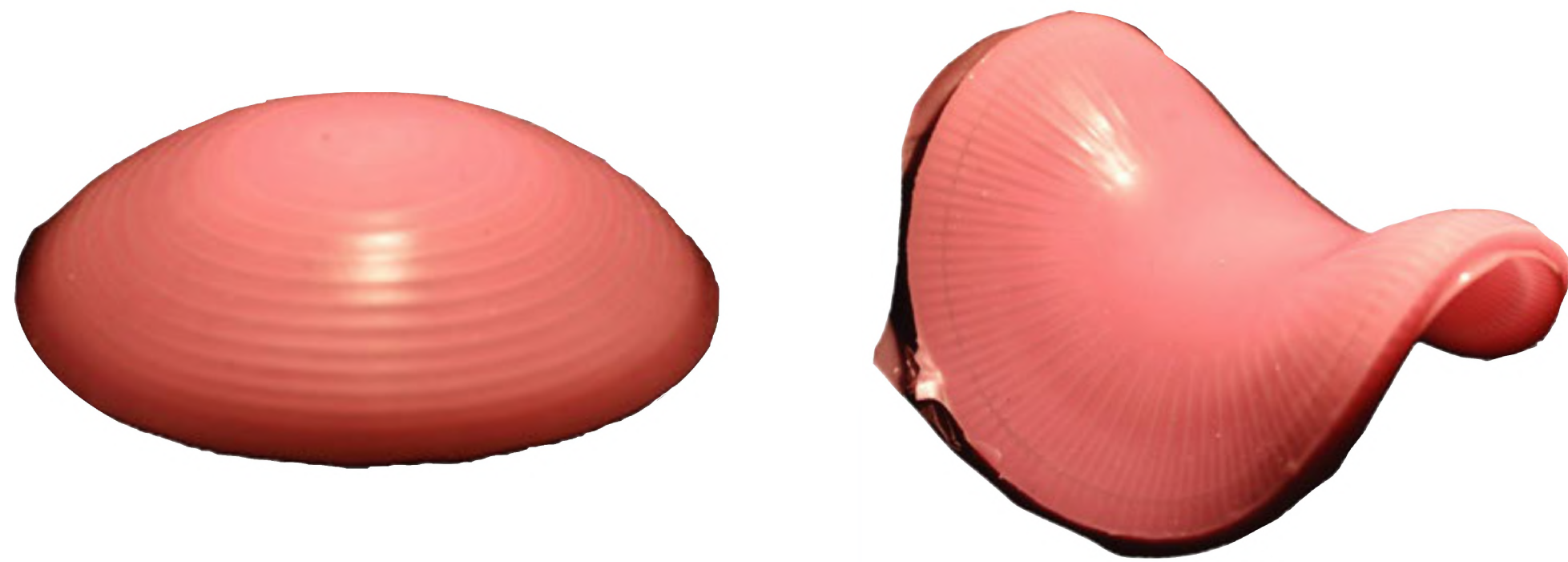
High shape-changing potential

Advantages

Soft

Safe

Rapid actuation

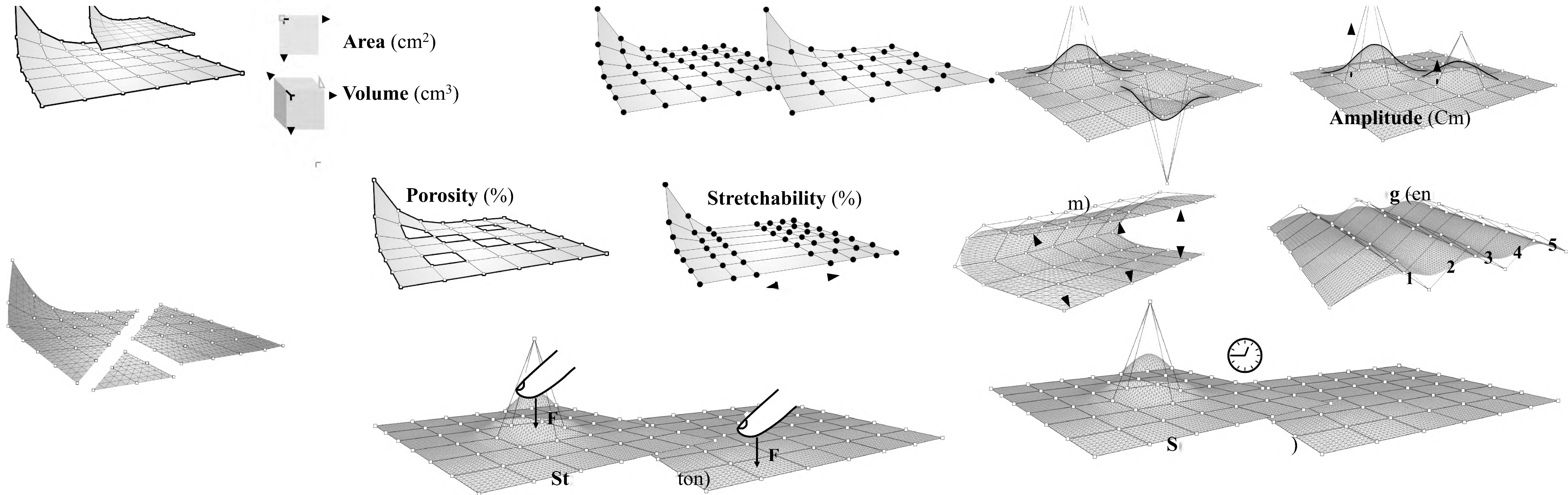


High shape-changing potential



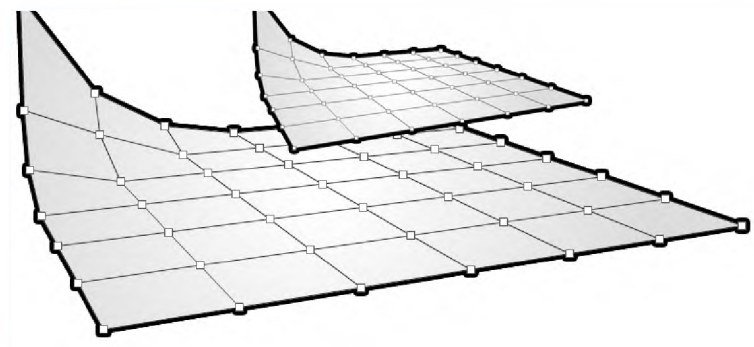
What shape-changes?

Uls' different shape-changes



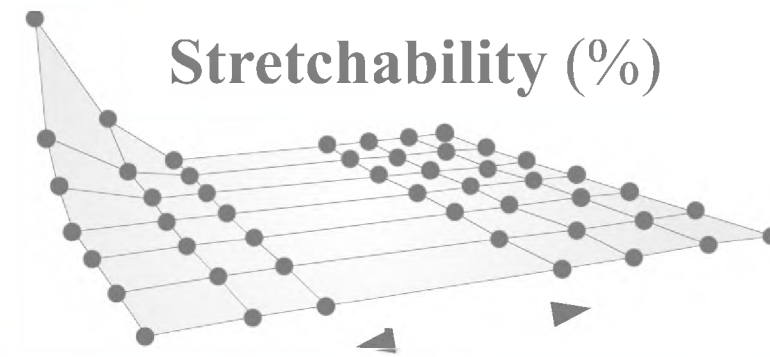
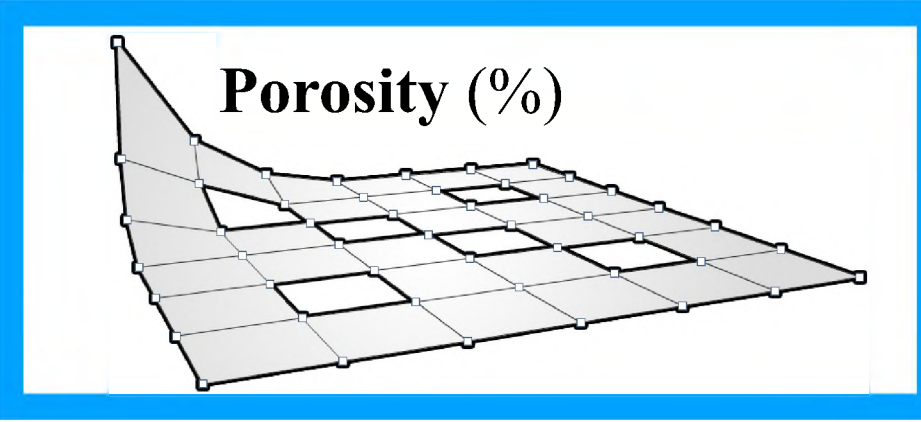
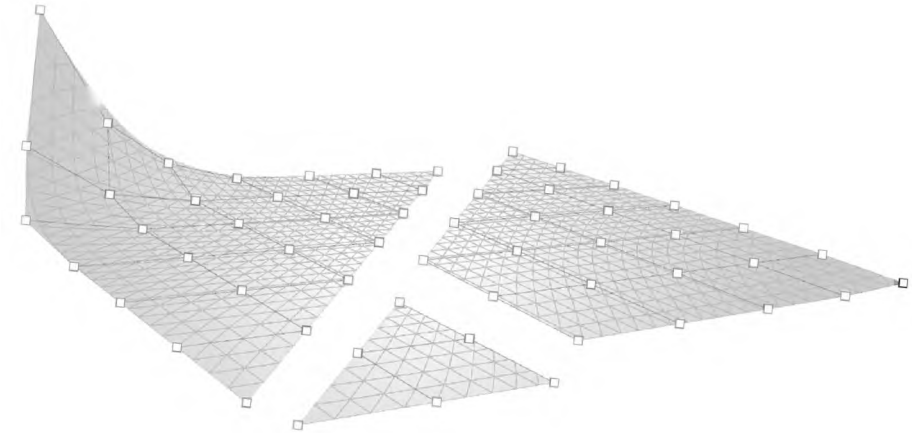
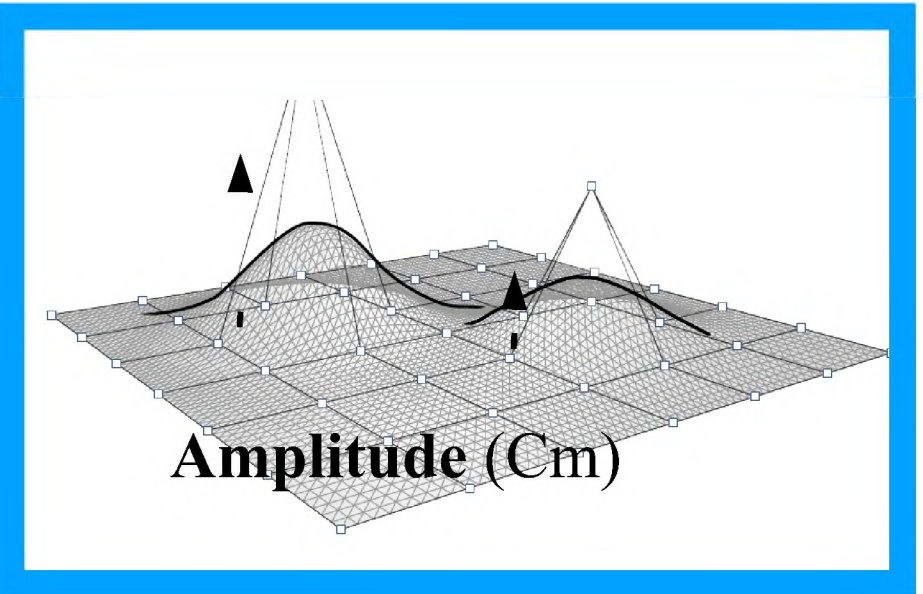
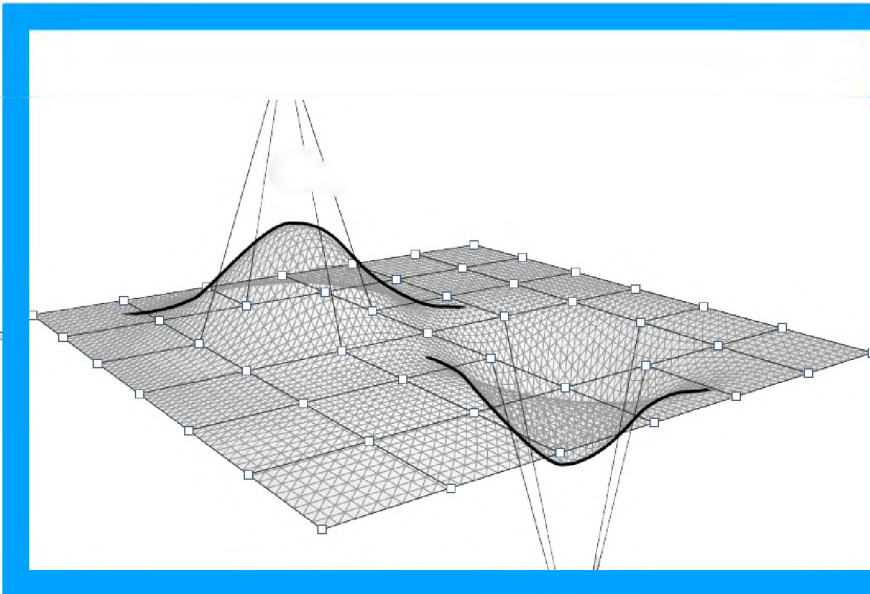
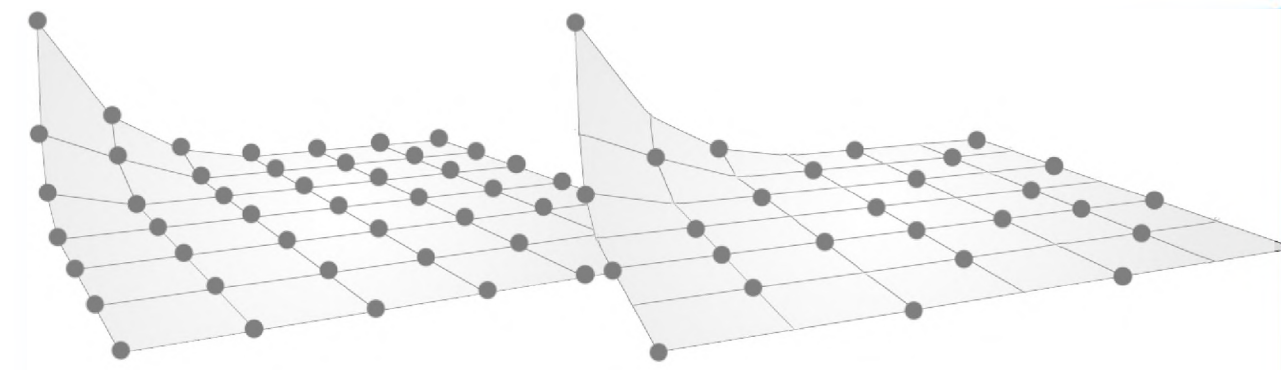
Morphees+
[Kim et al, CHI'18]

SoftMorphees

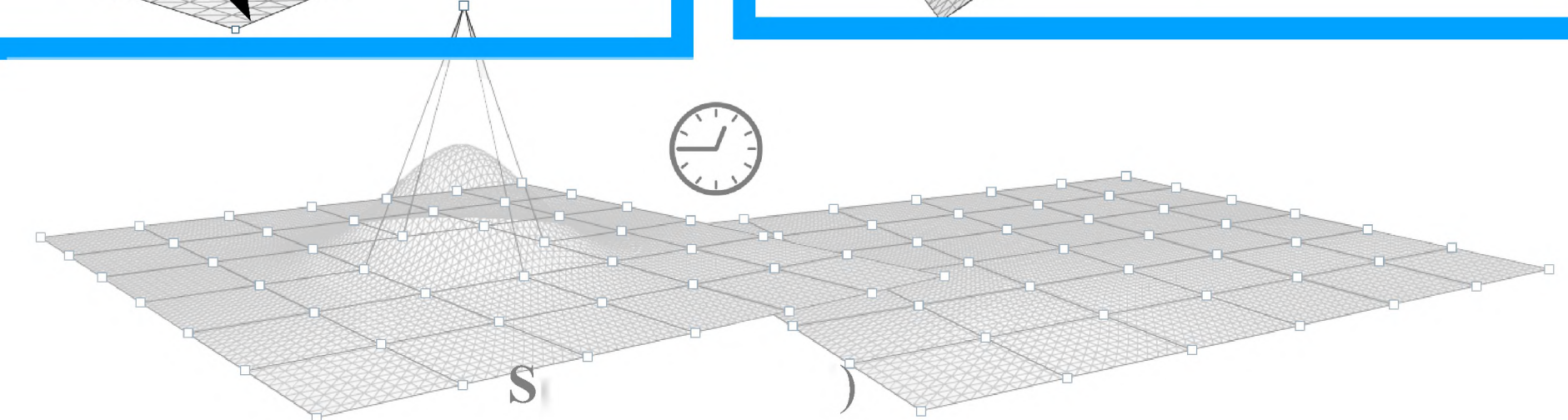
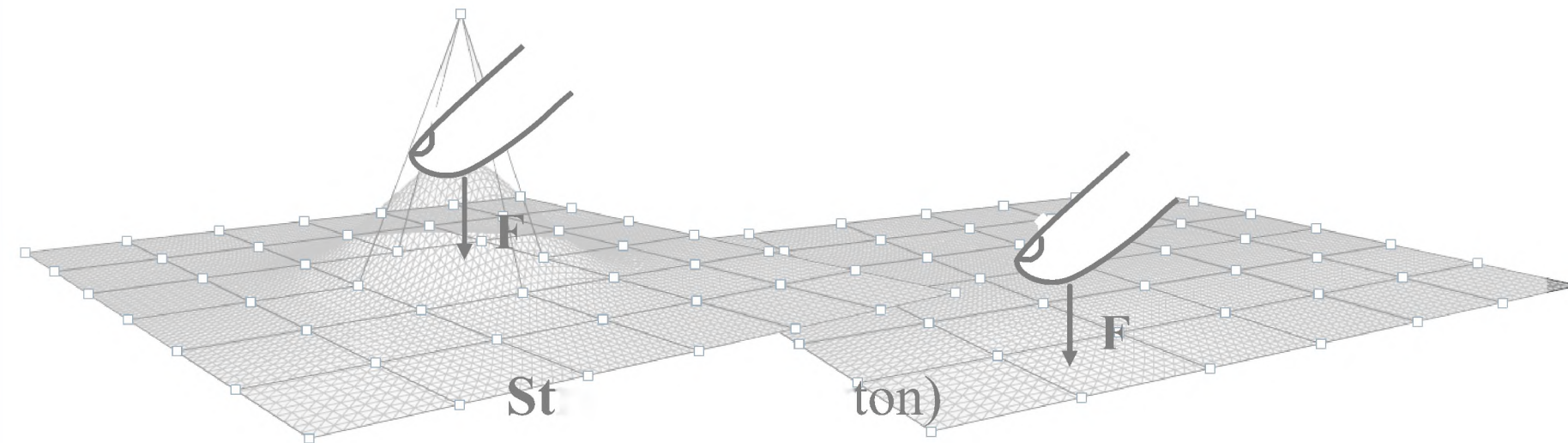
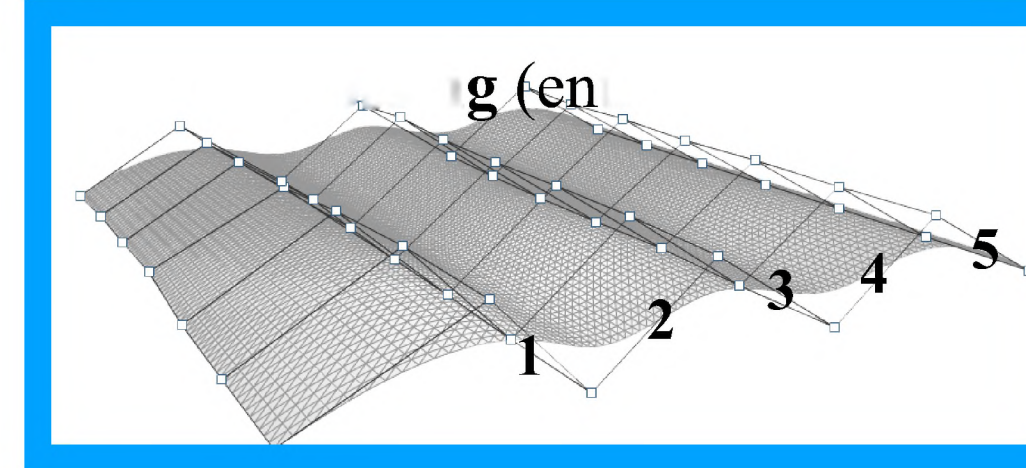
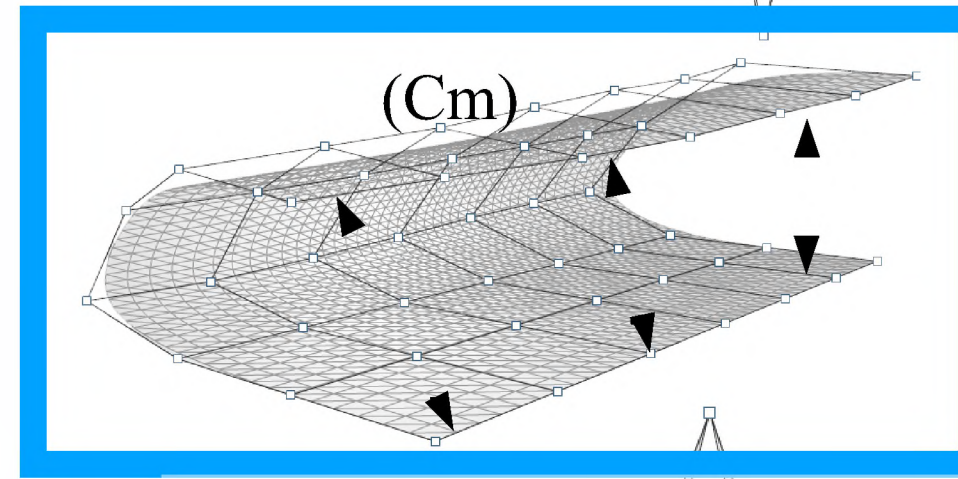


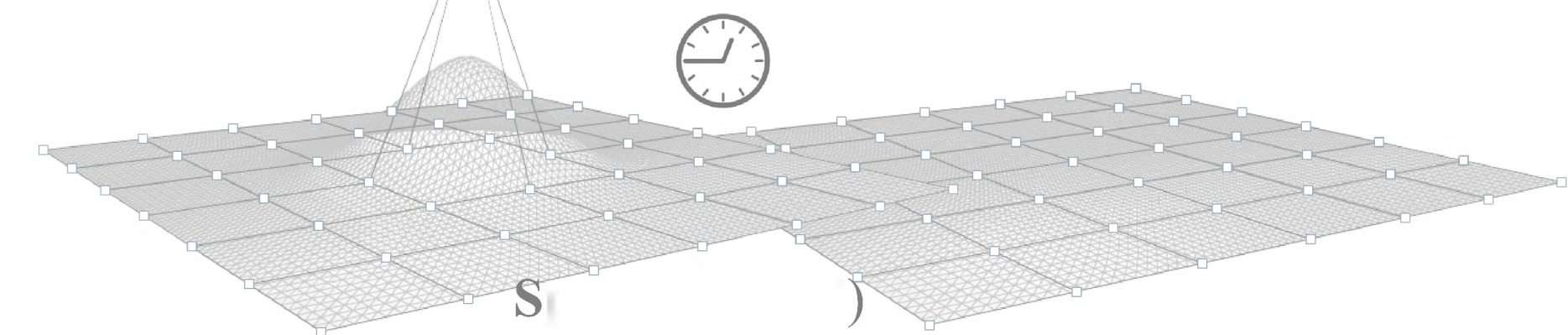
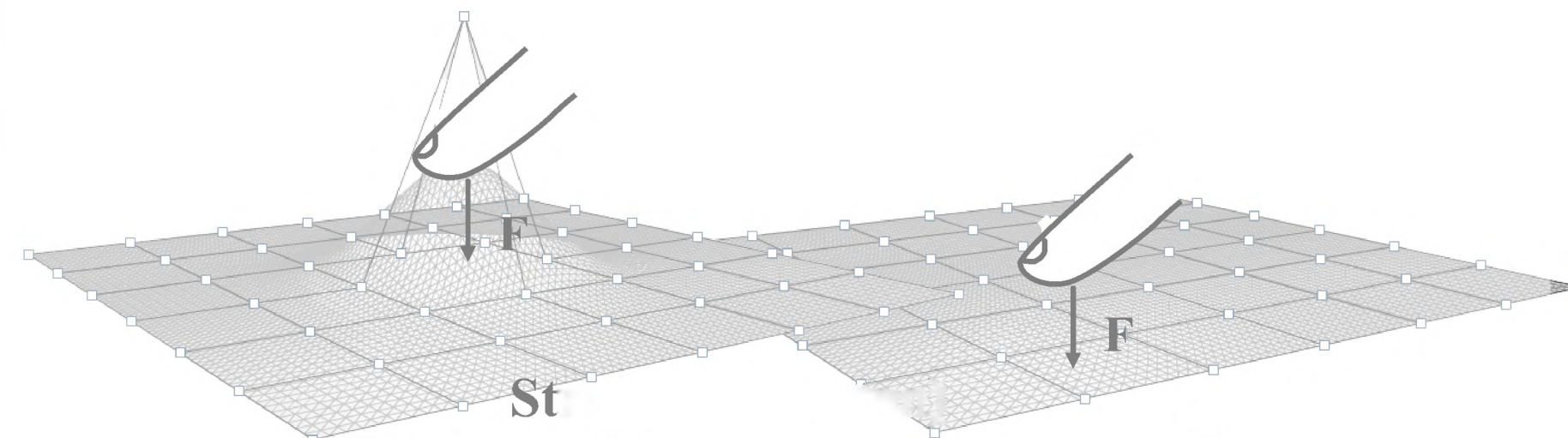
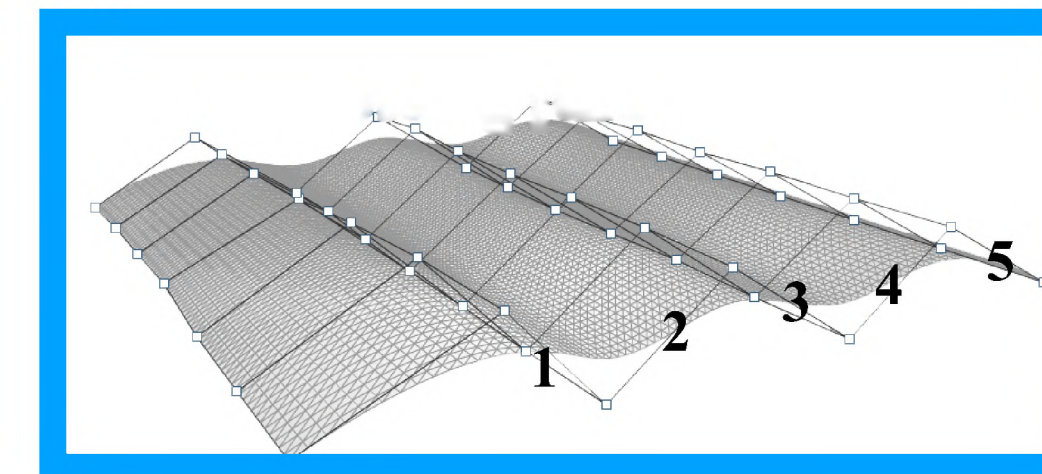
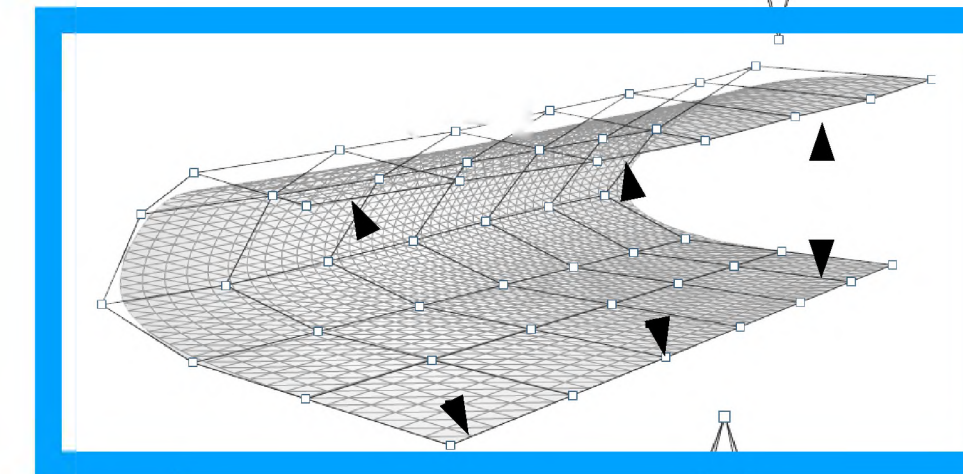
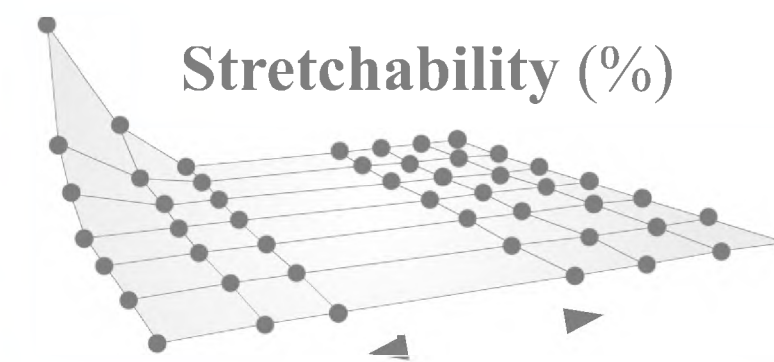
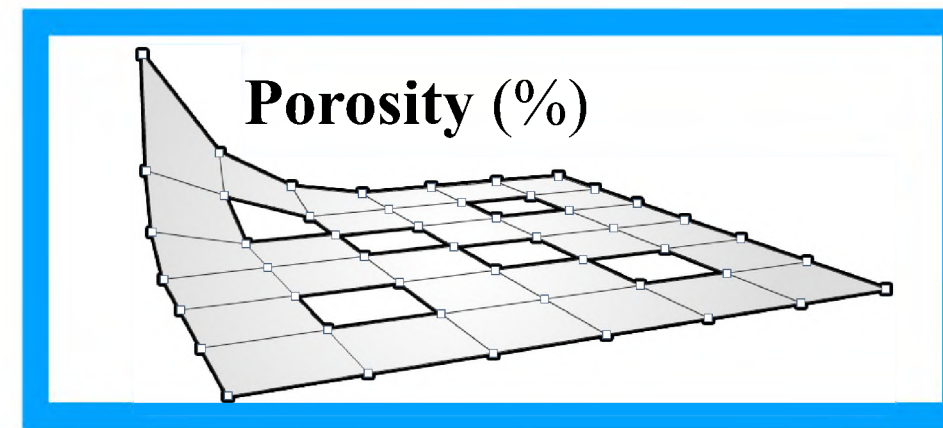
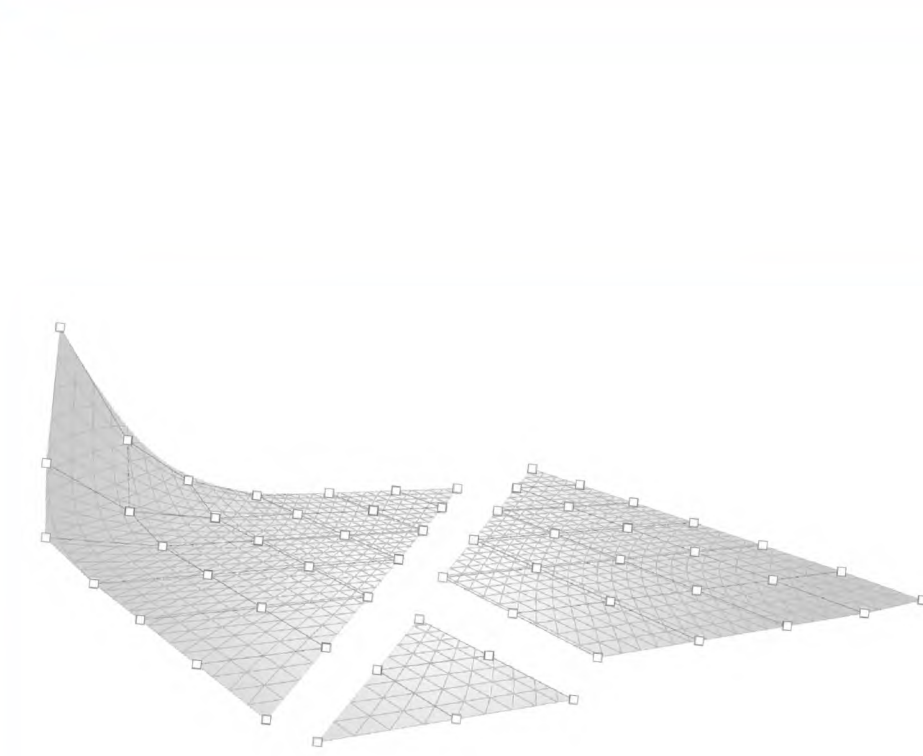
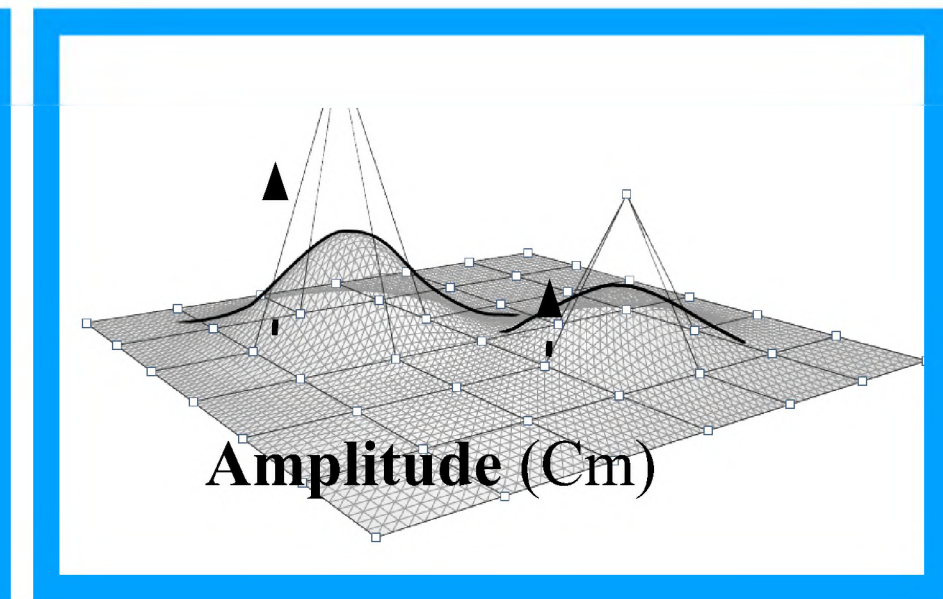
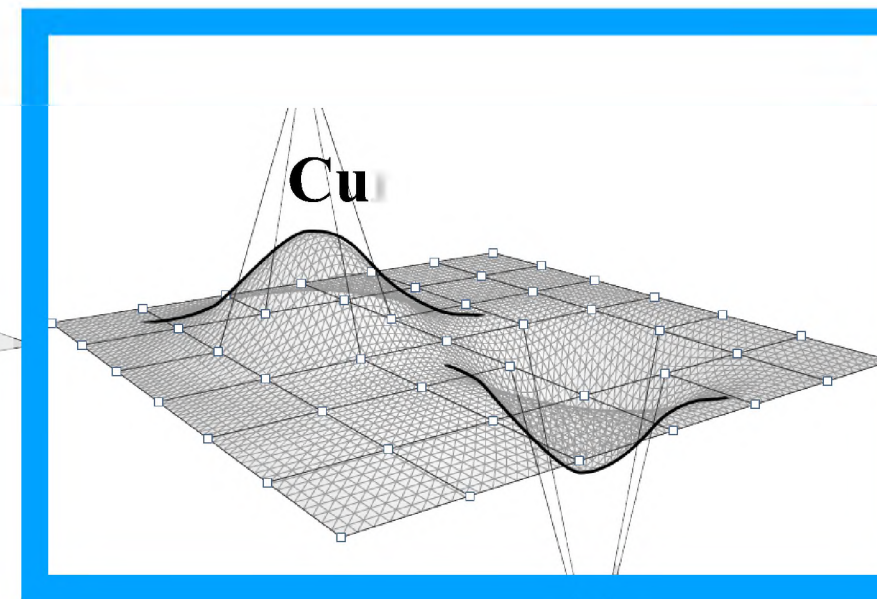
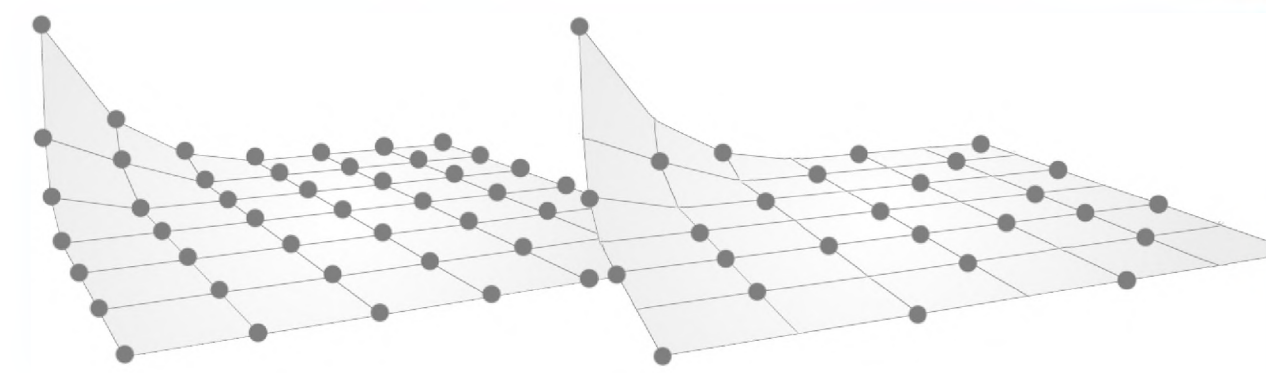
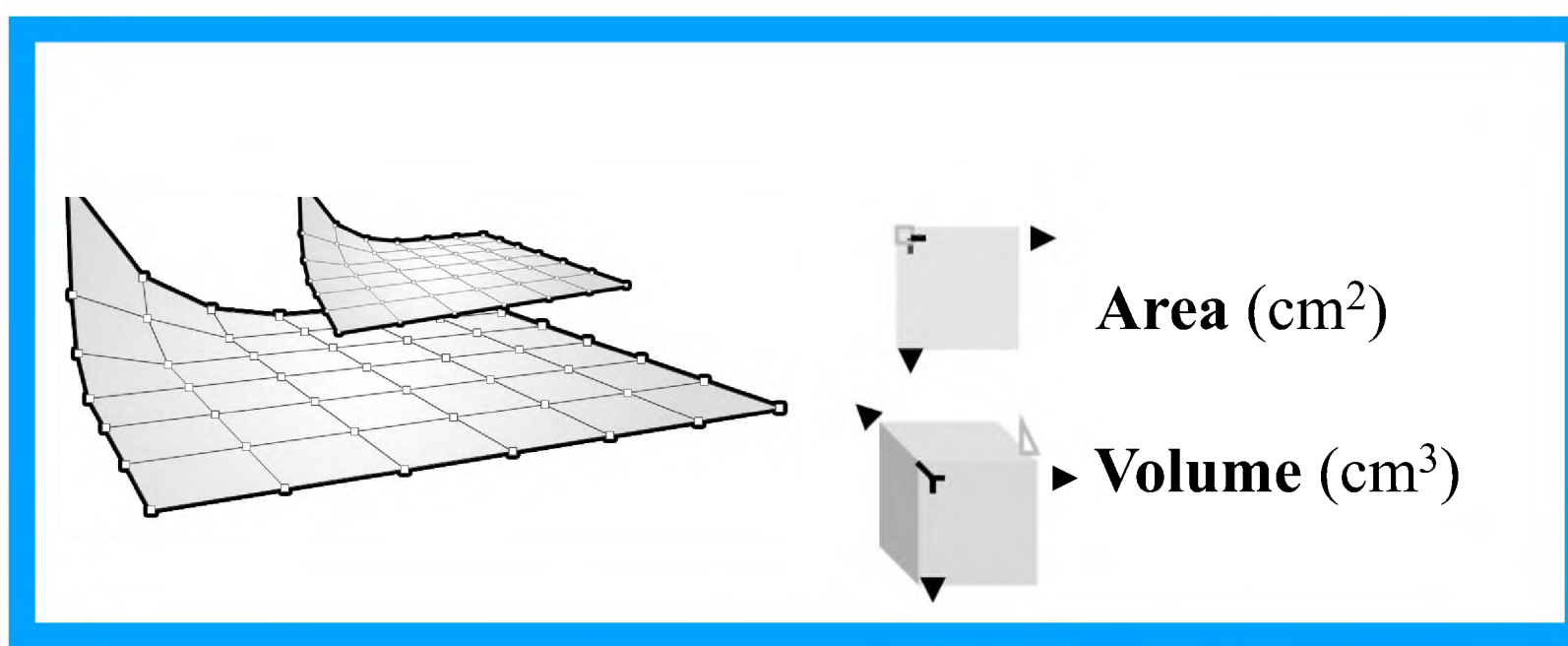
Area (cm²)

Volume (cm³)



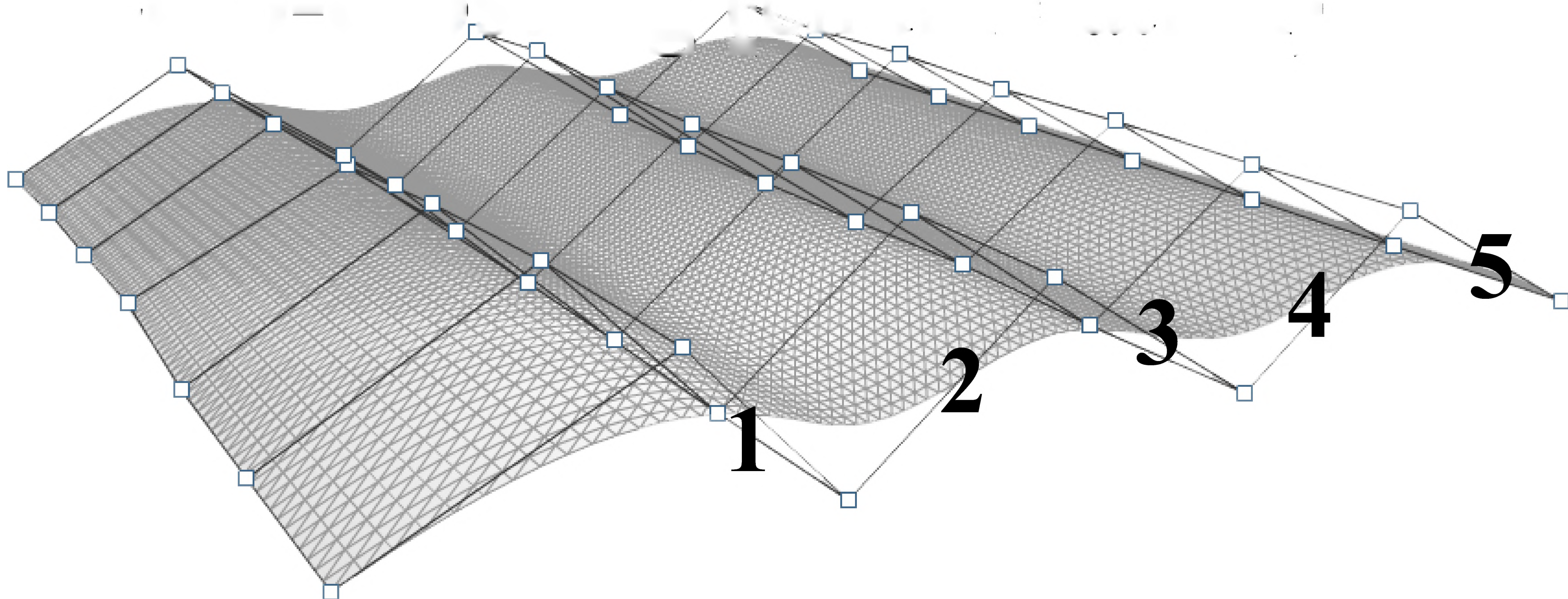
Stretchability (%)



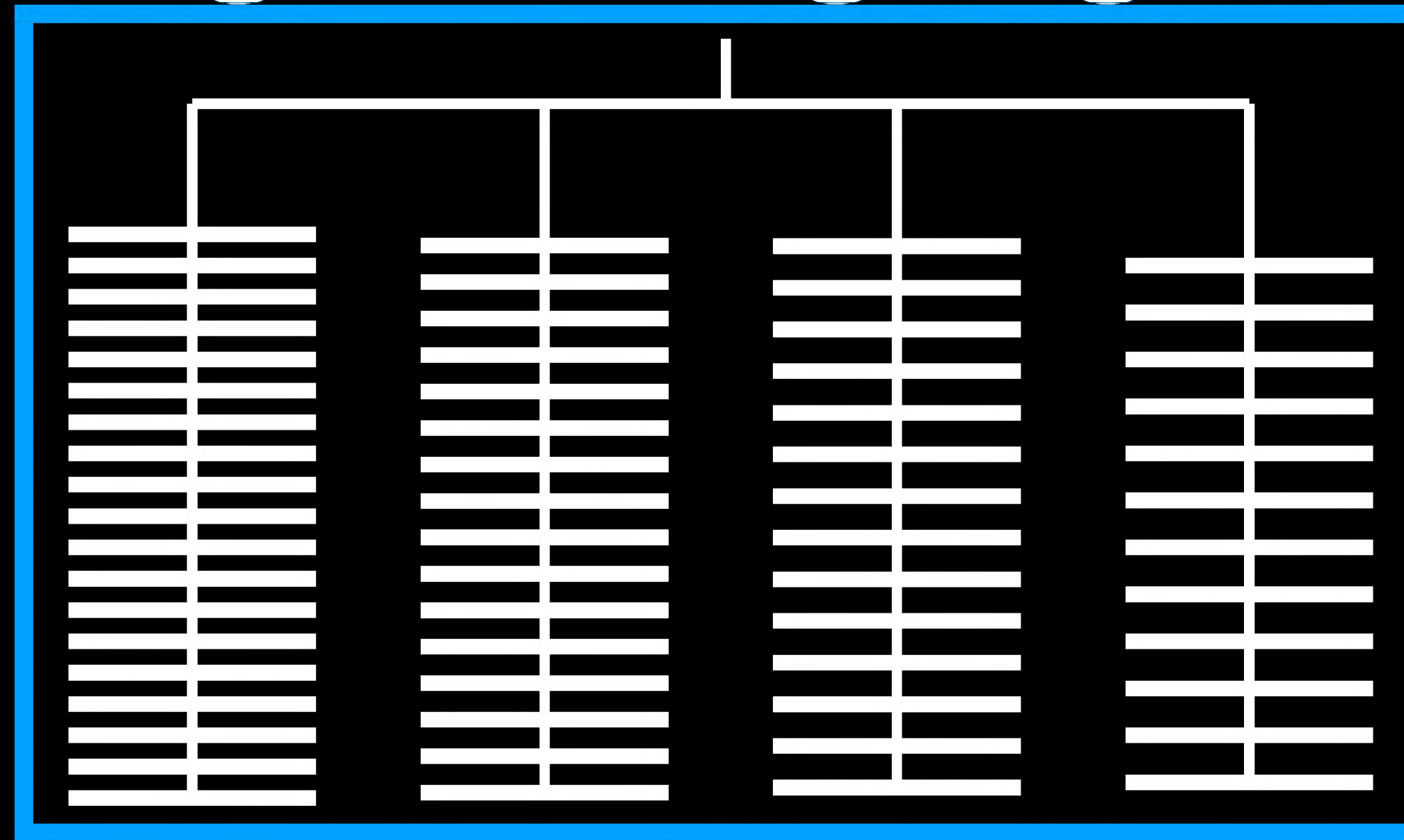


Only technology

to create all these six shape-changing features using soft materials



Zero-crossing changing module



10mm



Zero-crossing changing module

0 Psi

Side view:



Zero-crossing: 0

10mm

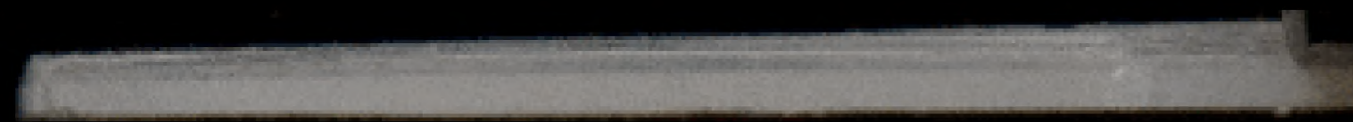
Above view:



Zero-crossing changing module

0 Psi

Side view:

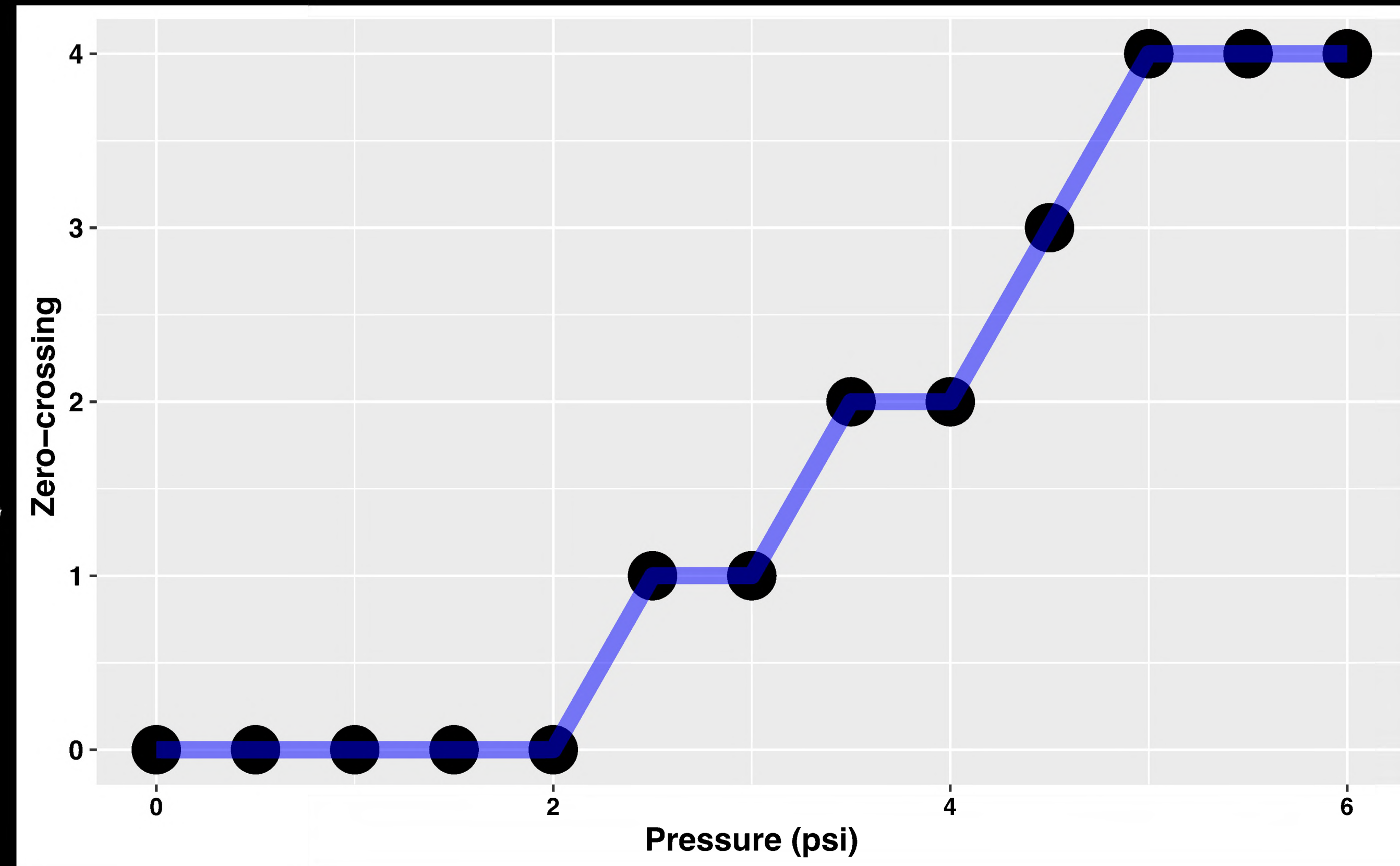


Zero-crossing: 0

10mm



Above view:



SoftMorphees



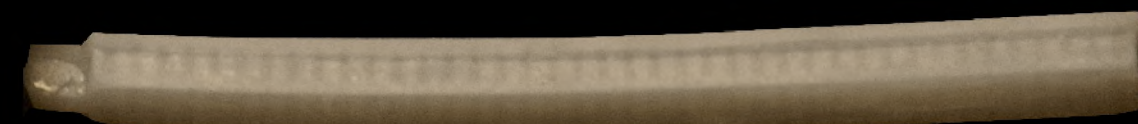
Size



Porosity



Curvature



Closure



Amplitude



Zero-crossing

Technological explorations

Programmable soft **materials**

for **different shape-changing** UIs

Novel technology **addressing limits** of
current programmable soft **materials**

A significant **drawback** of **elastomers**,
particularly for **shape-change**,
is the **trade-off** between **stretchability** and **strength**.

HCI meets Material Science
[Qamar et al, CHI'18]

Stretchability-strength trade-off of elastomers



High stretchability

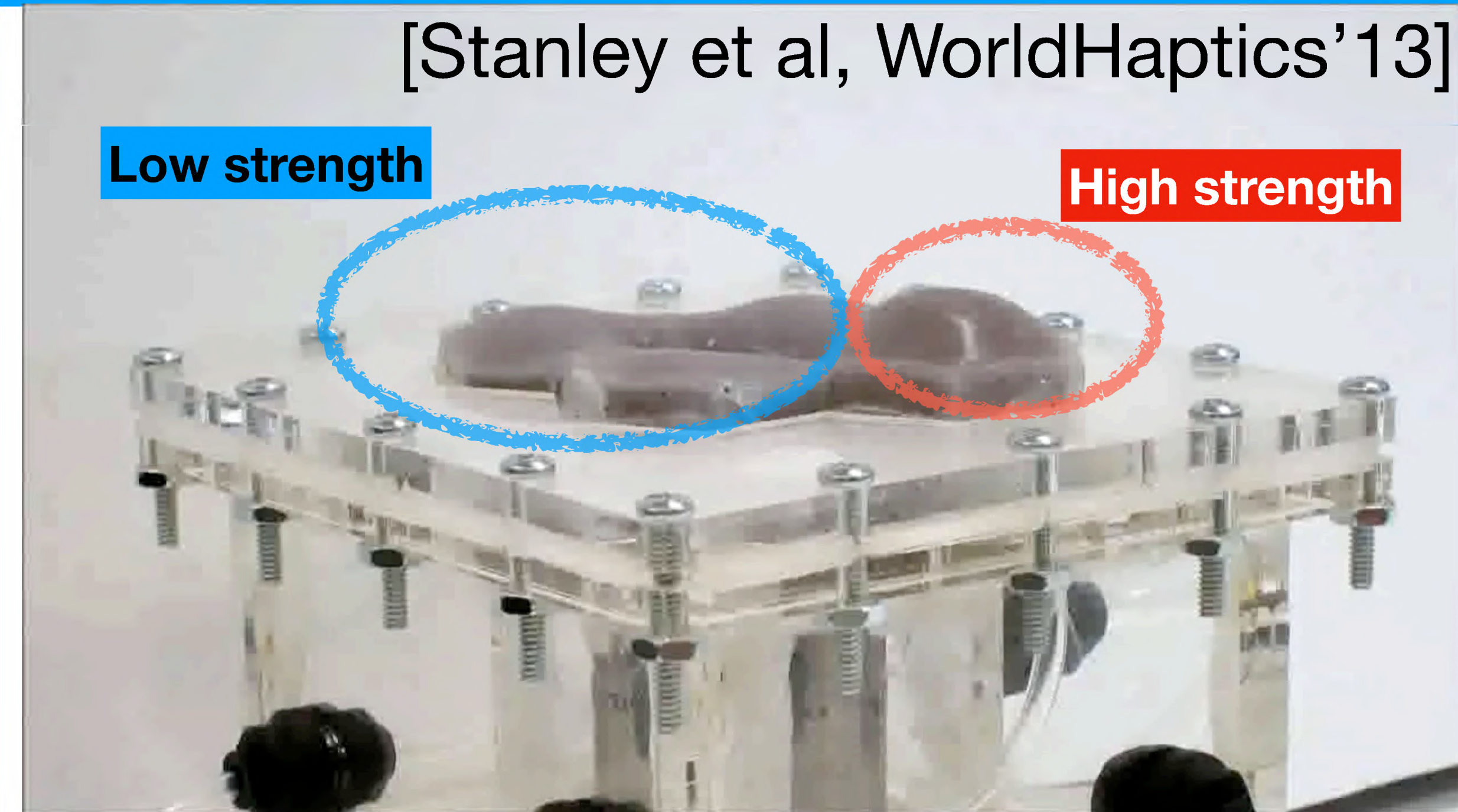


Low strength

Stretchability-strength trade-off of elastomers



High stretchability



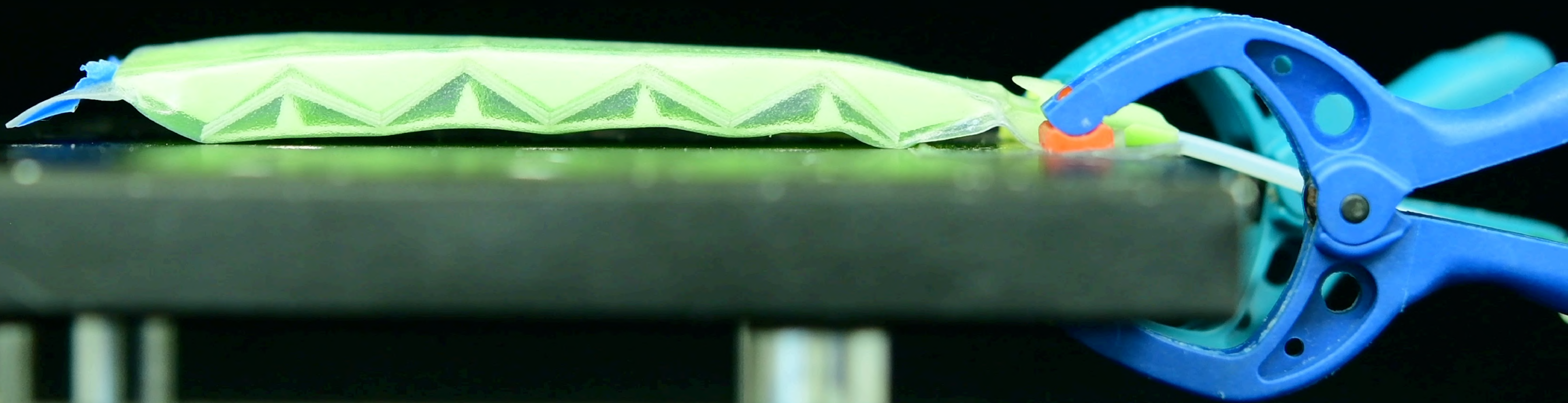
Low strength

**Enhance the strength
of UIs made of soft materials**

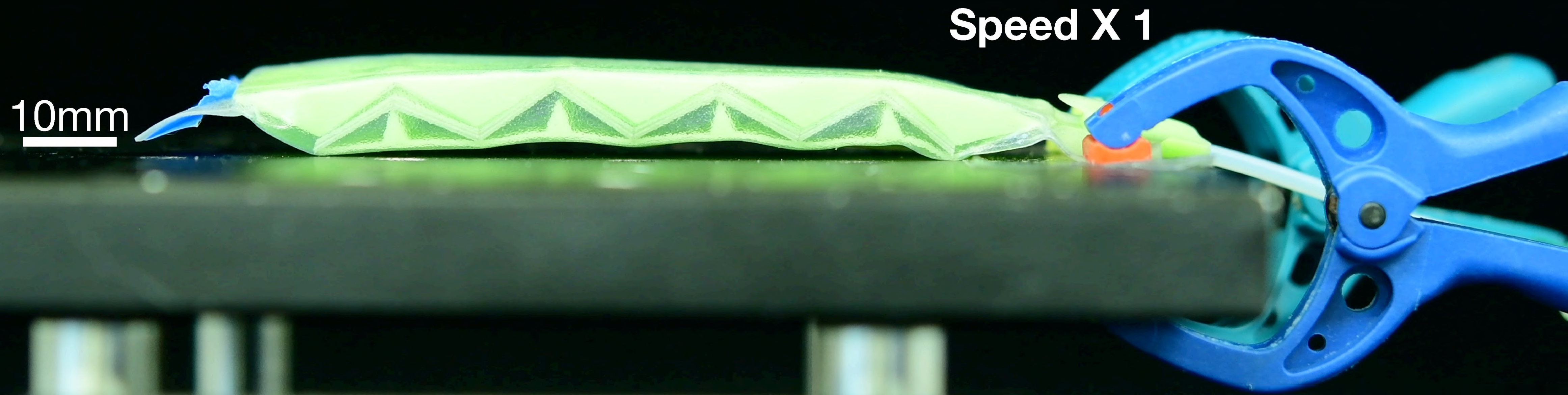
Jamming Origami Endoskeleton

Jamming Origami Endoskeleton

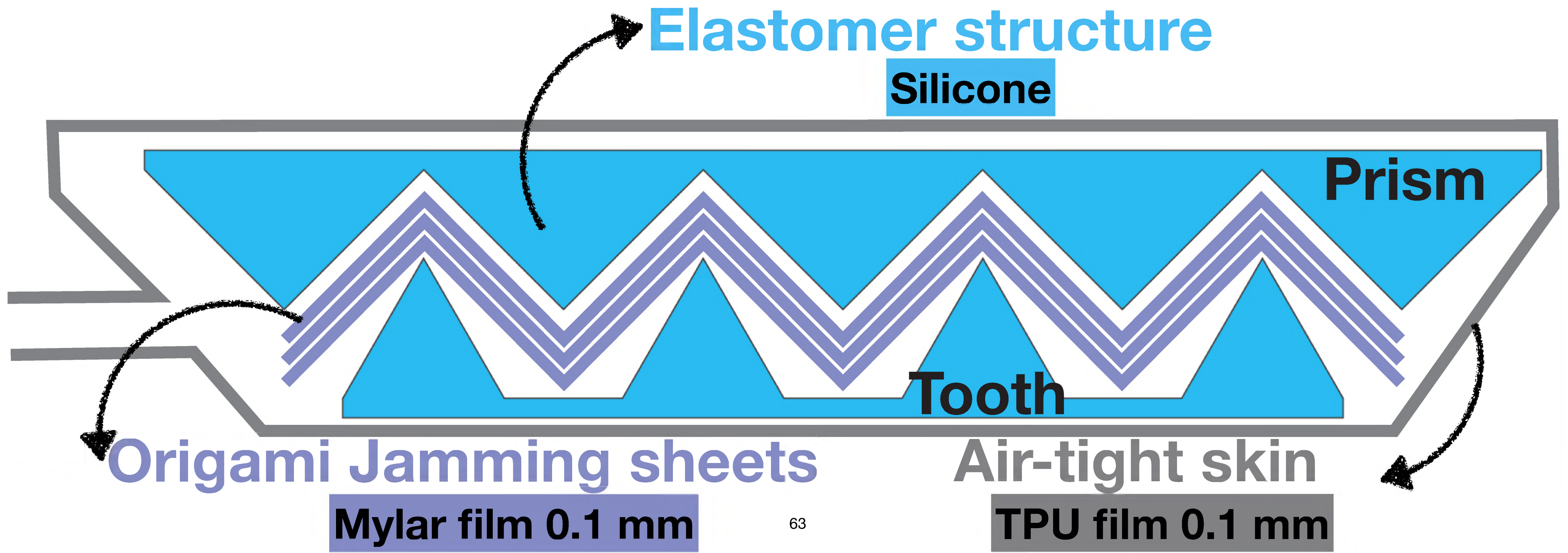
10mm



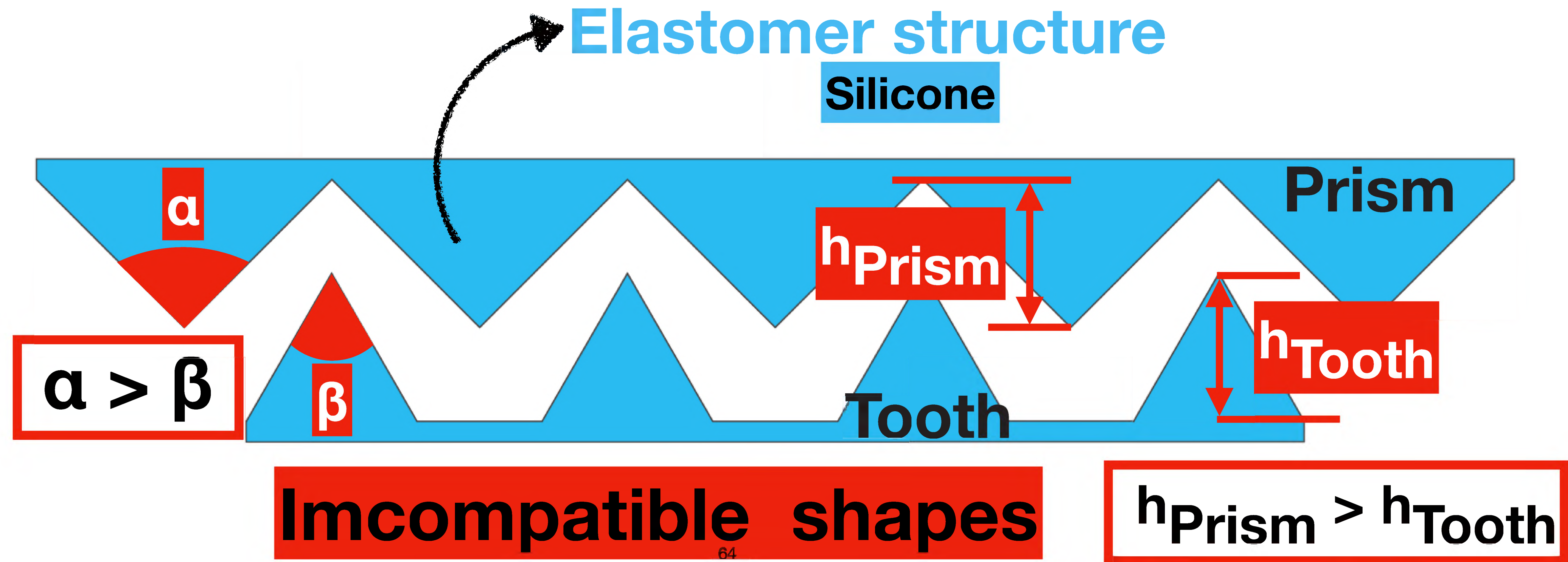
Jamming Origami Endoskeleton



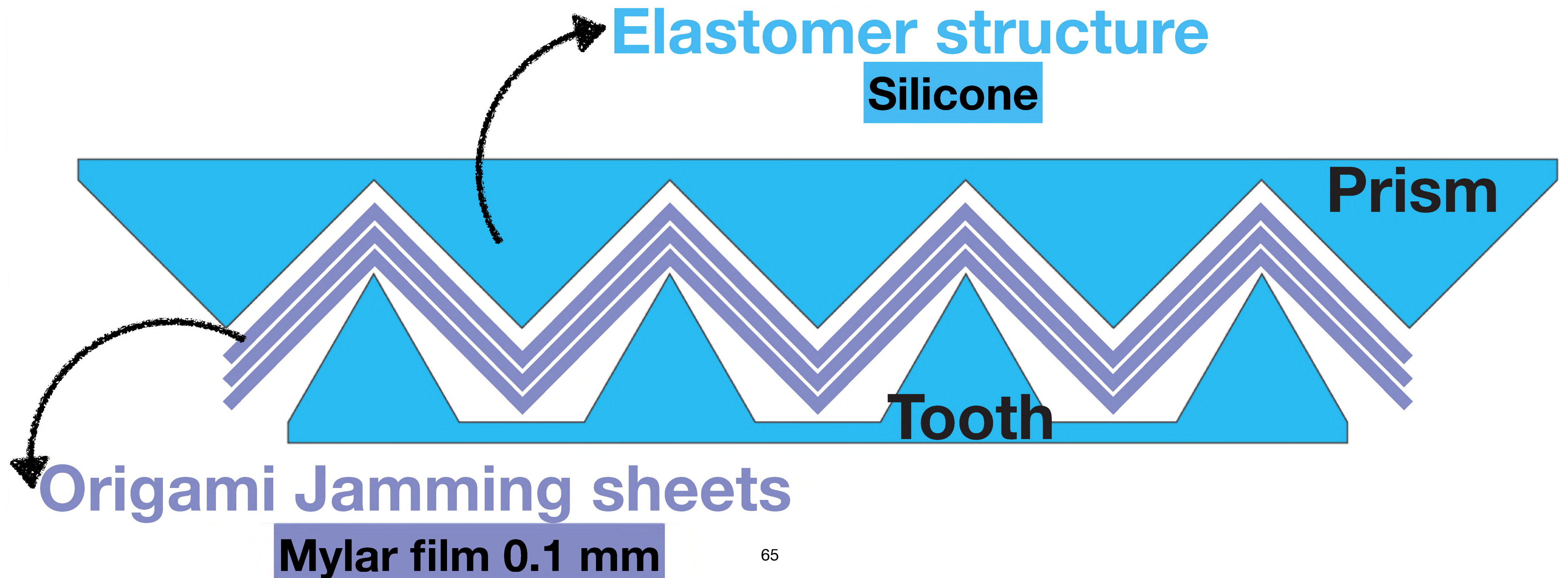
Jamming Origami Endoskeleton



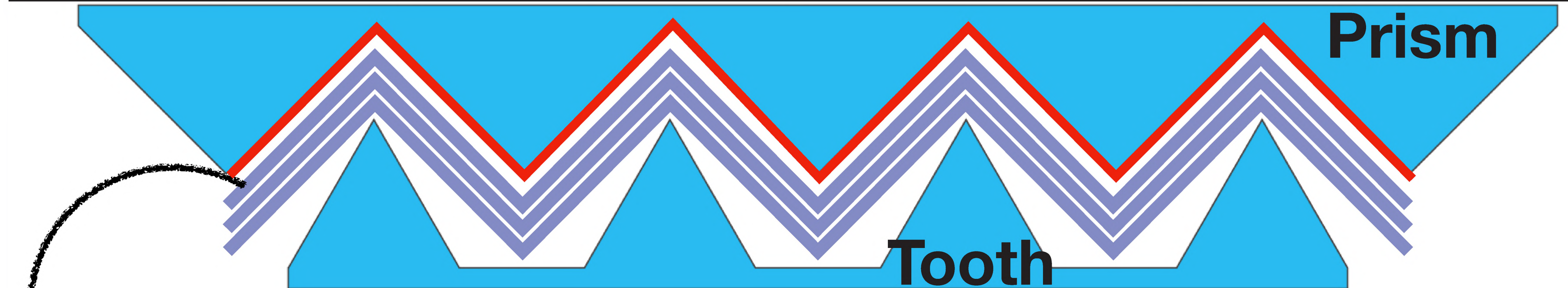
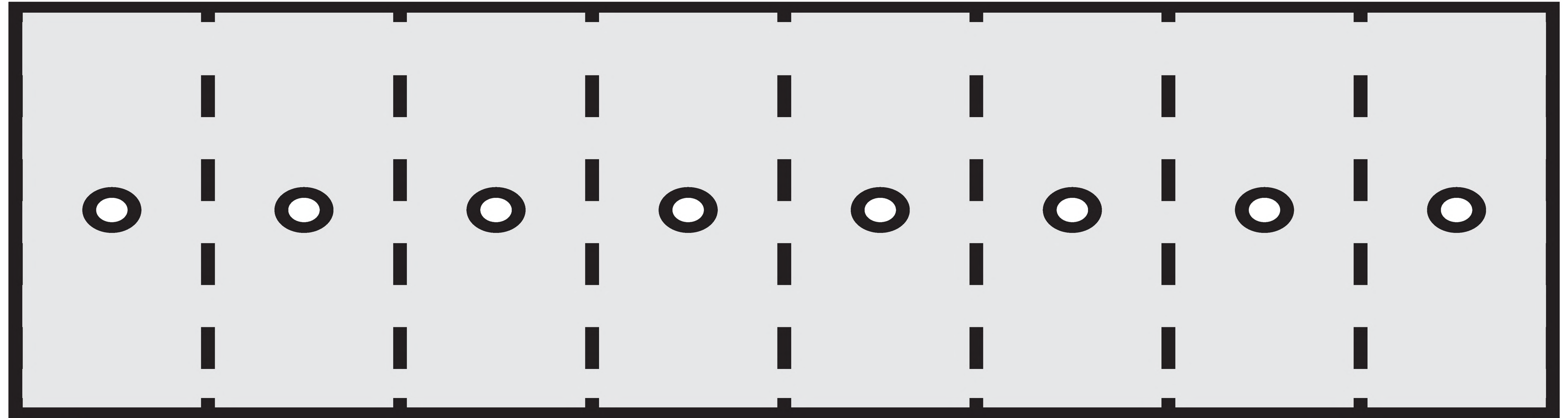
Jamming Origami Endoskeleton



Jamming Origami Endoskeleton



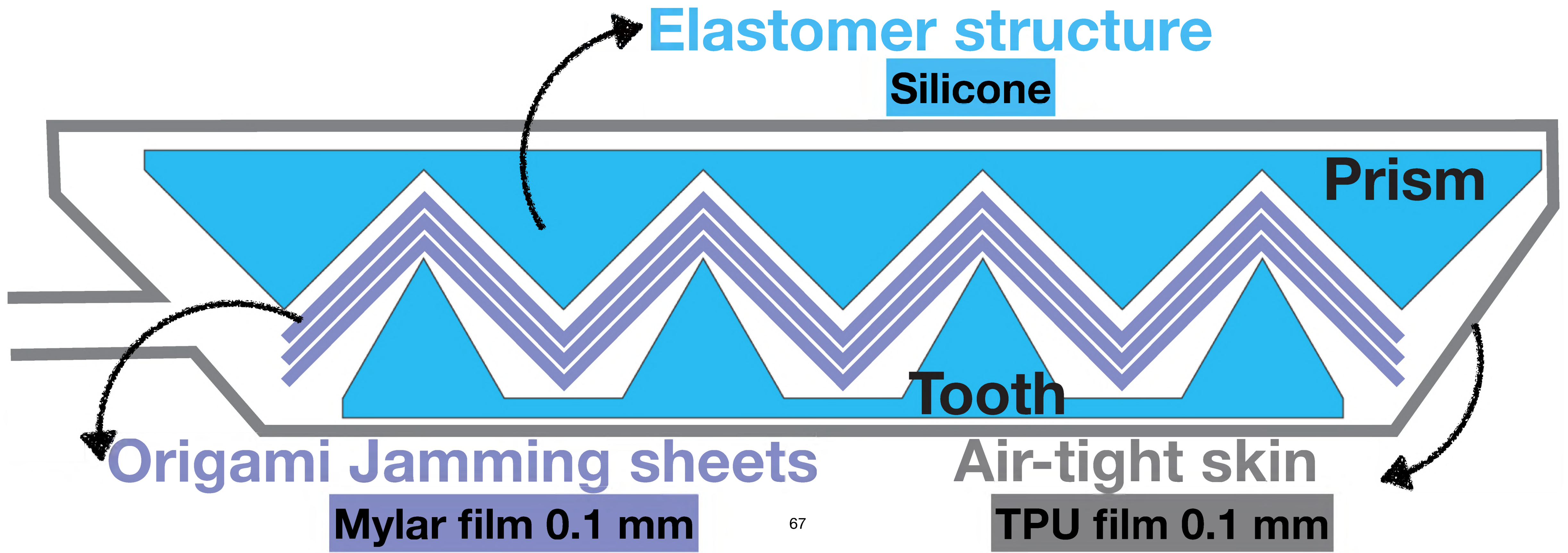
Jamming Origami Endoskeleton



Origami Jamming sheets

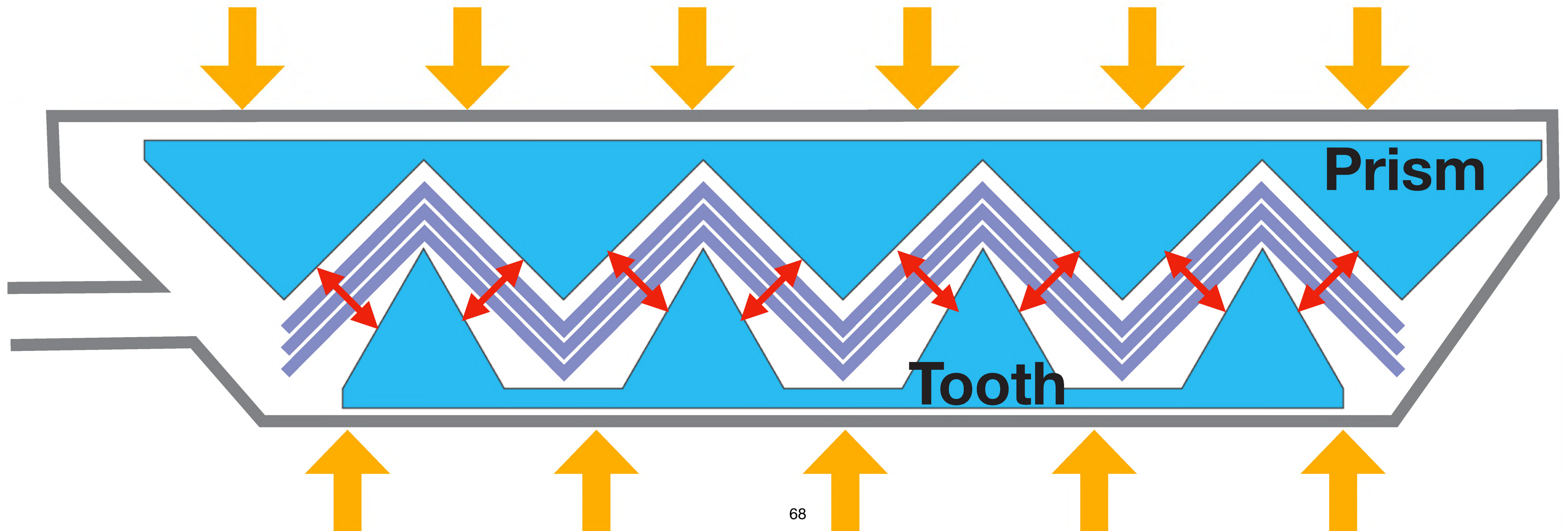
Mylar film 0.1 mm

Jamming Origami Endoskeleton



Jamming Origami Endoskeleton

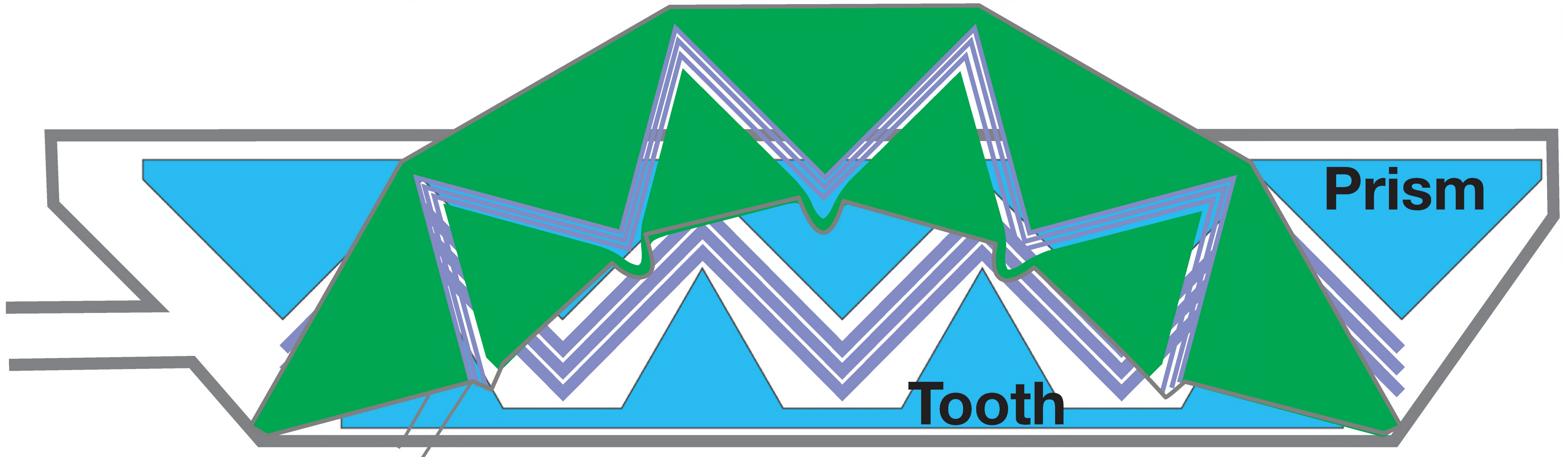
Atmosphere



Jamming Origami Endoskeleton

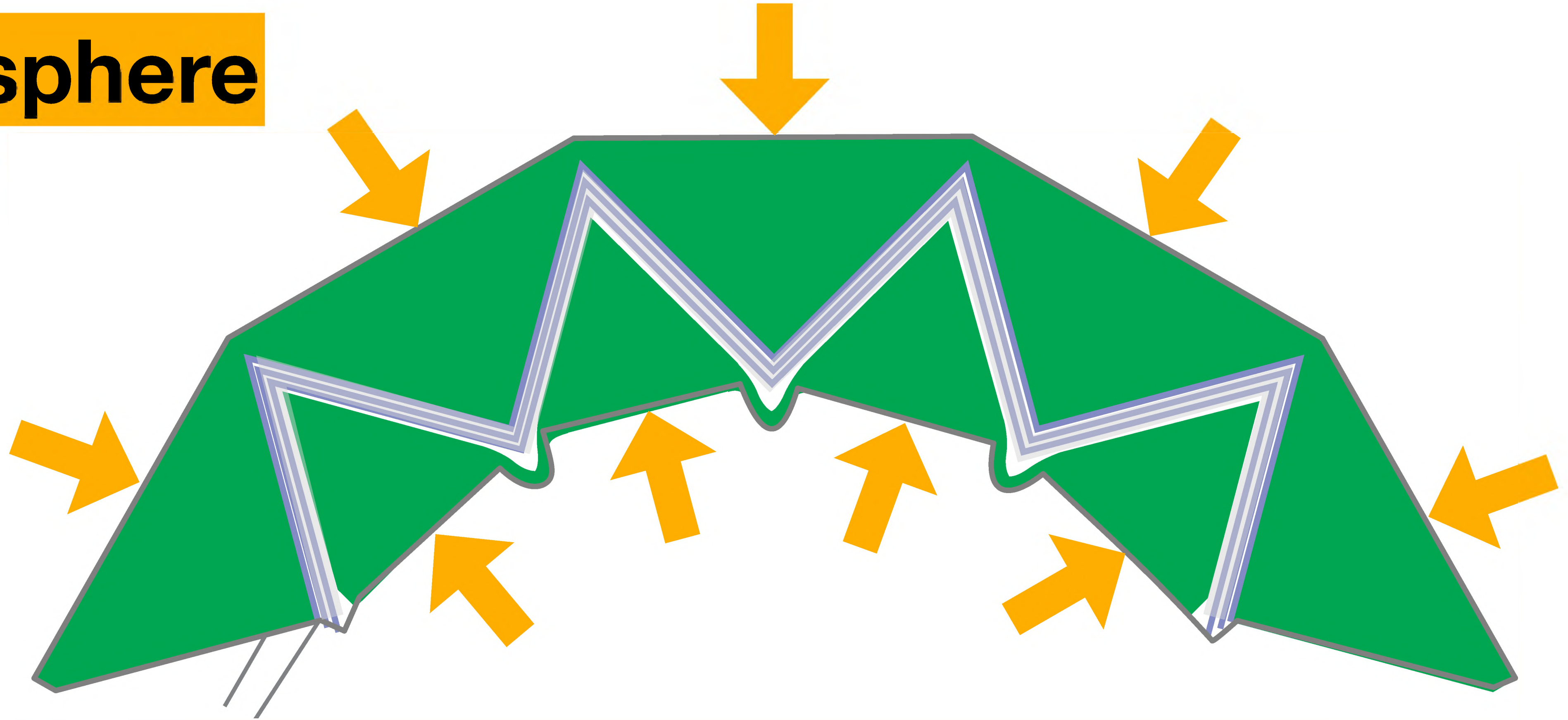
Atmosphere

Curvature



Jamming Origami Endoskeleton

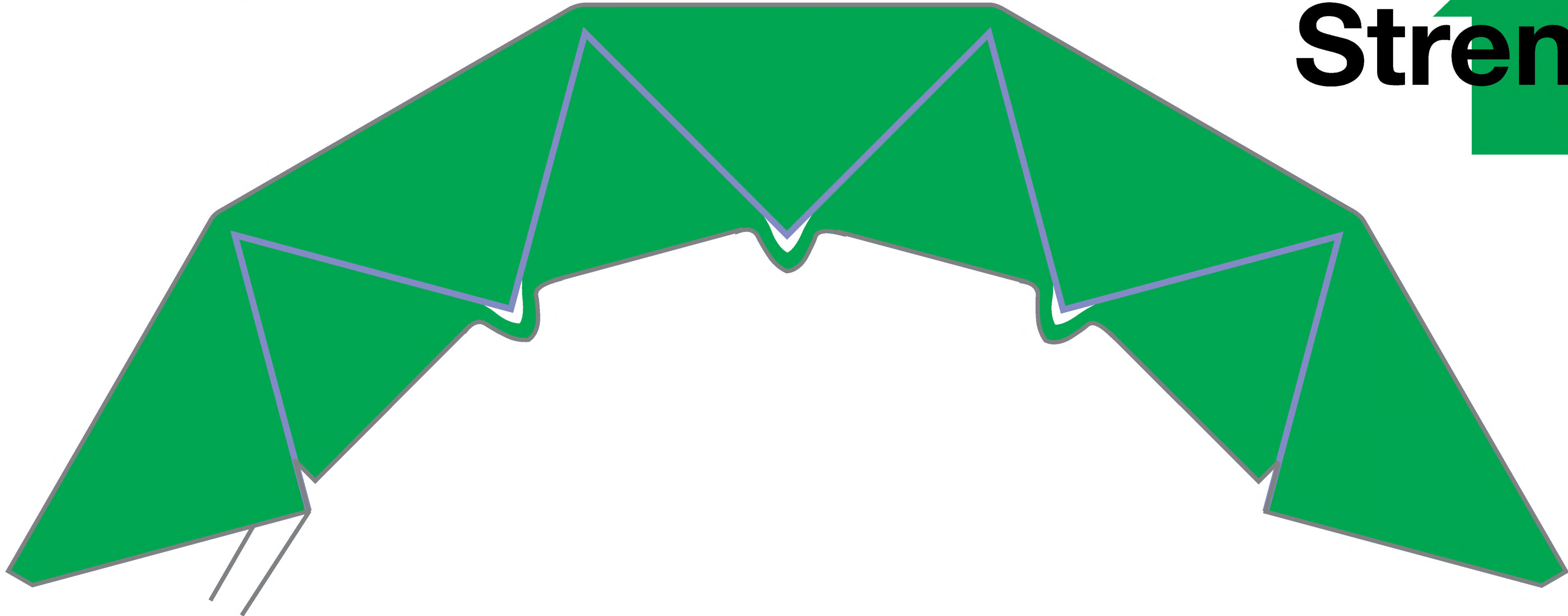
Atmosphere



Jamming Origami Endoskeleton

Atmosphere

Strength



Improved curvature change

Without Jamming layers

With Jamming layers

Air vacuumed

$R=83\text{mm}$

Improved curvature change

Without Jamming layers

With Jamming layers

Air vacuumed

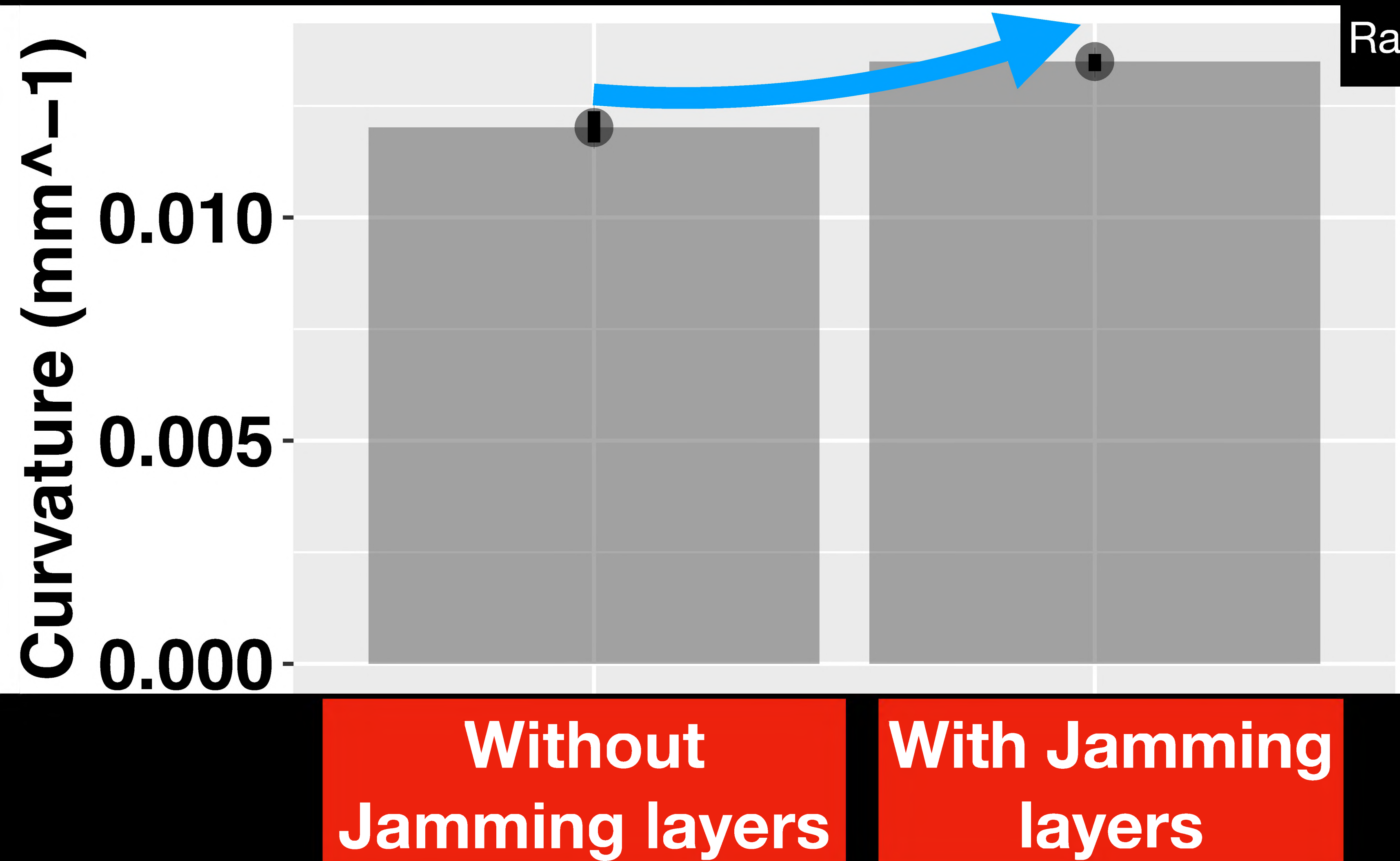
$R=83\text{mm}$

$R=74\text{mm}$

Curvature = $1/R$

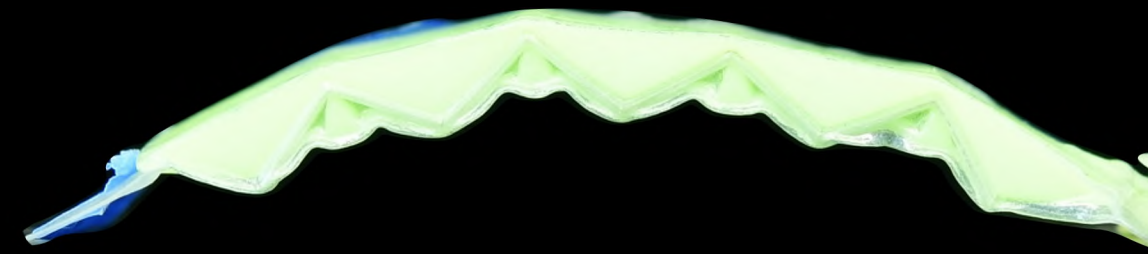
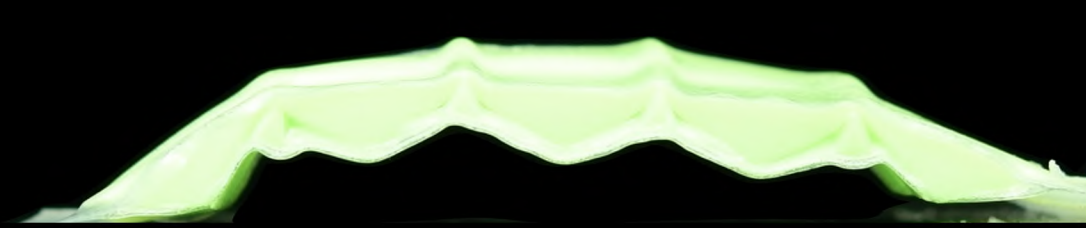
Improved curvature change

Increases by **12 %**



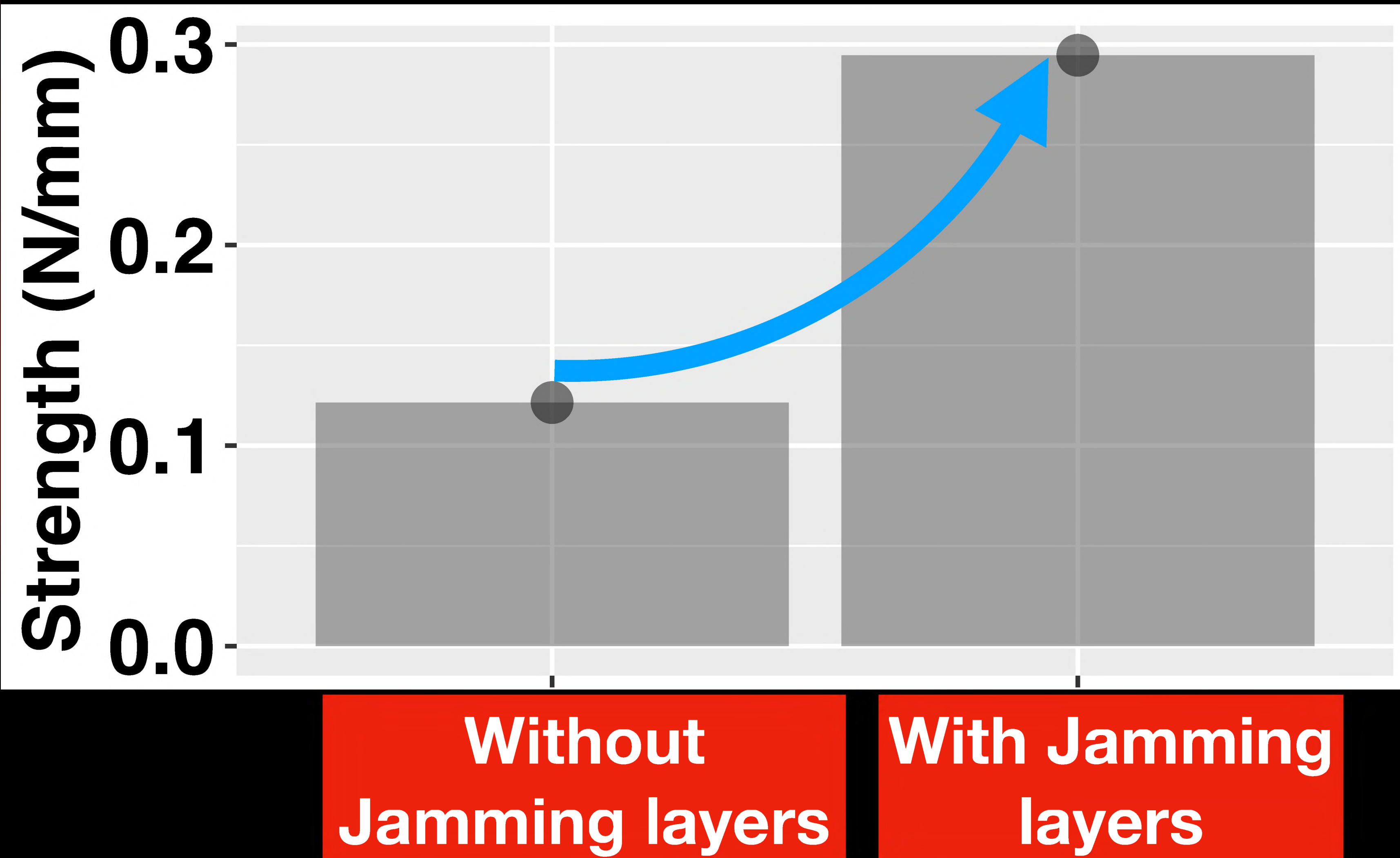
Radius from **83 mm** to **74 mm**

Enhanced strength

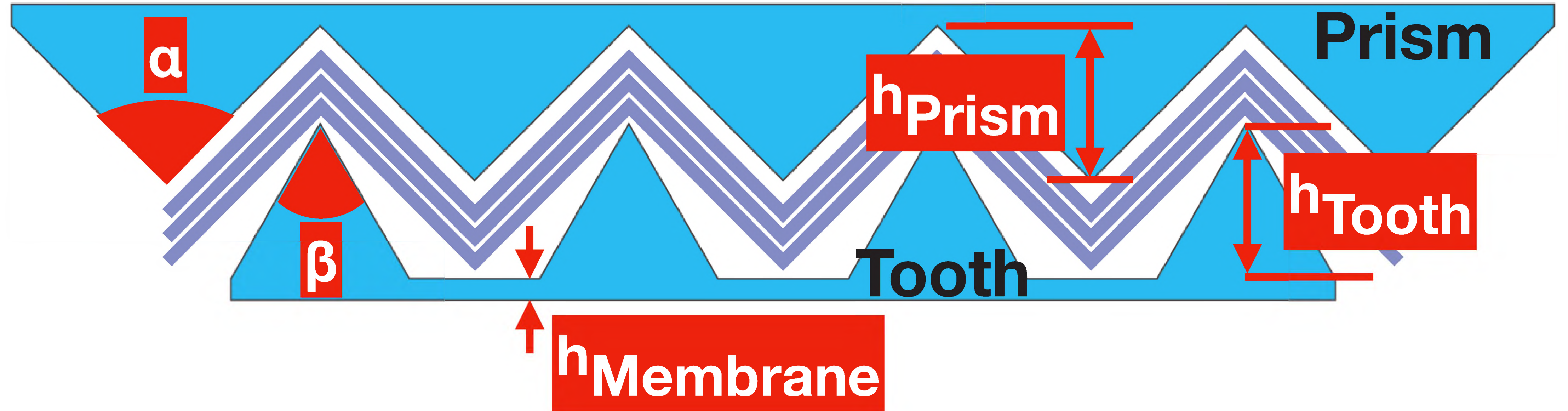


Increases by **150 %**

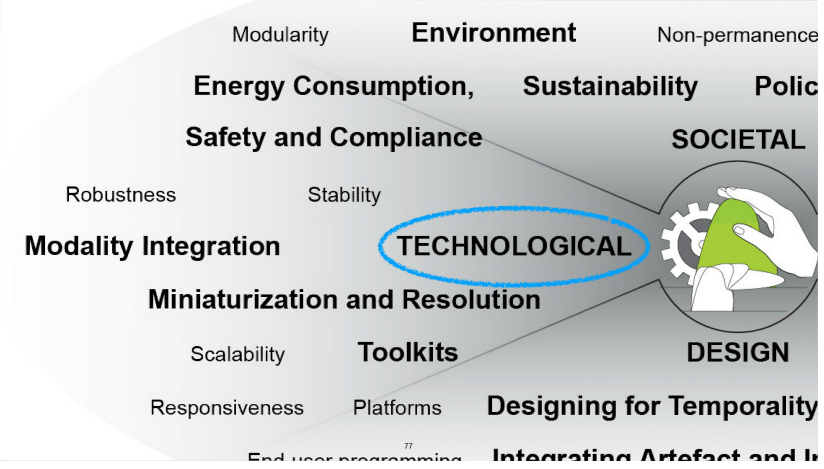
from 0.12 N/mm to 0.3 N/mm



Design Parameters



- $\Delta \text{Thickness} = h_{\text{Prism}} - h_{\text{Tooth}} - h_{\text{Membrane}}$
- $\Delta \text{Angle} = \alpha - \beta$
- h_{Prism}
- Pressure



Technological explorations

Programmable soft **materials**

for **different shape-changing** UIs

Novel technology **addressing limits** of
current programmable soft **materials**

Technological explorations

Lower technological barrier

Novel technology **addressing limits** of
current programmable soft **materials**

Technological explorations

Lower technological barrier

**Addressed
stretchability-strength trade-off**